



UNIVERSITY OF
TORONTO

Bit-Tactical: Sparse/Dense Deep Learning Inference Accelerator(*)

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Milos Nikolic, Zissis Poulos, Sayeh Sharify,

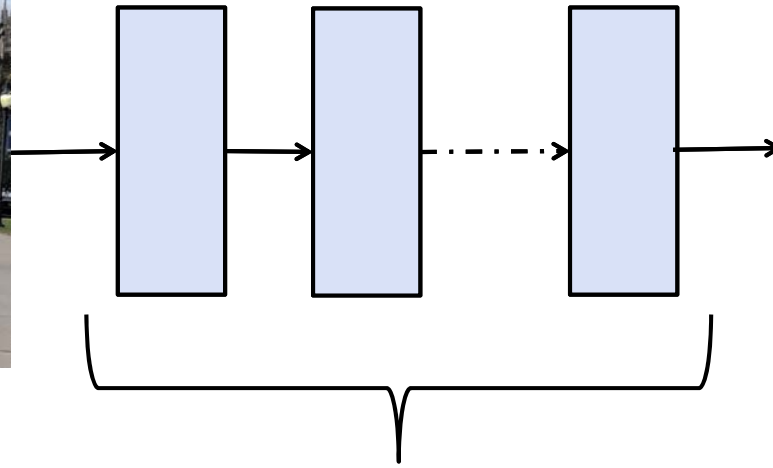
Kevin Siu, Dylan Stuart

Andreas Moshovos

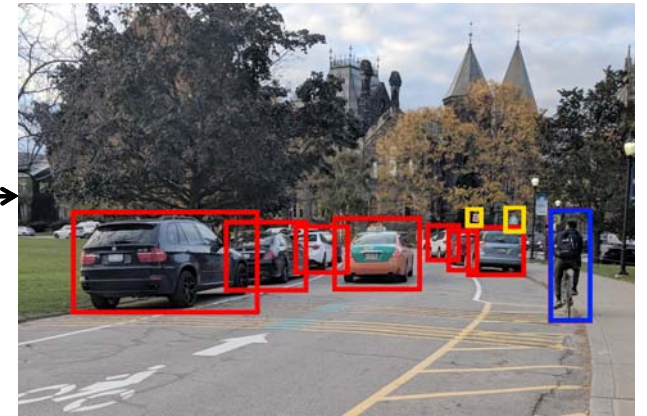
(*) For licensing please contact the University of Toronto Innovation Office



Input image



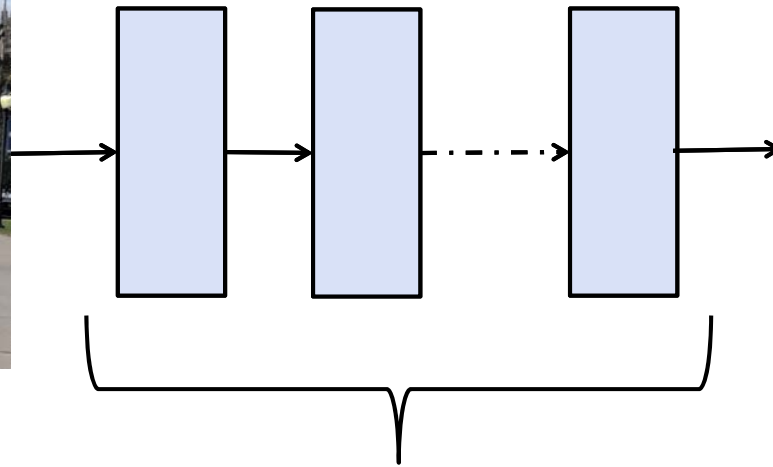
layers
10s-100s



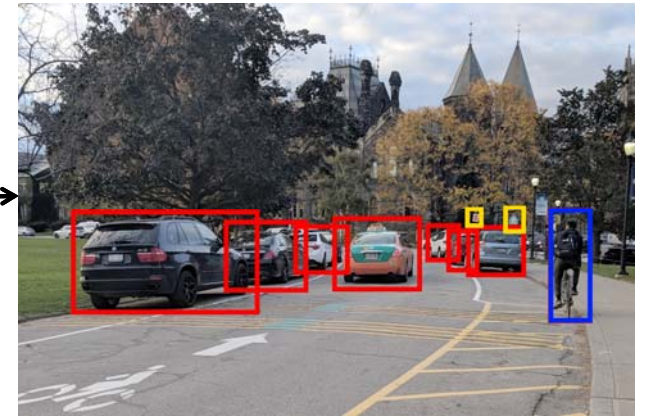
Annotated
image



Input image



layers
10s-100s

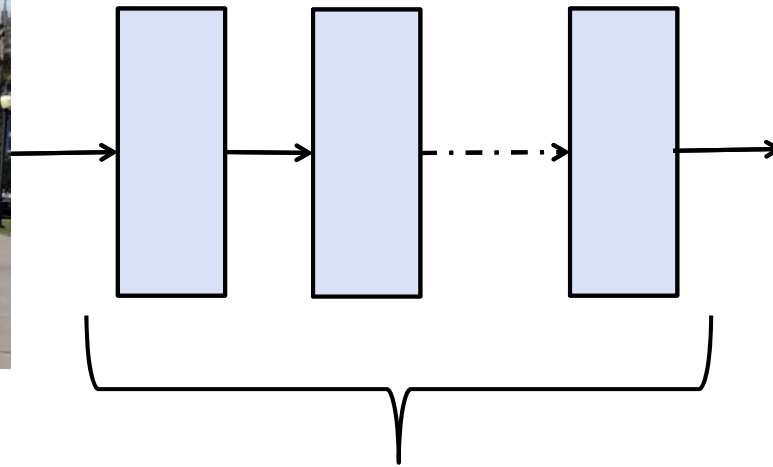


Annotated
image

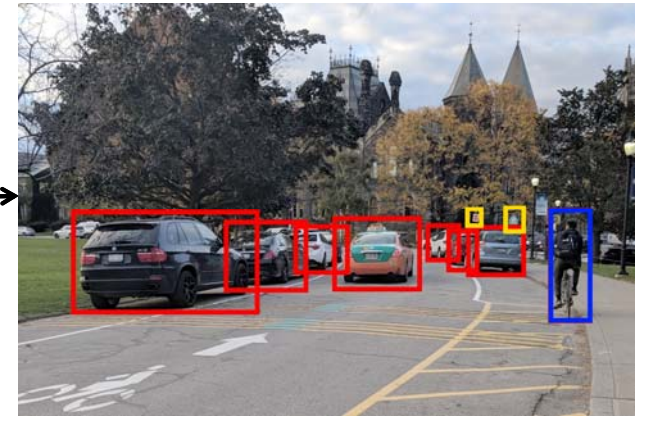
Faster
+
More Energy Efficient



Input image



layers
10s-100s



Annotated
image

Fewer Operations
Fewer Data Transfers

Fewer Operations
Fewer Data Transfers

Fewer Operations

Fewer Data Transfers

$$\text{Out} += A_0 \times W_0$$

$$\text{Out} += A_1 \times W_1$$

$$\text{Out} += A_2 \times W_2$$

$$\text{Out} += A_3 \times W_3$$

$$\text{Out} += A_4 \times W_4$$

⋮

Eliminate Ineffectual Operations

$$\text{Out} += A_0 \times W_0$$

$$\text{Out} += A_1 \times W_1$$

$$\text{Out} += A_2 \times W_2$$

$$\text{Out} += A_3 \times W_3$$

$$\text{Out} += A_4 \times W_4$$

⋮

Eliminate Ineffectual Operations

$$\text{Out} += A_0 \times W_0$$

$$\text{Out} += \mathbf{0} \times W_1$$

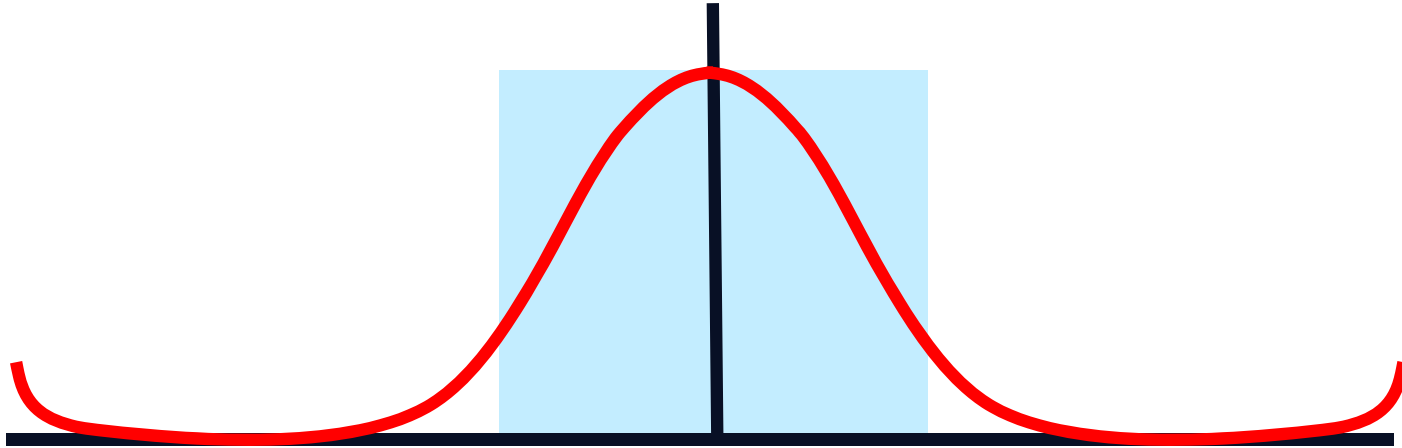
$$\text{Out} += A_2 \times W_2$$

$$\text{Out} += A_3 \times \mathbf{0}$$

$$\text{Out} += A_4 \times W_4$$

⋮

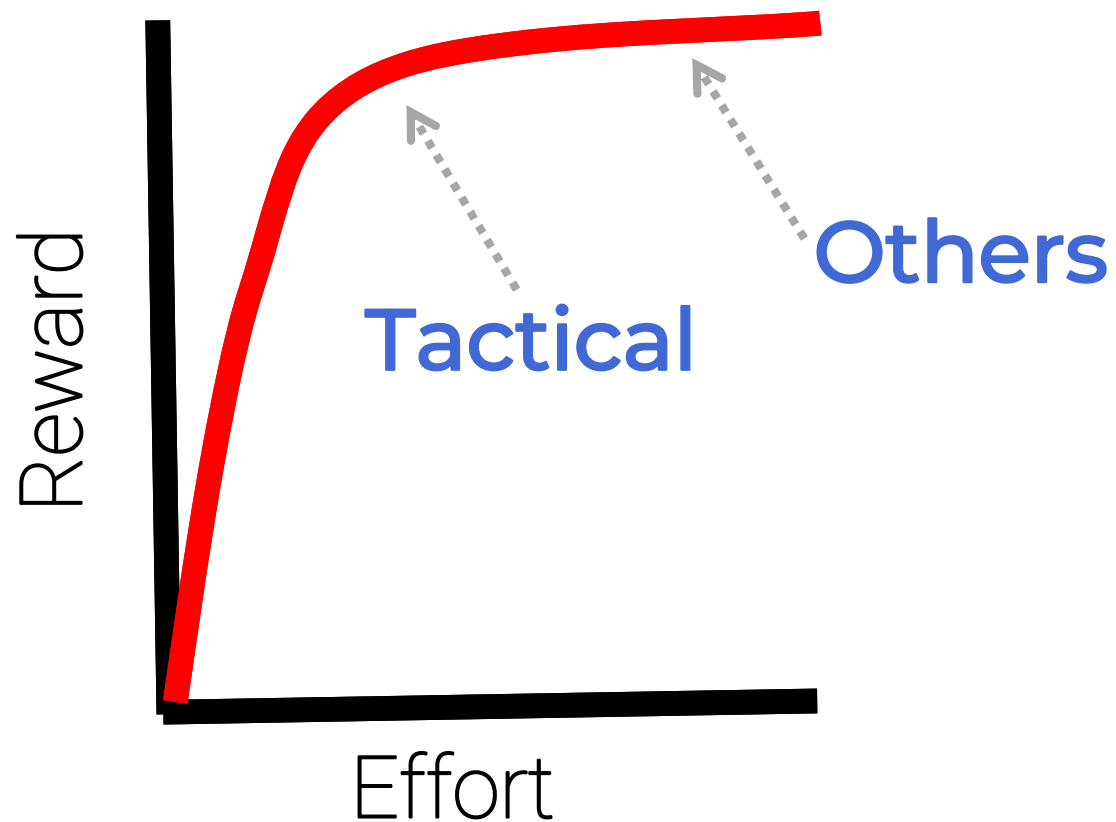
Takeaway #1



0.5x – 0.2x Off-Chip Transfers
On-Chip Storage

Takeaway #2

Out += A x 0



Takeaway #2

$$\text{Out} \neq A \times 0$$

Aim to get **most** not **all**

Simple Design
Software Scheduler

Takeaway #3

Out += 0 x W

Don't!

Only ~50% A==0

Takeaway #3

Out += 0100001 x W

Go for Bit Sparsity

> 90%

Takeaway #4

vs. SCNN

Speed

5.3x

Energy

0.85x

Do as you are told?

$$\text{Out} += A_0 \times W_0$$

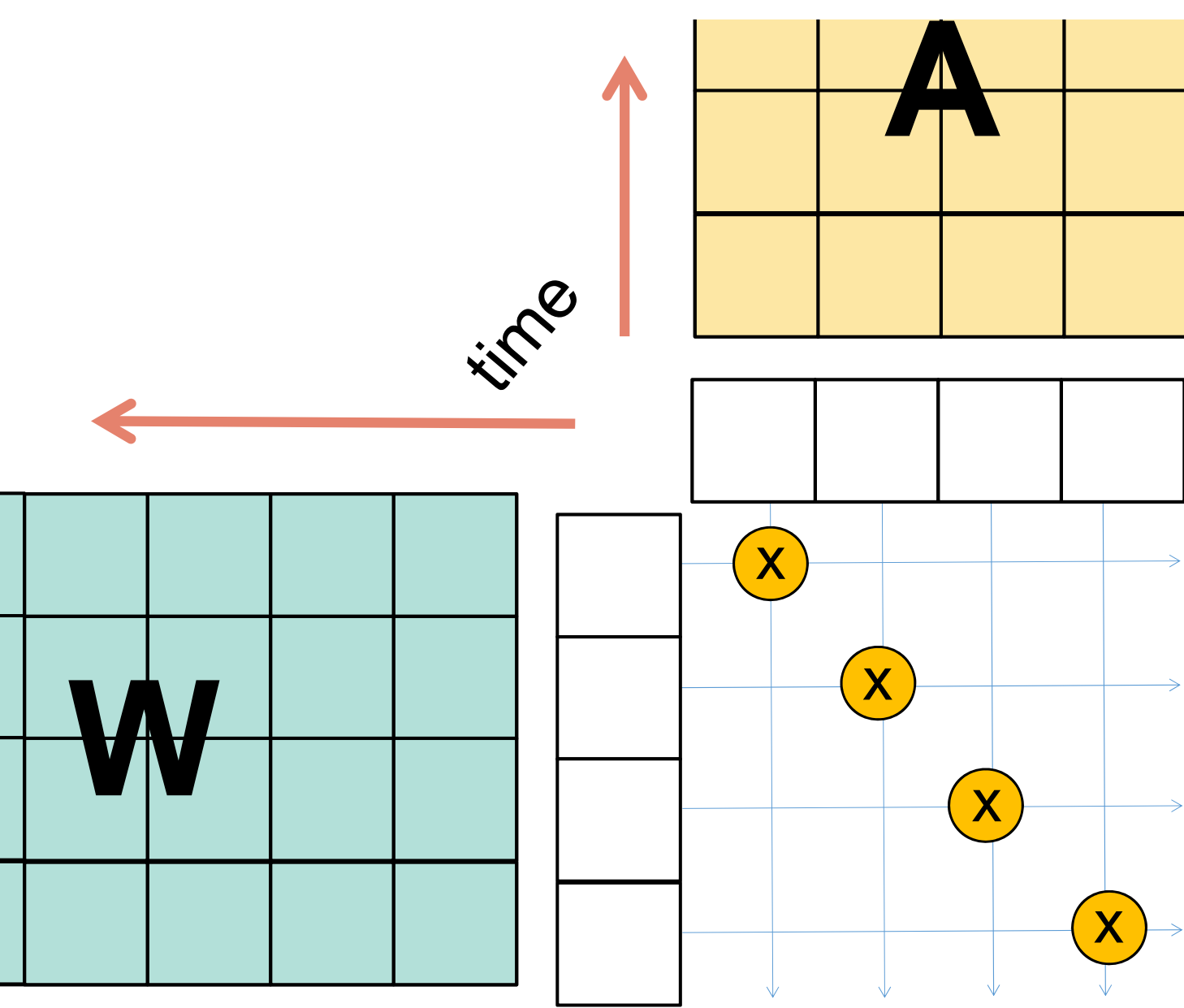
$$\text{Out} += A_1 \times W_1$$

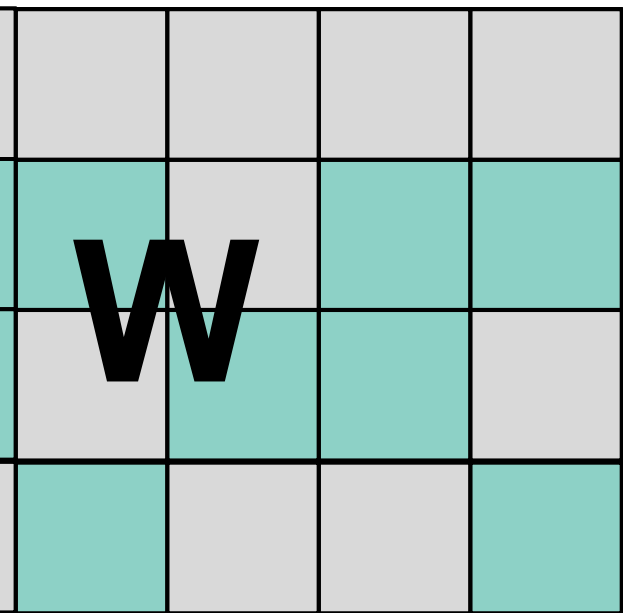
$$\text{Out} += A_2 \times W_2$$

$$\text{Out} += A_3 \times W_3$$

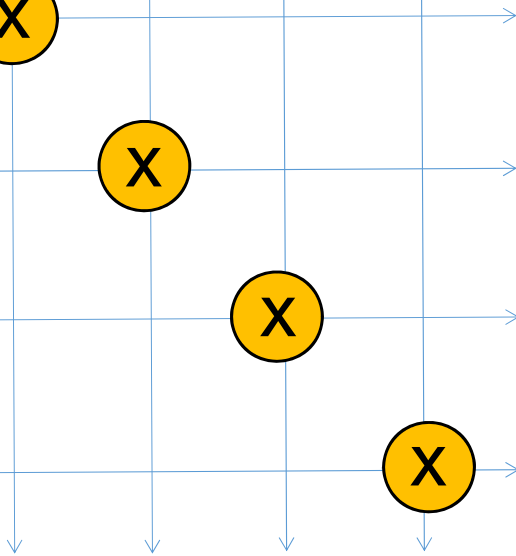
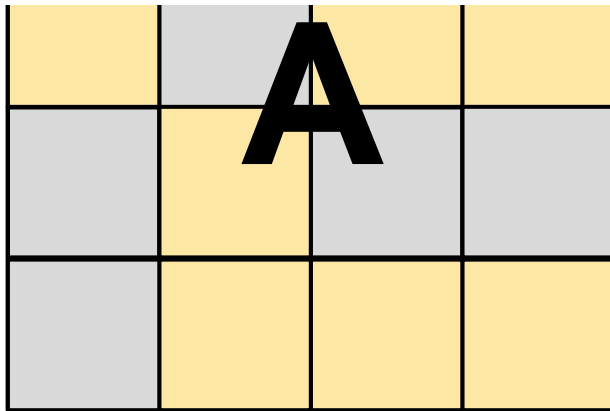
$$\text{Out} += A_4 \times W_4$$

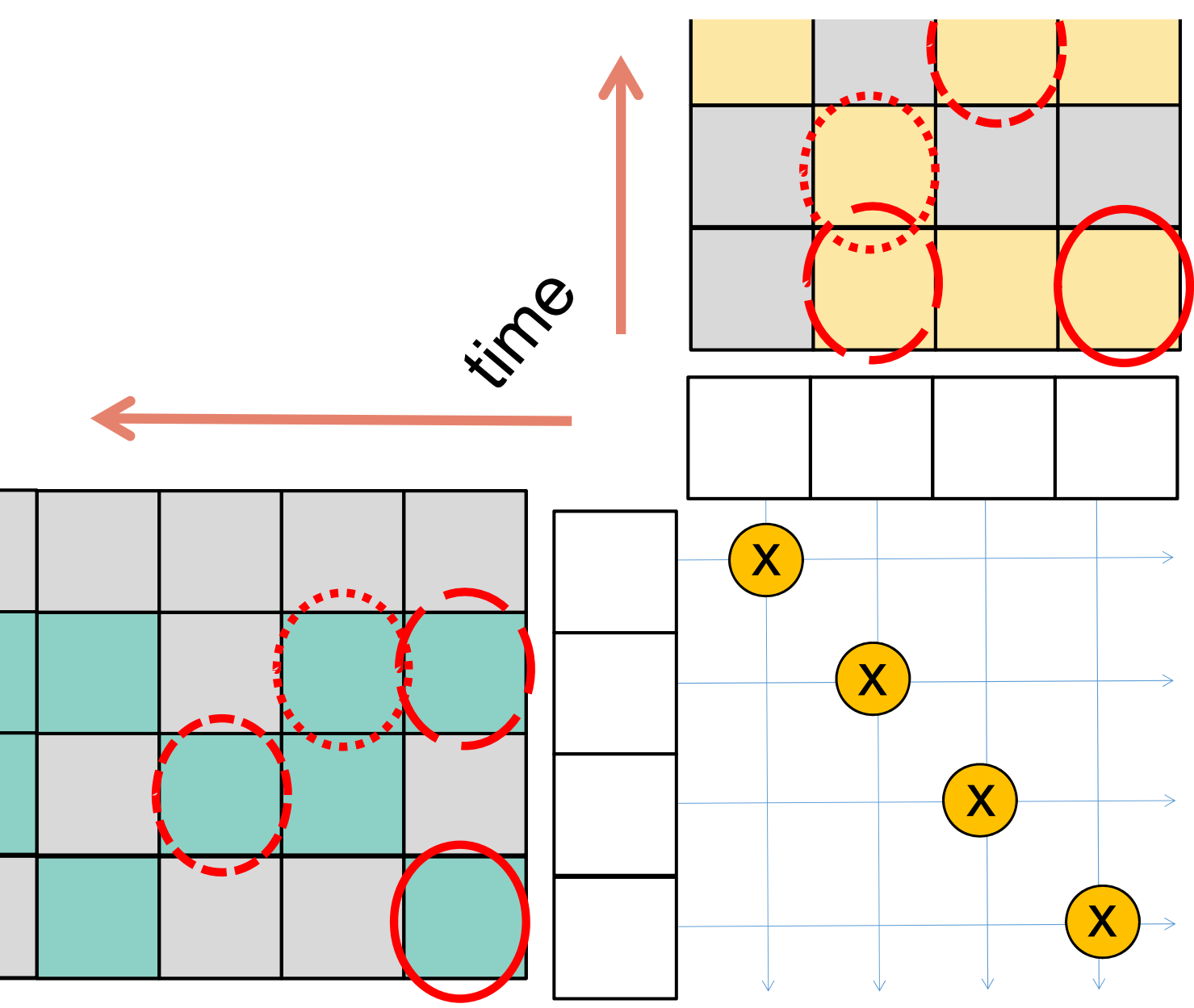


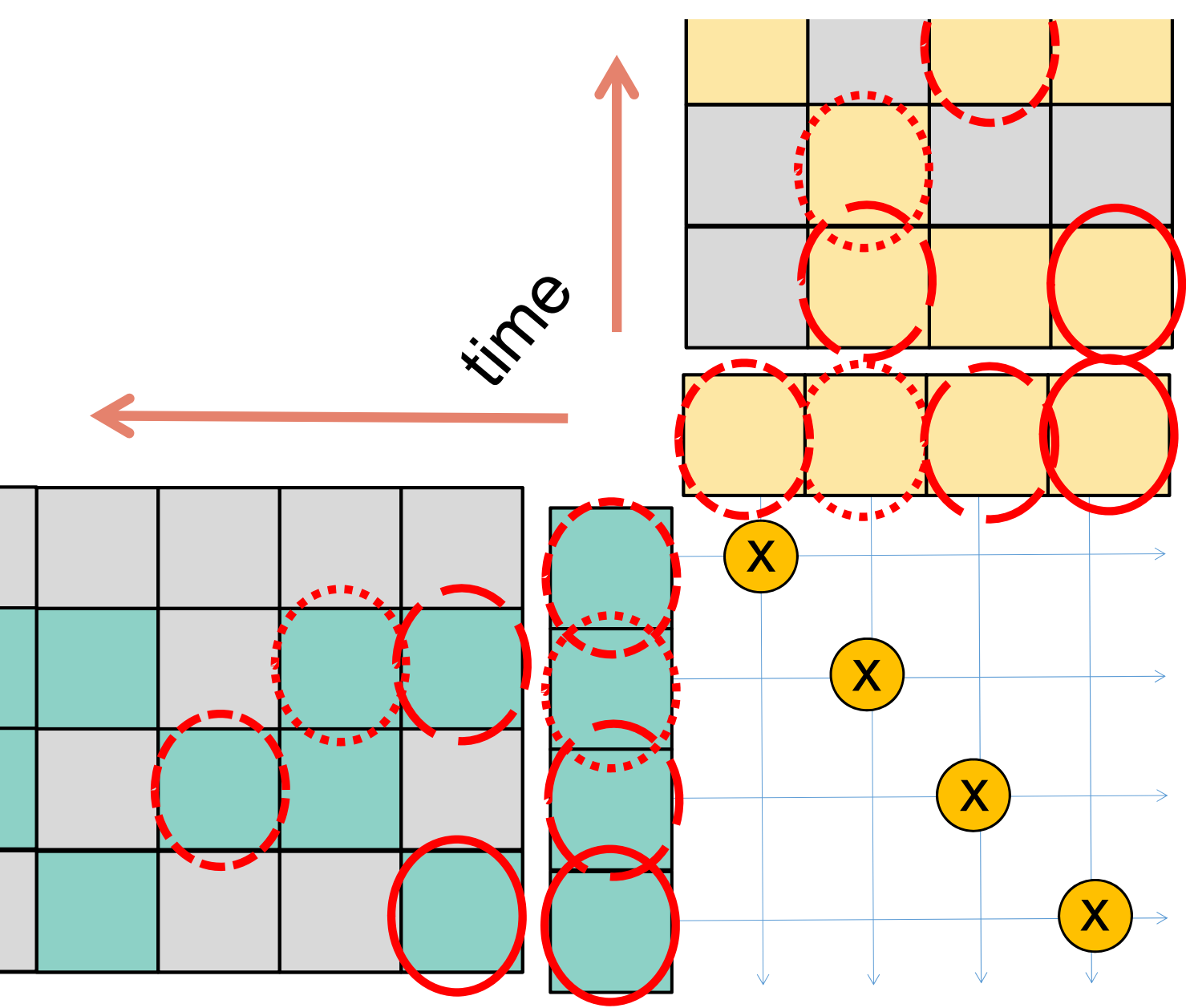


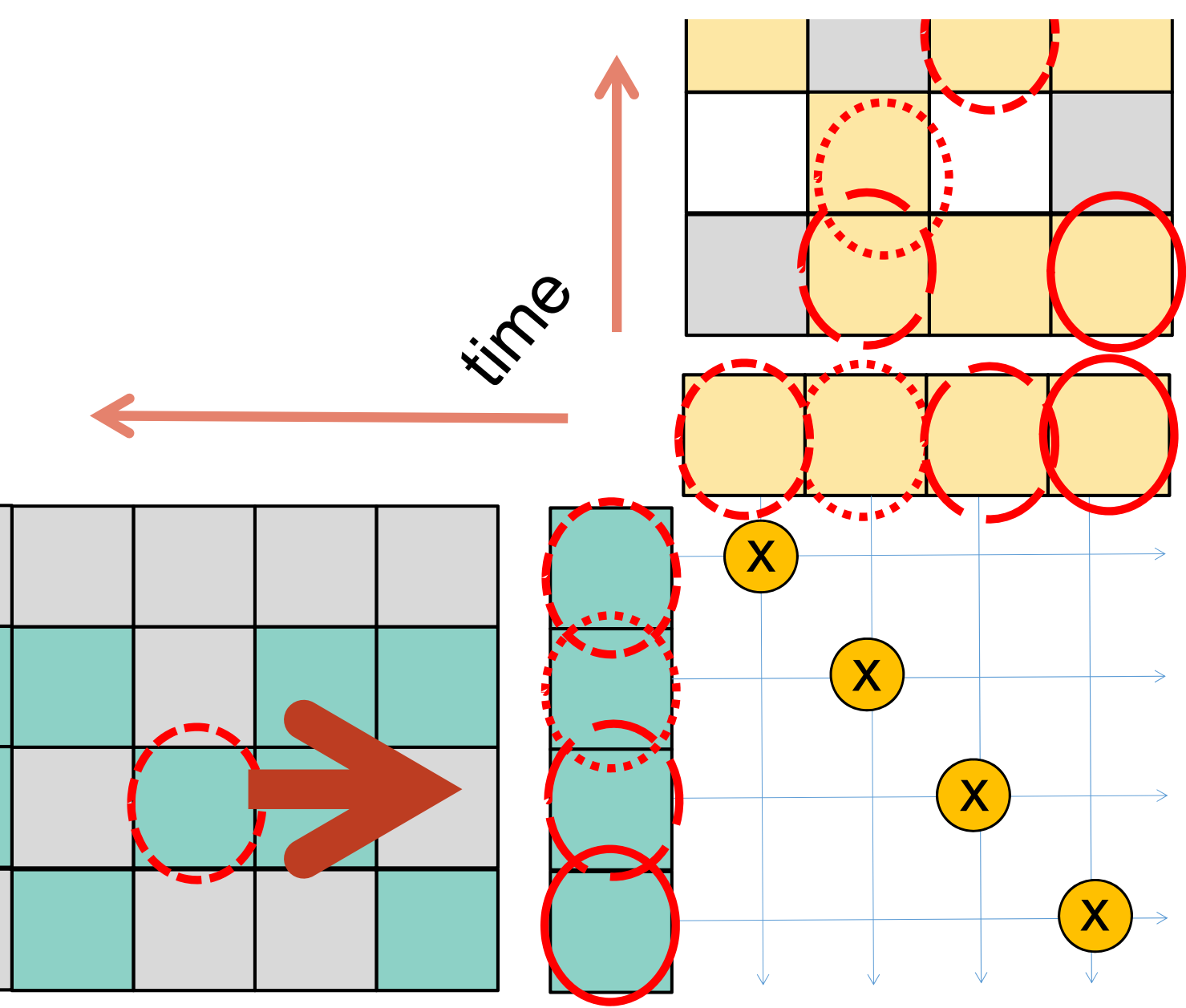


time

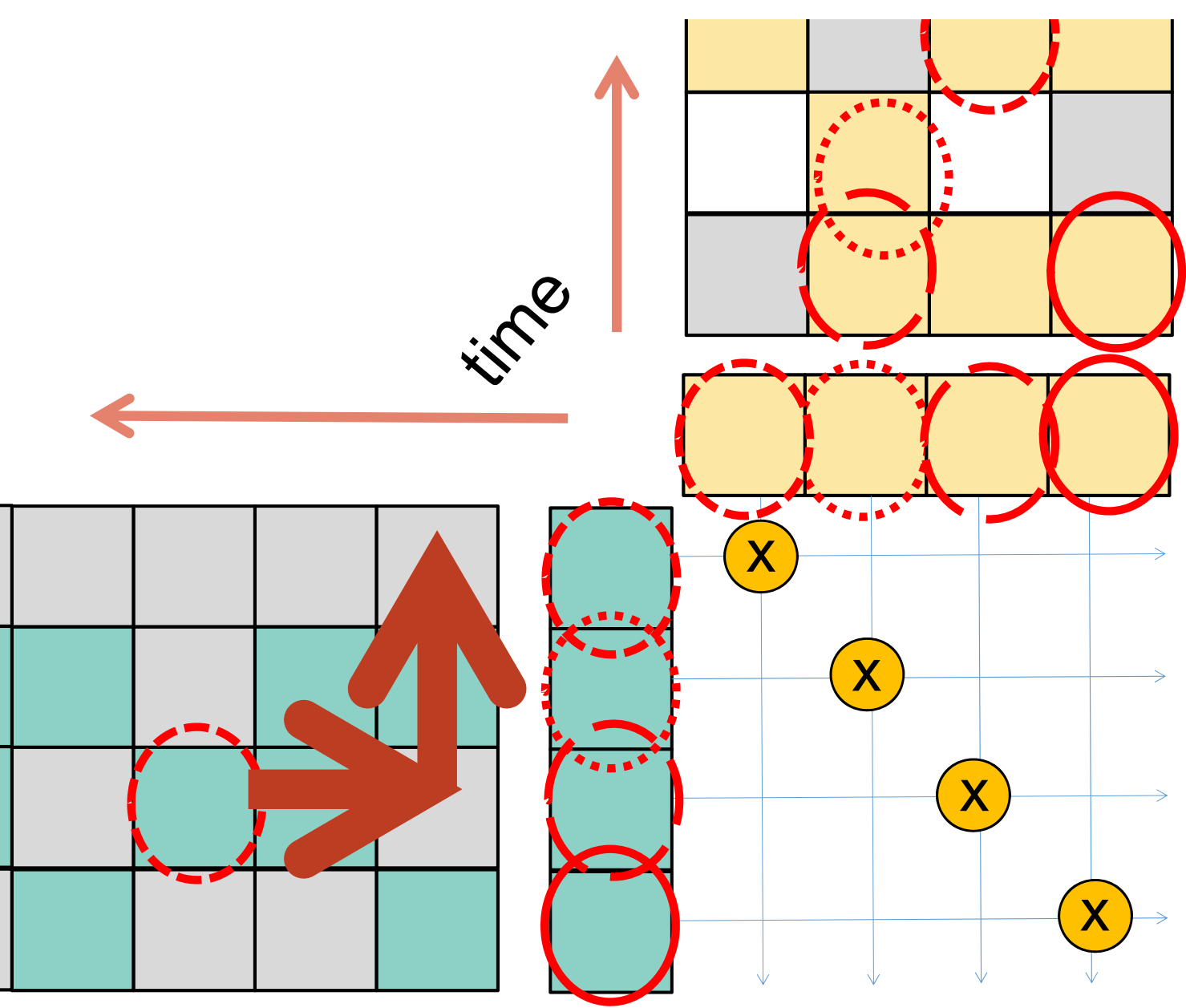




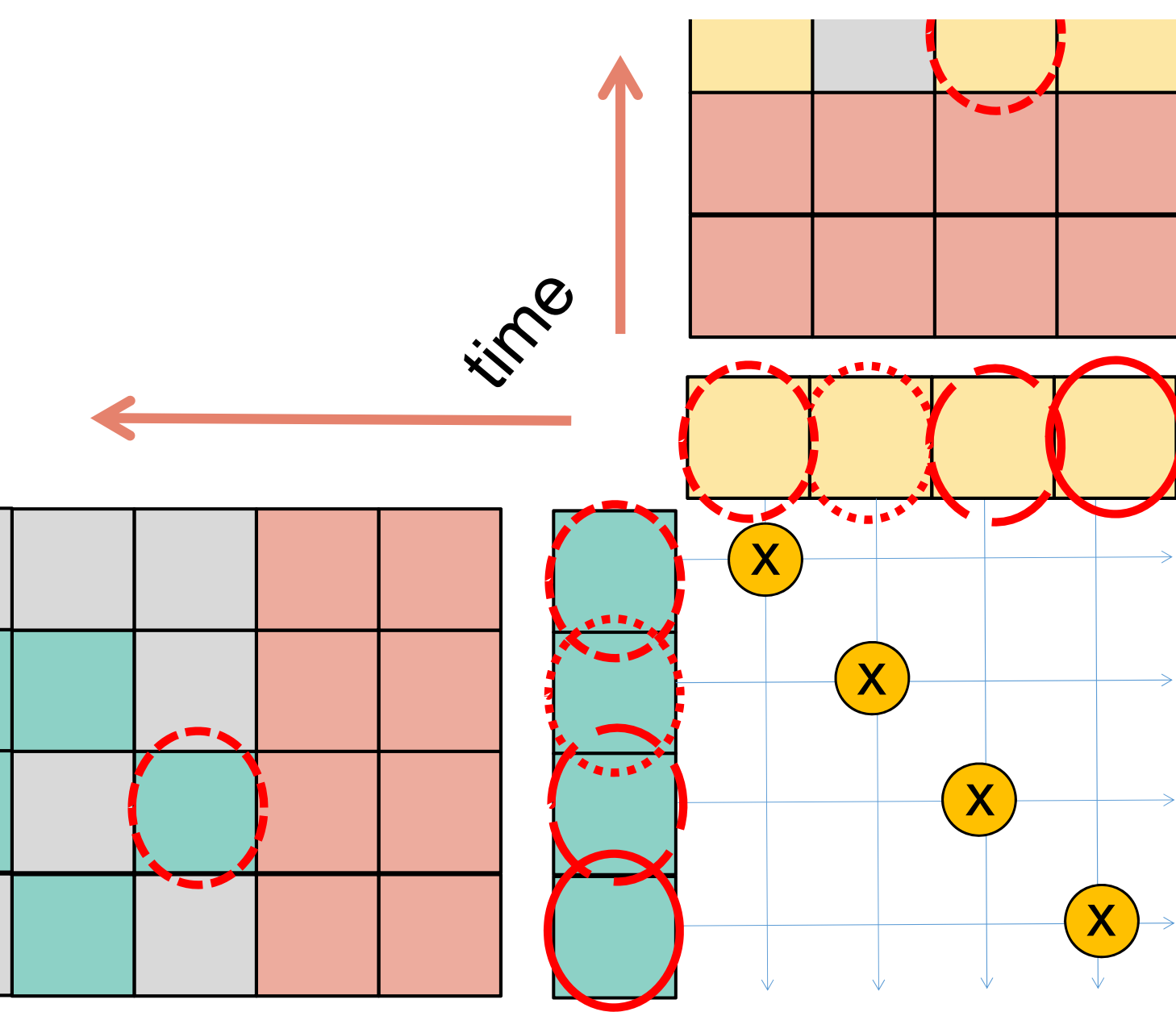




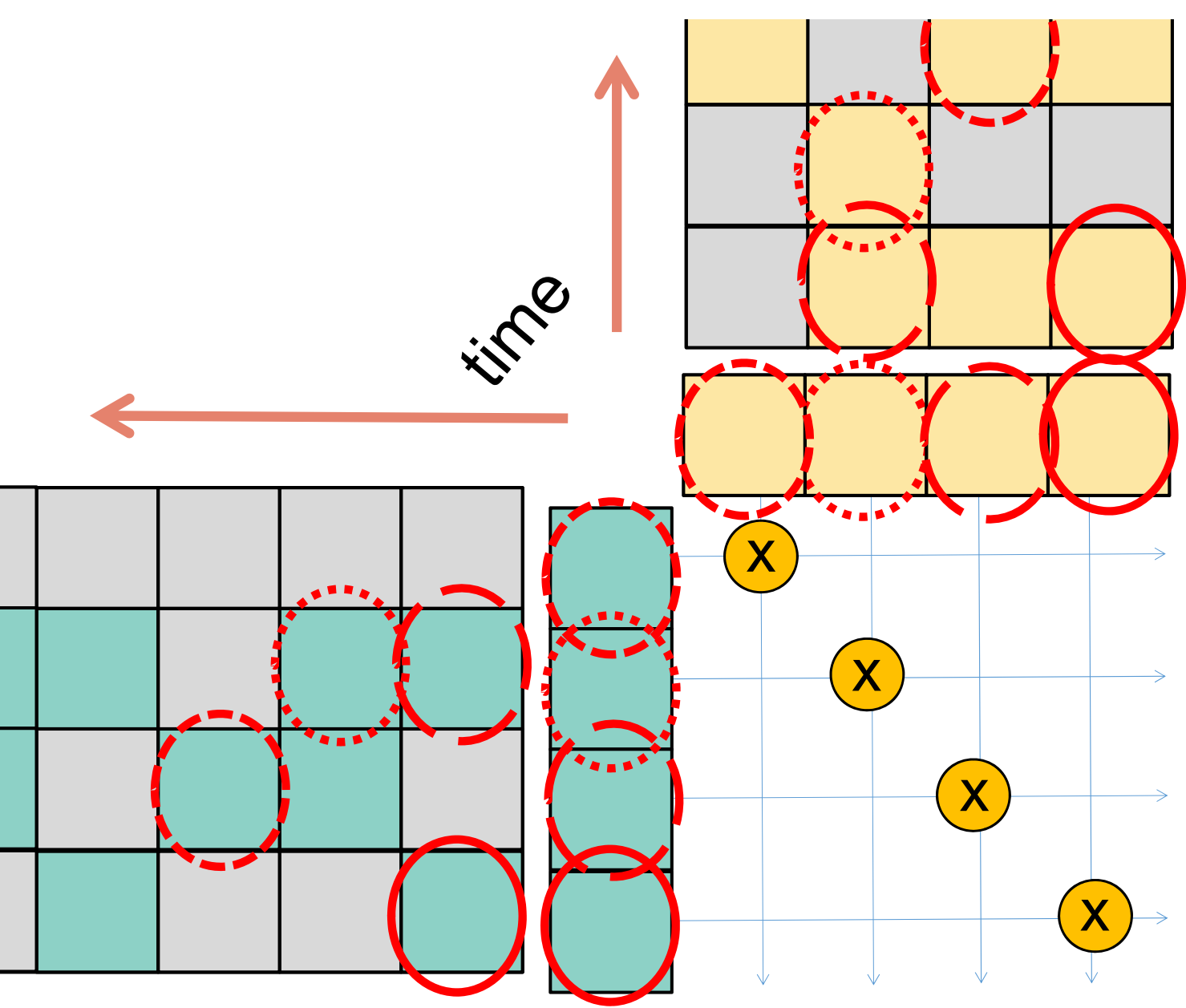
2 steps in **time**



Another 2 steps in **space**

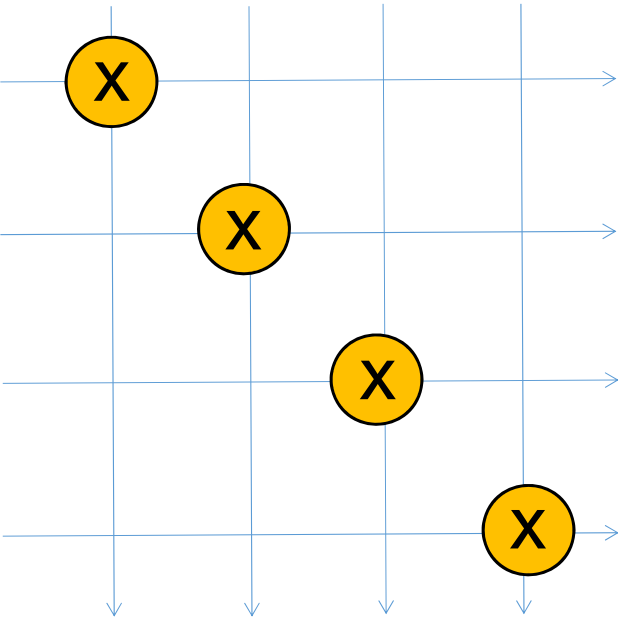
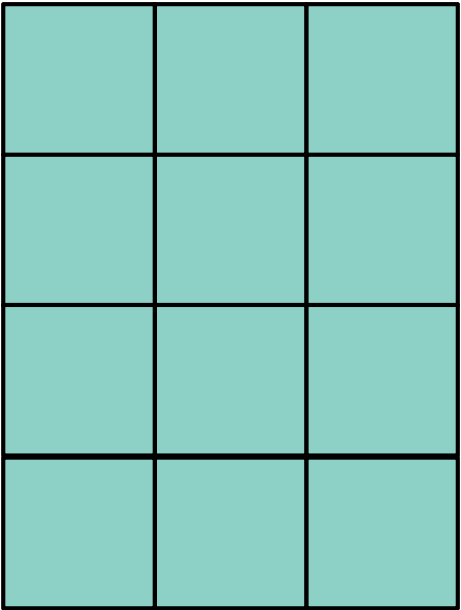
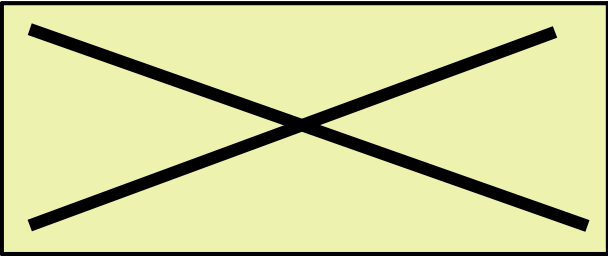
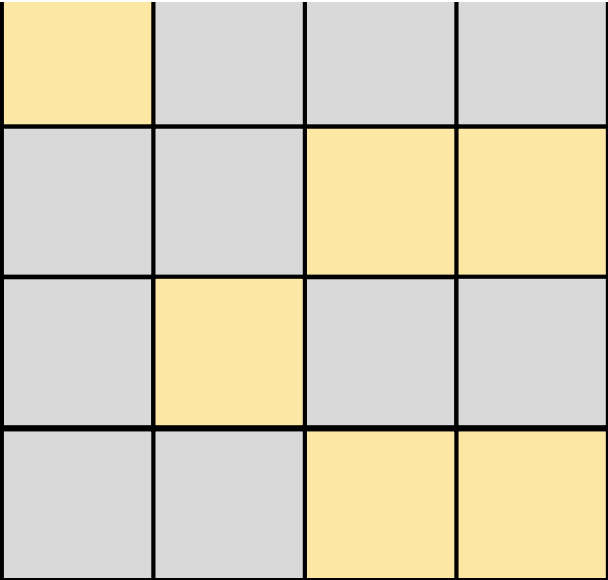


“unrestricted” motion



A: Dynamic Sparsity Pattern

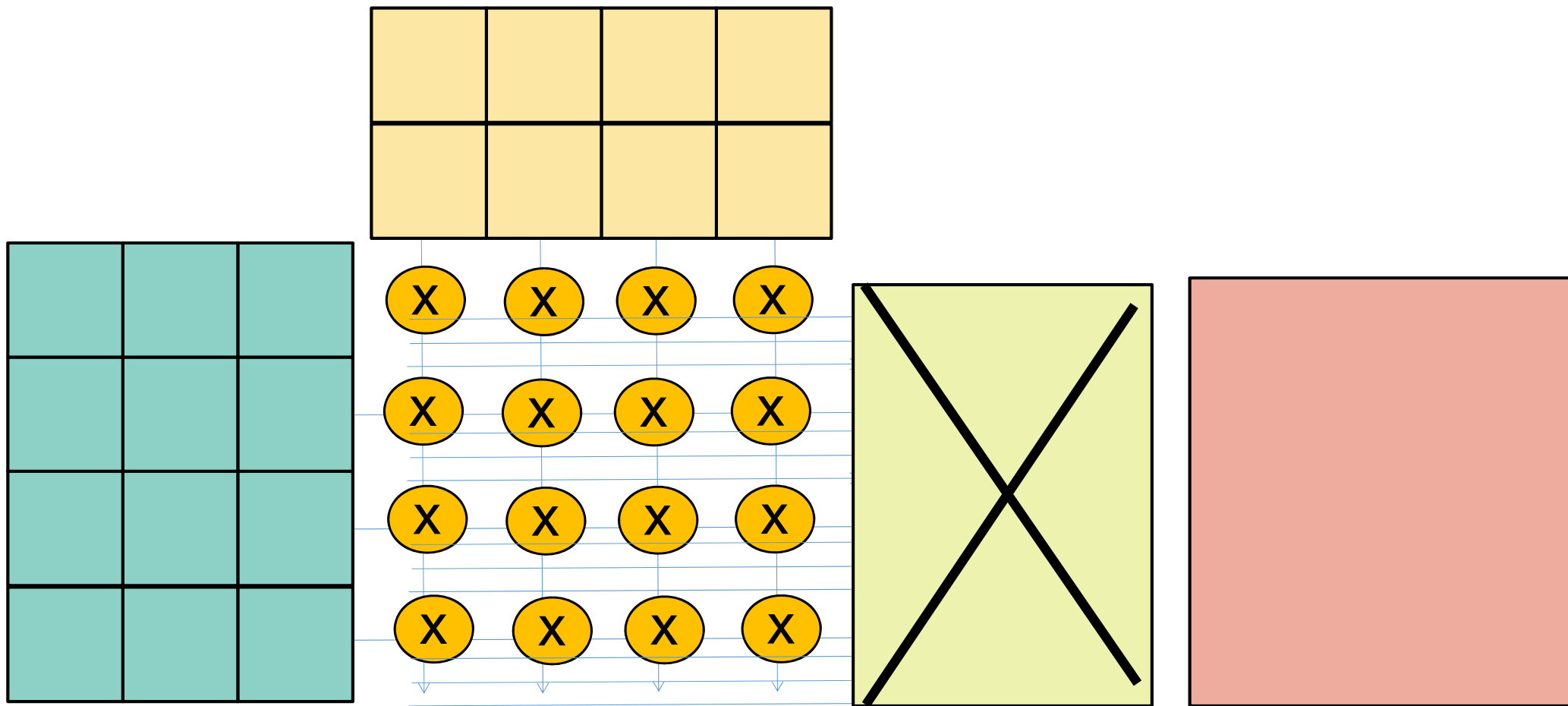
Cambricon-X



time
"any"

space
"any"

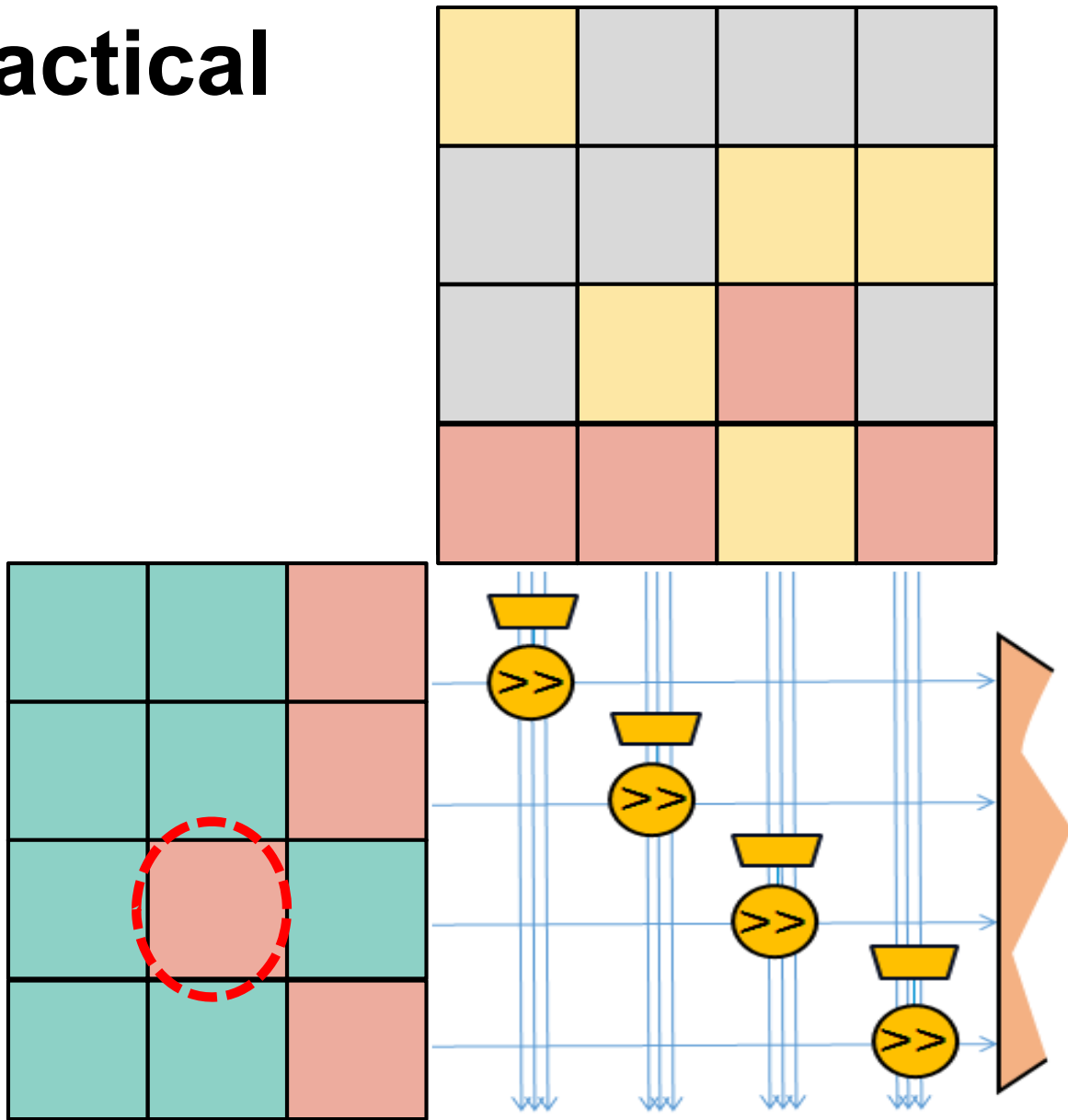
Nvidia's SCNN



time
"any"

space
"any"

Bit-Tactical



Weights

time

1-2 steps

space

2-5 places

Do as you are told?

$$\text{Out} += A_0 \times W_0$$

$$\text{Out} += A_2 \times W_2$$

$$\text{Out} += 0 \times W_3$$

$$\text{Out} += A_4 \times W_4$$



Do as you are told?

$$\text{Out} += A_0 \times W_0$$

$$\text{Out} += A_2 \times W_2$$

$$\text{Out} += 0 \times W_3$$

$$\text{Out} += A_4 \times W_4$$

⋮

Do as you are told?

$$\text{Out} += A_0 \times W_0$$

$$\text{Out} += A_2 \times W_2$$

$$\text{Out} += A_3 \times W_3$$

$$\text{Out} += A_4 \times W_4$$



Do as you are told?

$$\text{Out} += 000100100 \times W_0$$

$$\text{Out} += 000110100 \times W_2$$

$$\text{Out} += 000010000 \times W_3$$

$$\text{Out} += 010000010 \times W_4$$



Do as you are told?

$$\text{Out} += 000100100 \times W_0$$

$$\text{Out} += 000110100 \times W_2$$

$$\text{Out} += 000010000 \times W_3$$

$$\text{Out} += 010000010 \times W_4$$

⋮

Do as you are told?

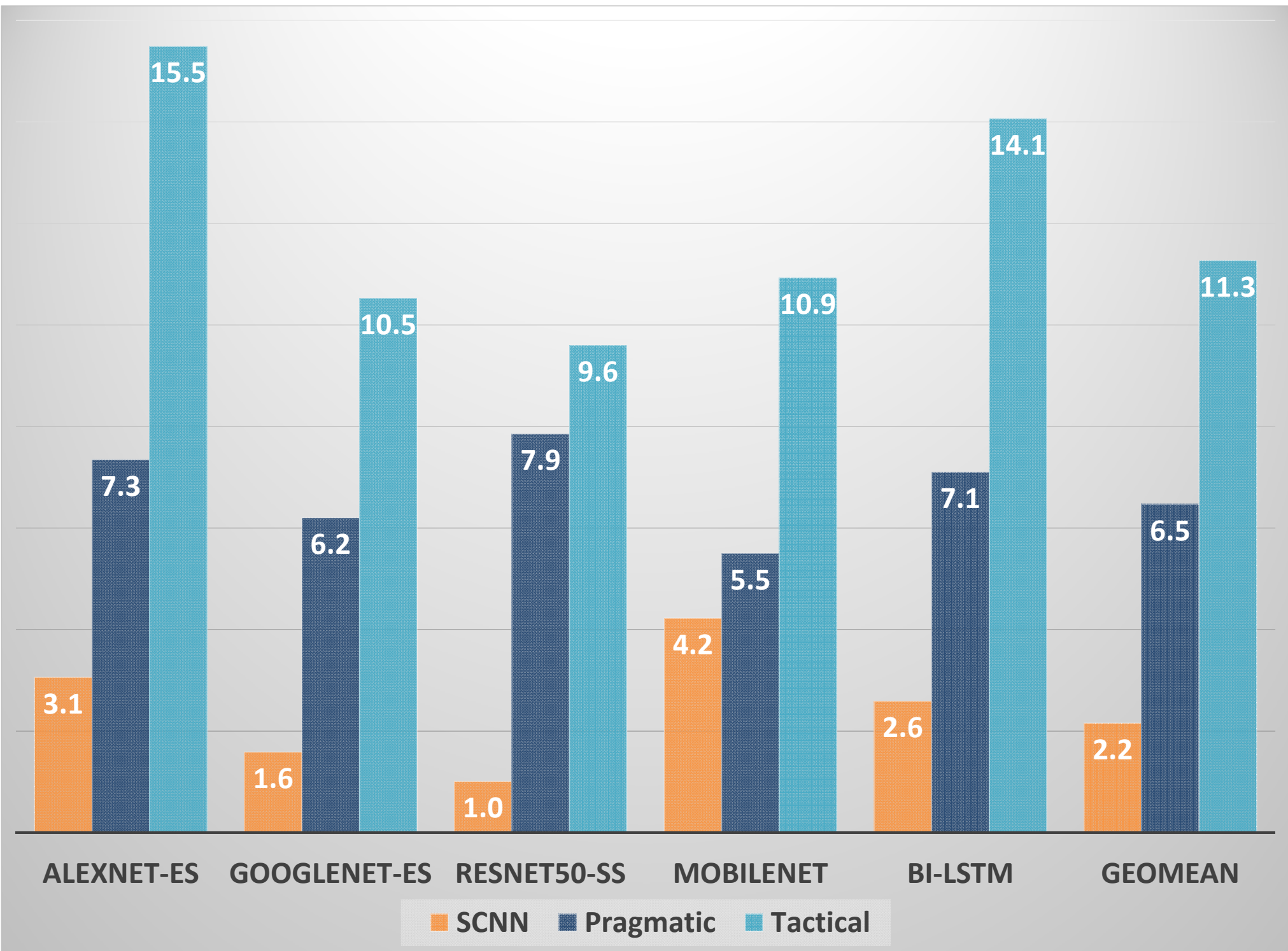
$$\text{Out} += \begin{bmatrix} 1 & 1 \end{bmatrix} \times W_0$$

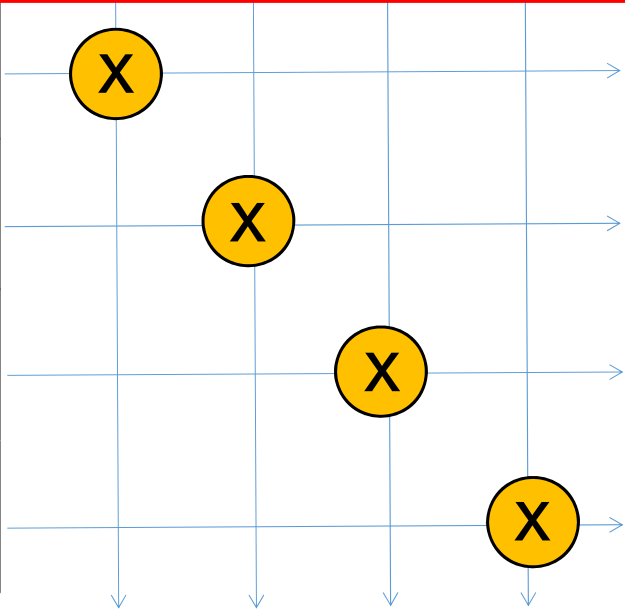
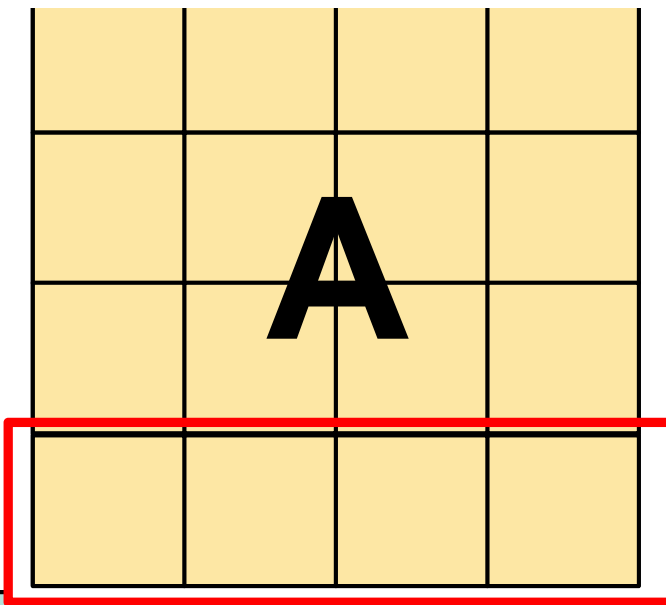
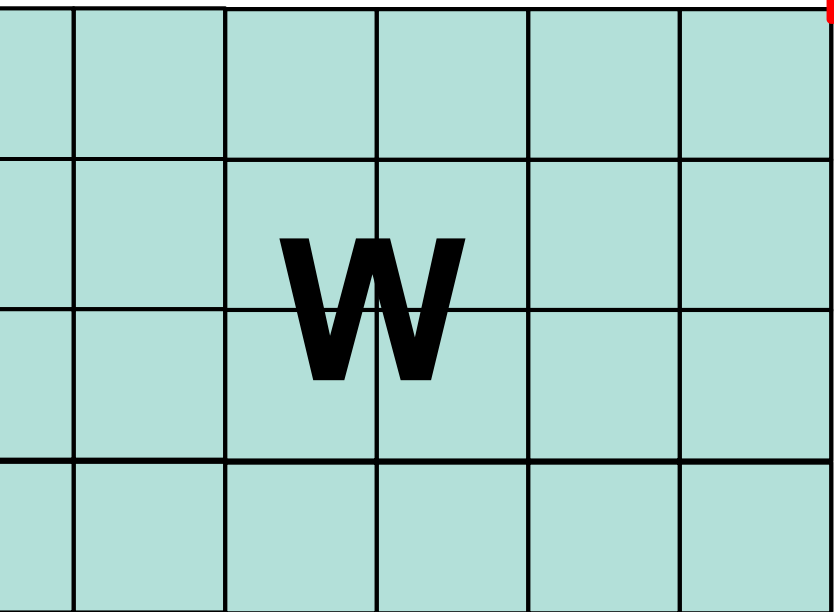
$$\text{Out} += \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \times W_2$$

$$\text{Out} += \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \times W_3$$

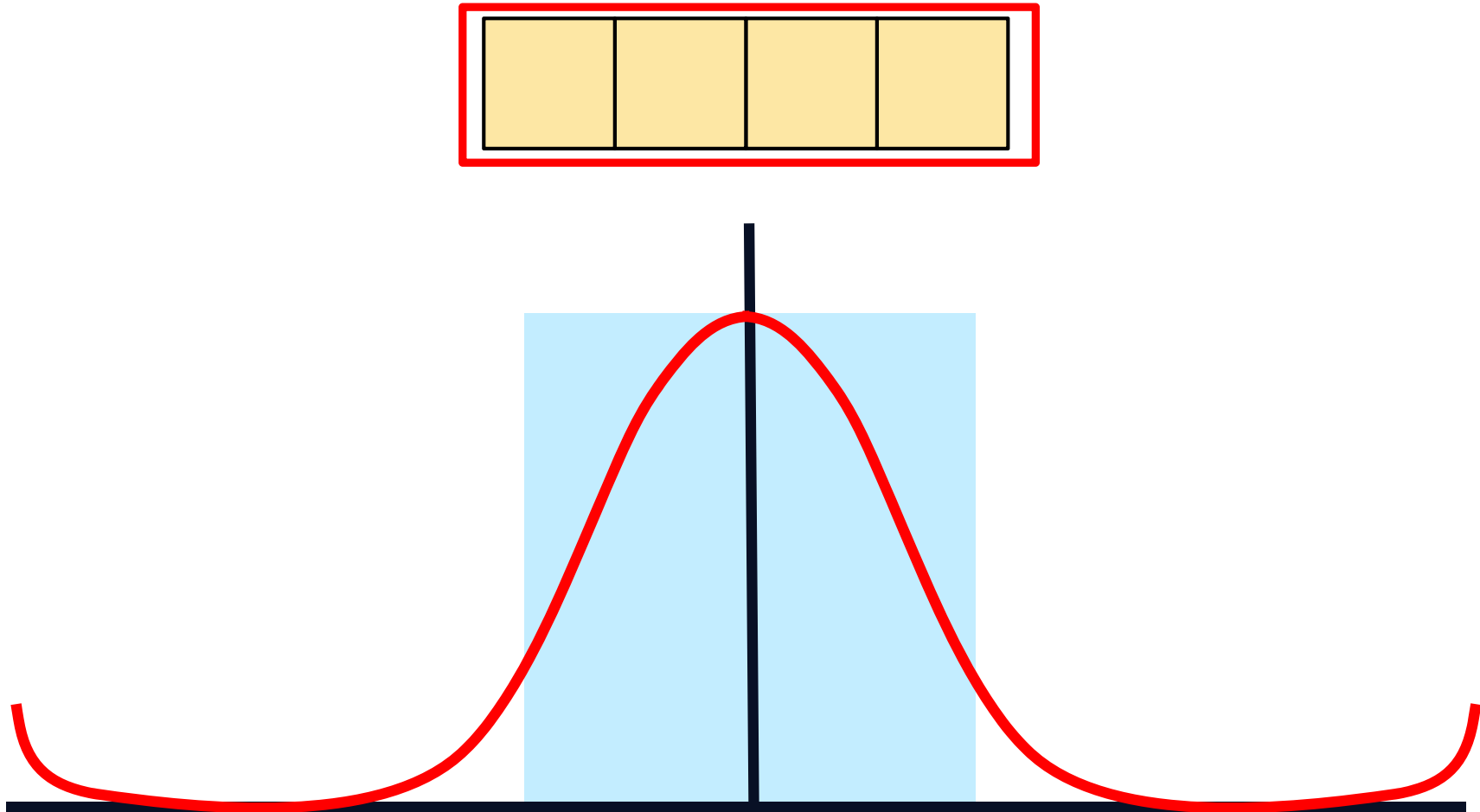
$$\text{Out} += \begin{bmatrix} 1 & & & 1 \end{bmatrix} \times W_4$$





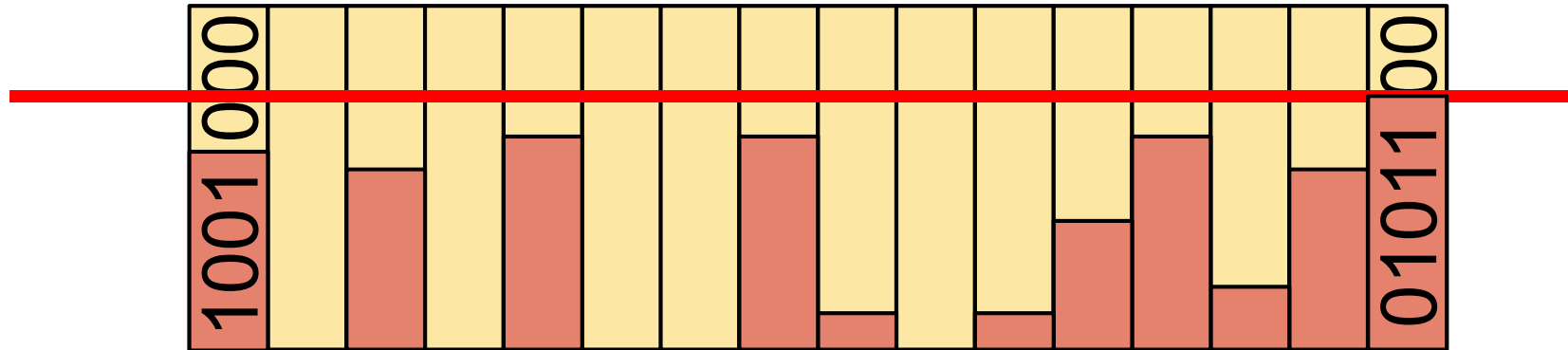
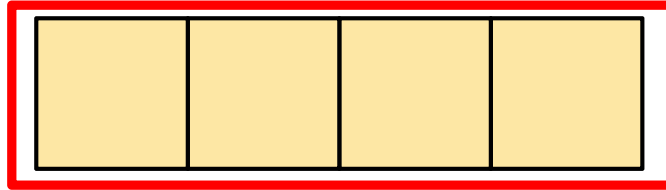


Making Typical Values Matter



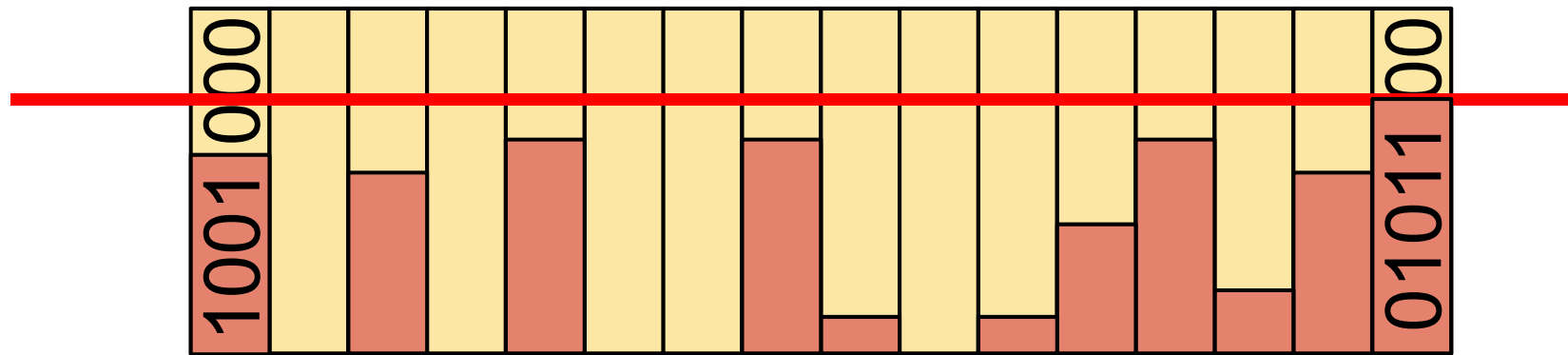
DPRed: Making Typical Activation and Weight Values Matter In Deep Learning Computing, Delmas et al.,
<https://arxiv.org/abs/1804.06732>

Fine-Grain Precision Adaptation

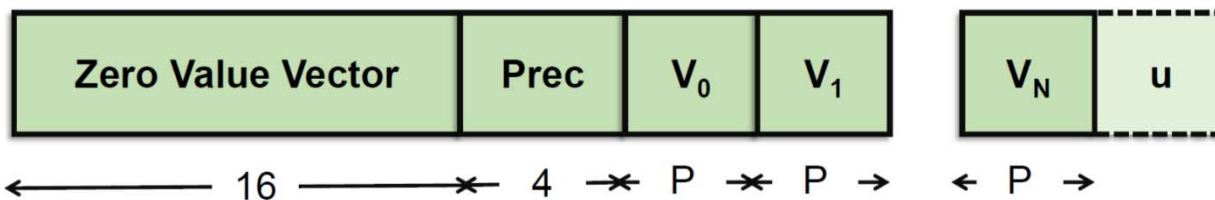
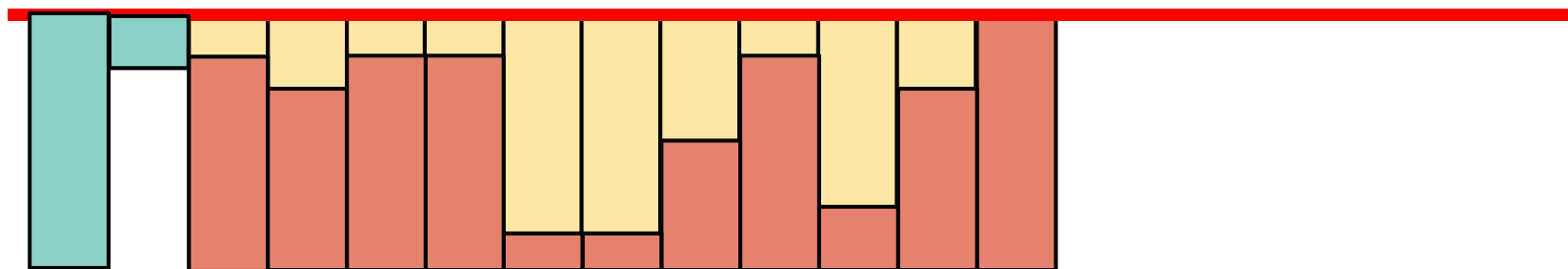


Per Group Precision Detection/Encoding

Detect Precisions: On-the-fly for Activations + Statically for Weights



In Memory



← 16 → * 4 * P * P → ← P →

Takeaways

Don't go after all $W = 0$

Go for enough

Software Scheduler + Restricted Motions are enough

Don't go after $A = 0$

Go for bit sparsity 50% vs 90%+

Don't let the loud values dominate the data type

Encode in groups

Bit-Tactical: Exploiting Ineffectual Computations in Convolutional Neural Networks: Which, Why, and How, [Alberto Delmas](#), [Patrick Judd](#), [Dylan Malone Stuart](#), [Zissis Poulos](#), [Mostafa Mahmoud](#), [Sayeh Sharify](#), [Milos Nikolic](#), [Andreas Moshovos](#), arXiv:1803.03688

Laconic: Goal

```
      W 0001 0100
      A 0010 1010
-----
      0000 0000
      0010 1010
      0000 0000
      0010 1010
      0000 0000
      0010 1010
      0000 0000
      0000 0000
```

Laconic: Goal

W 0001 0100

A 0010 1010

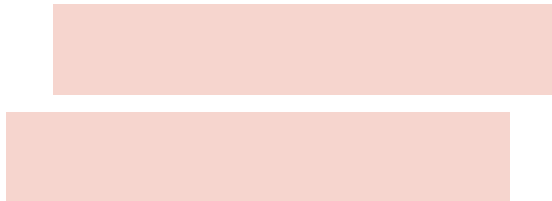
0010 1010

0000 0000

0010 1010

0000 0000

0010 1010



Laconic: Goal

W 0001 0100

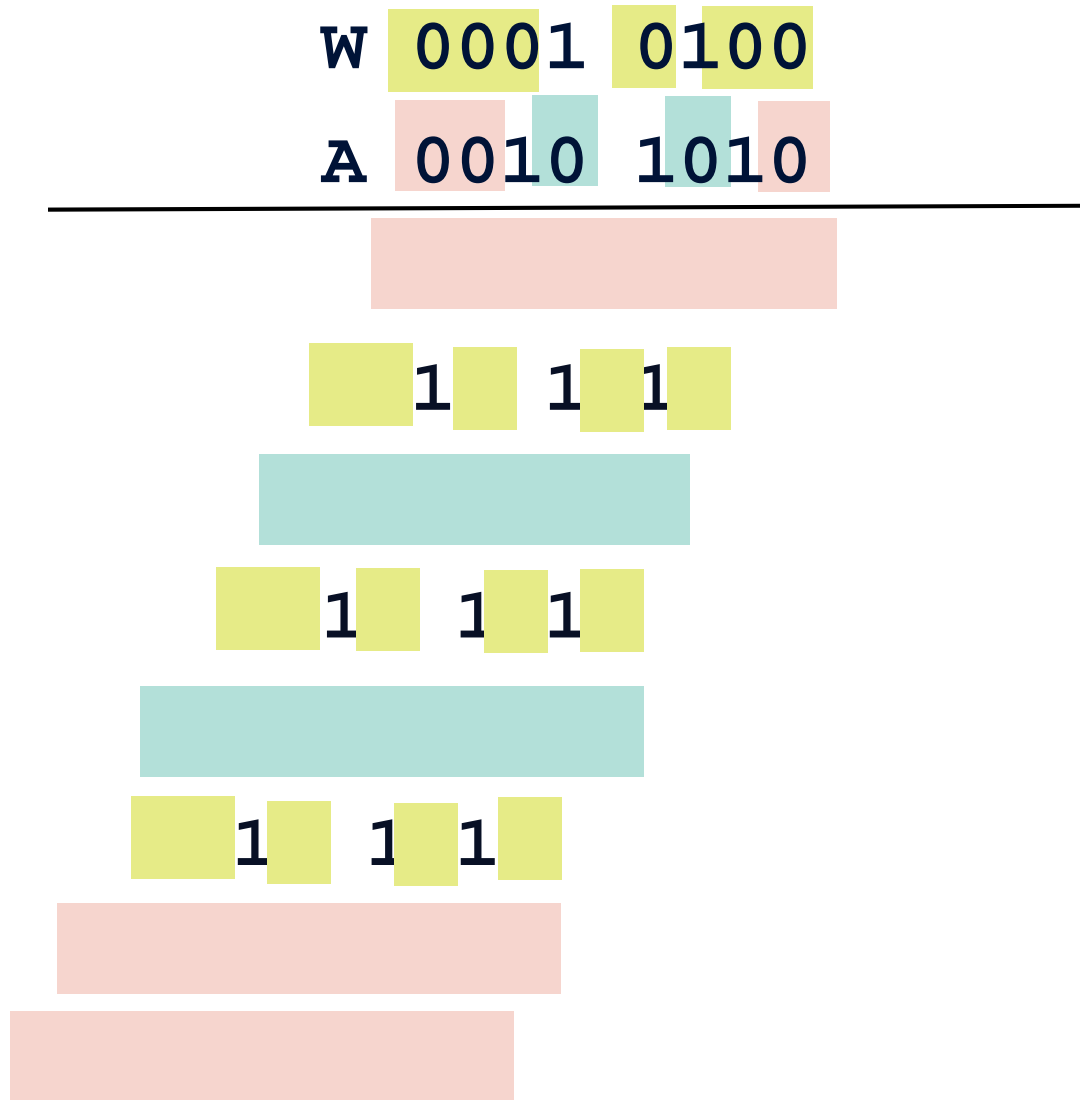
A 0010 1010

0010 1010

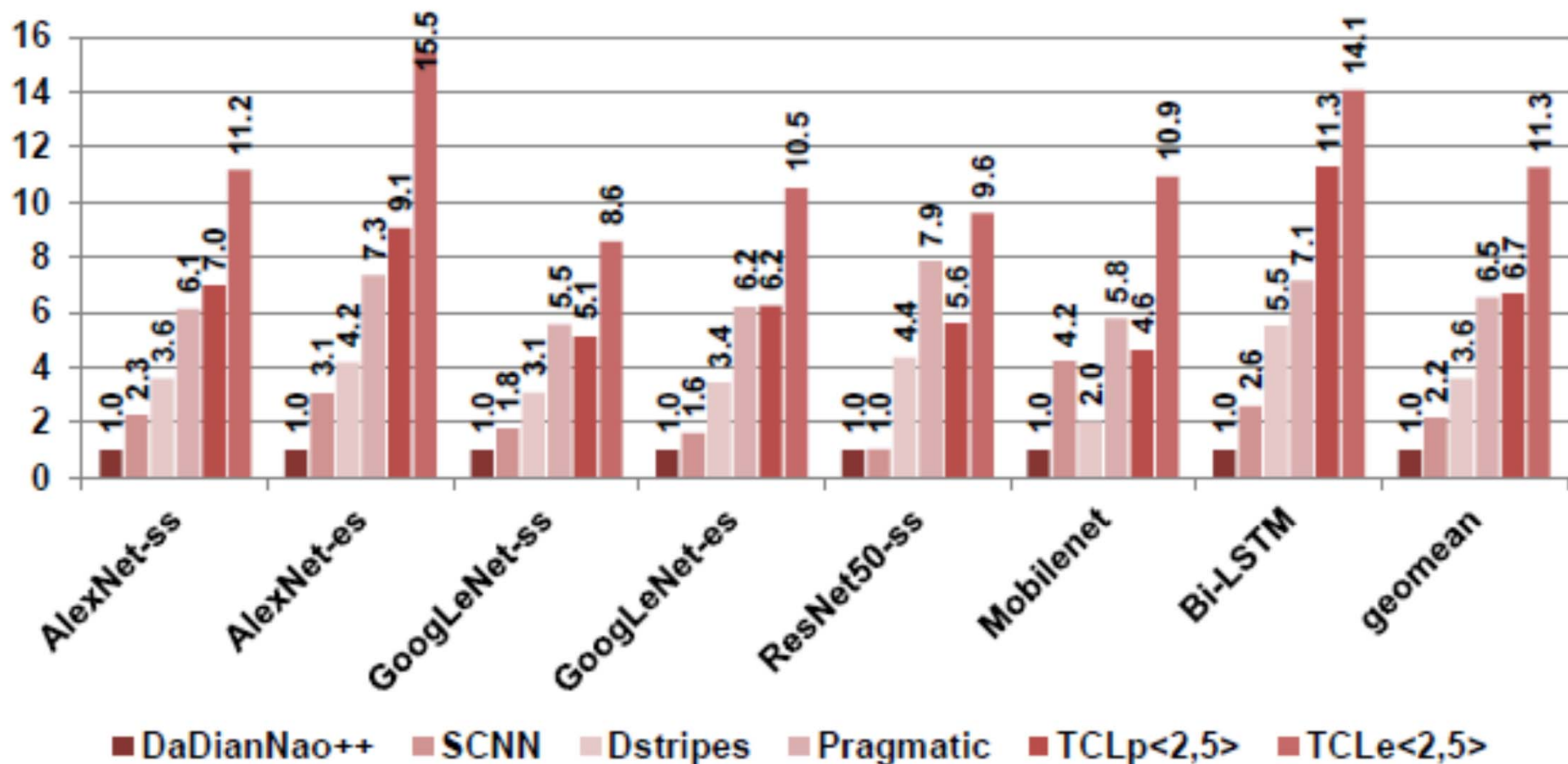
0010 1010

0010 1010

Laconic: Goal



- **Best for edge devices**
- **Laconic Deep Learning Computing**, *Sayeh Sharify, Mostafa Mahmoud, Alberto Delmas Lascorz, Milos Nikolic, Andreas Moshovos, Arxiv, **arXiv:1805.04513***



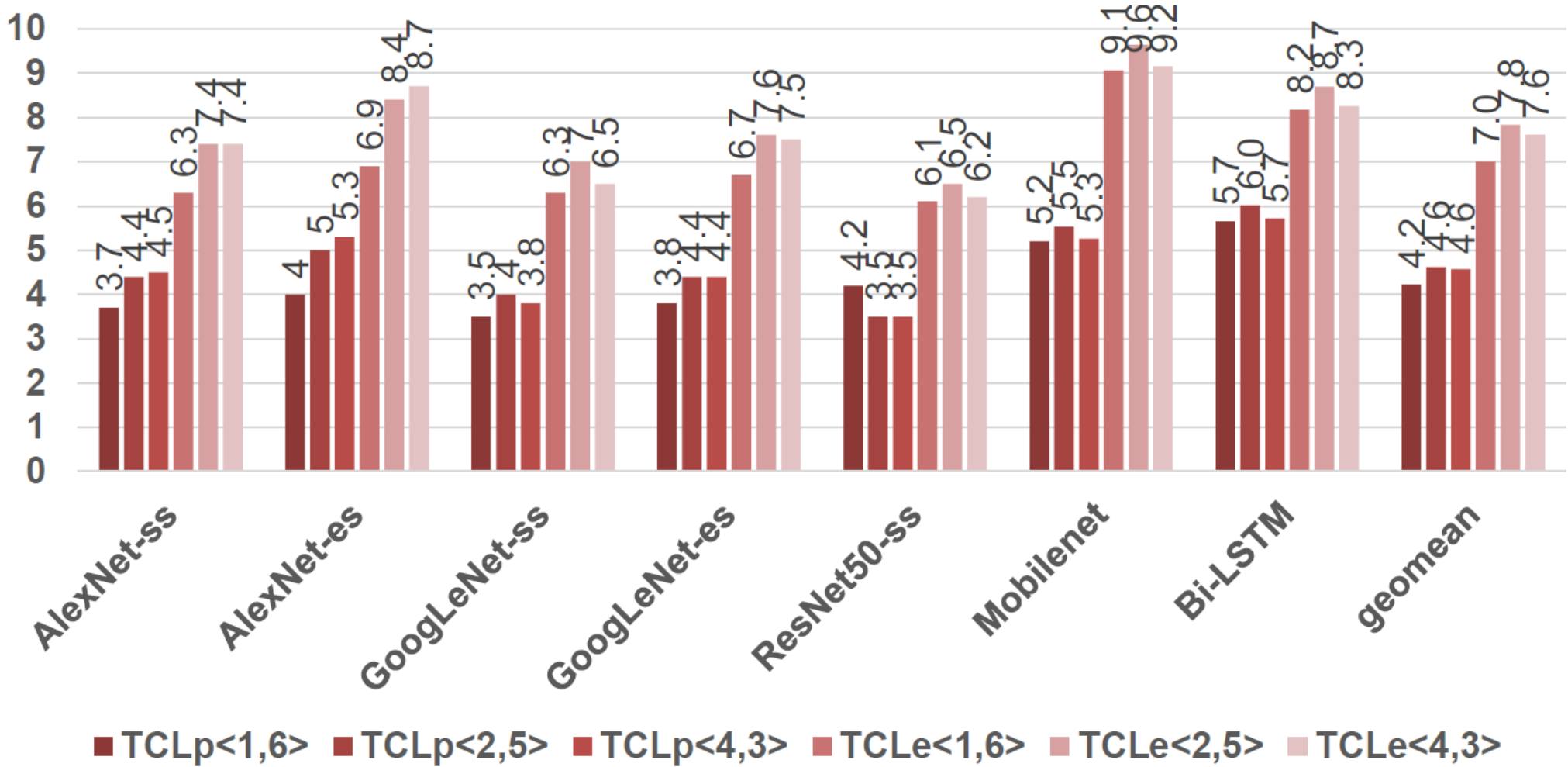


Figure 12: Speedup with 8b quantization