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NanoEdge AI Studio

Your fast track to smart products

Yijun DENG

APAC AI Competence Center

Aug 2022

NANOEDGE AI STUDIO

Agenda

1 Introduction to NanoEdge AI Studio

2 NanoEdge AI step by step

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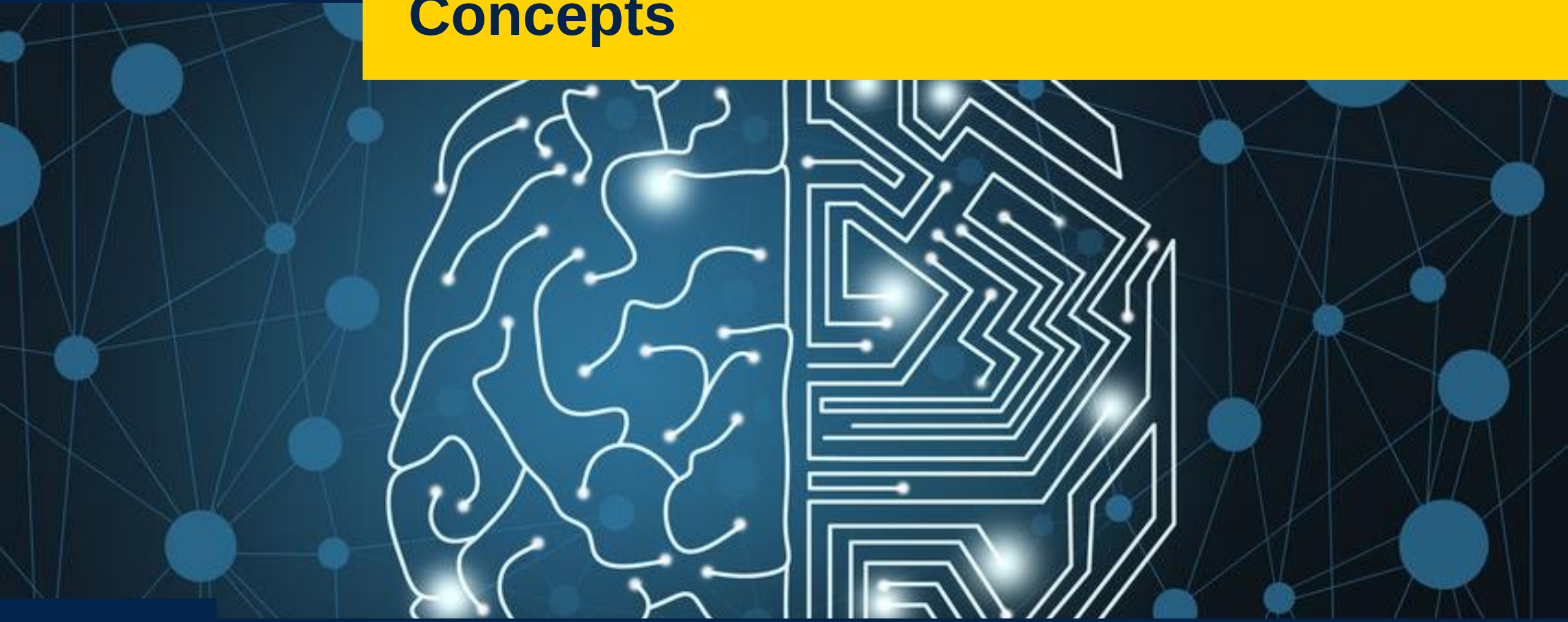
Quick Recap: Machine Learning Concepts



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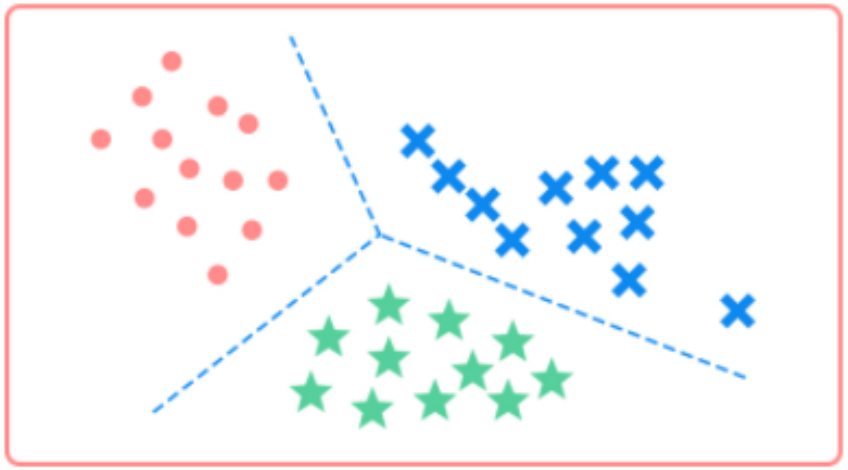
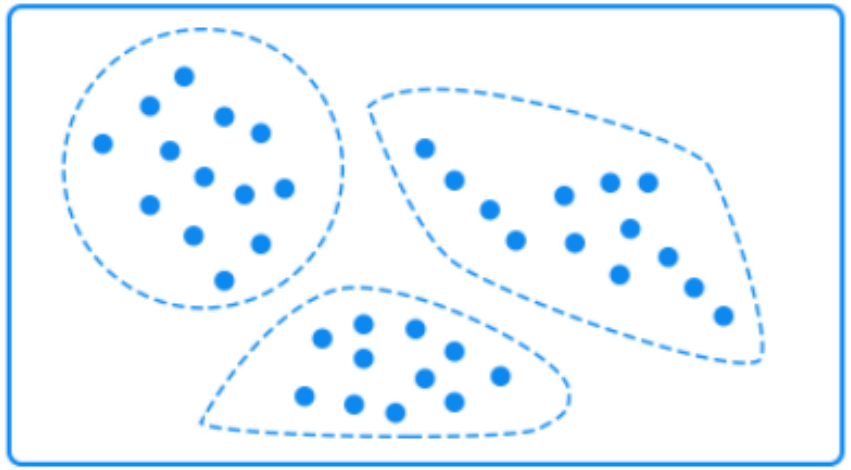
Machine Learning

- Can be divided into:
- Supervised learning: machine learning algorithm which learns a function that maps an input to an output based on example input-output pairs. E.g., Decision Tree, Support Vector Machine, Linear Regression, Deep Learning, …
- Unsupervised learning: machine learning algorithm which learns unknown patterns from un-labeled data. E.g., Clustering, K-Means, …



Supervised learning



Unsupervised learning

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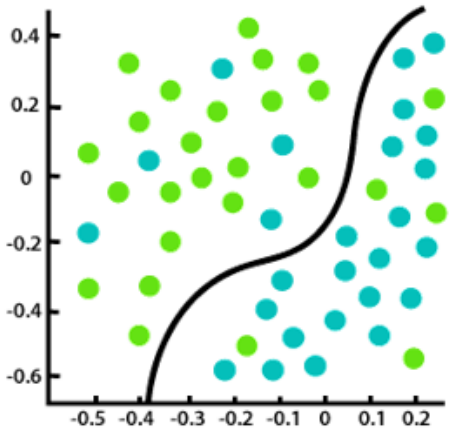
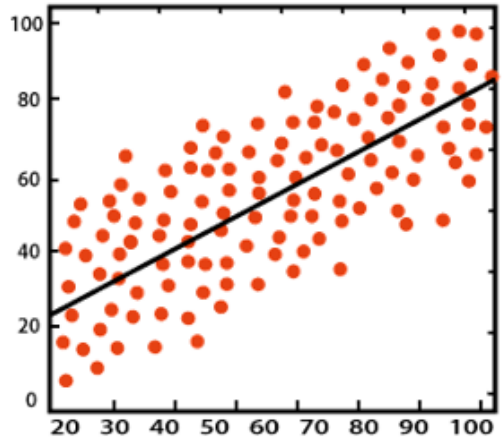
Classification vs Regression

- Supervised learning contains mainly 2 categories:
- Classification: algorithm to predict a discrete class label
- Regression: algorithm to predict a continuous quantity



Classification



Regression

Introduction to NanoEdge AI Studio

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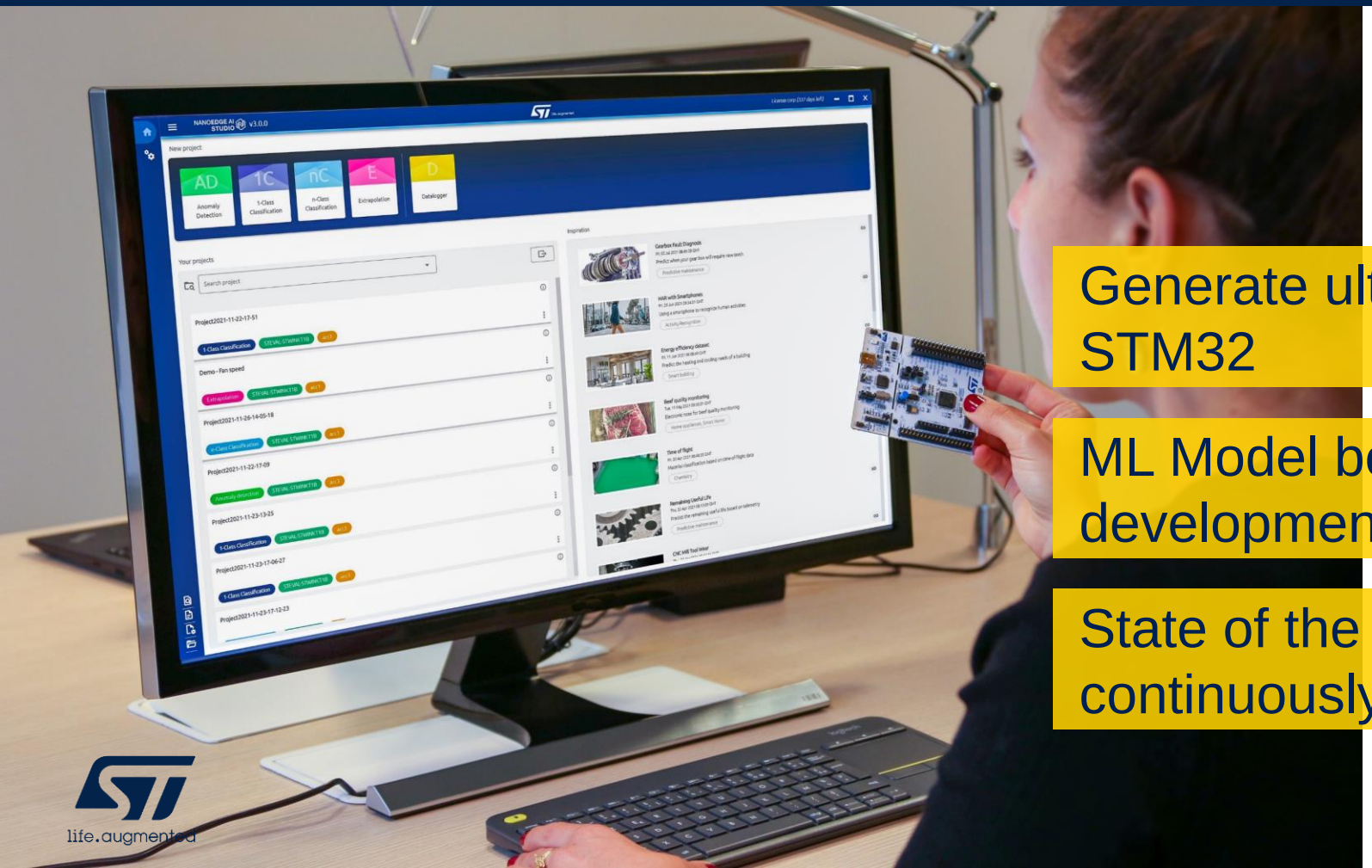
NanoEdge AI Studio

NanoEdge AI Studio, an automated ML design solution



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Generate ultra optimized ML library for any STM32

ML Model benchmark to speed up your development time

State of the art of ML implemented continuously: no specific AI skills needed

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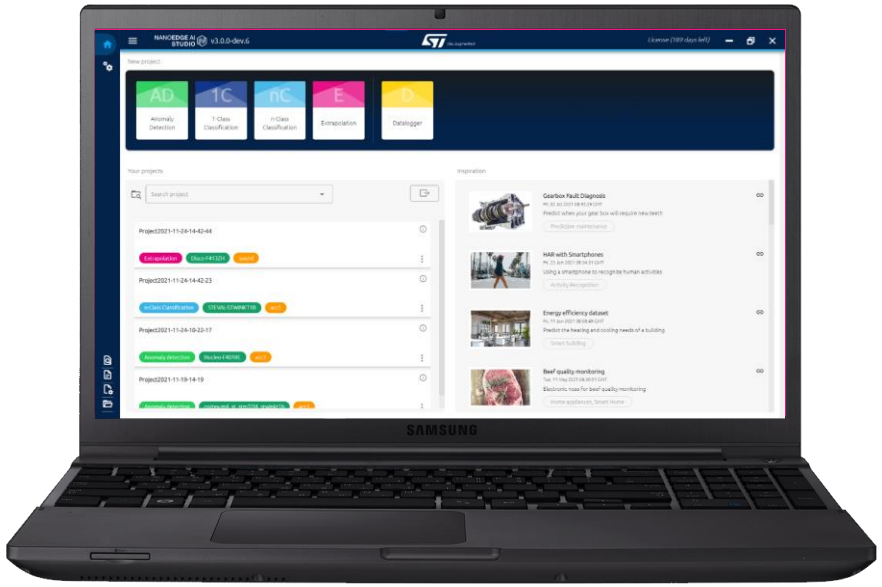
NanoEdgeAI Studio
For customers without AI expertise

1 Create the library, ONCE



Standalone PC (Win/Linux) solution

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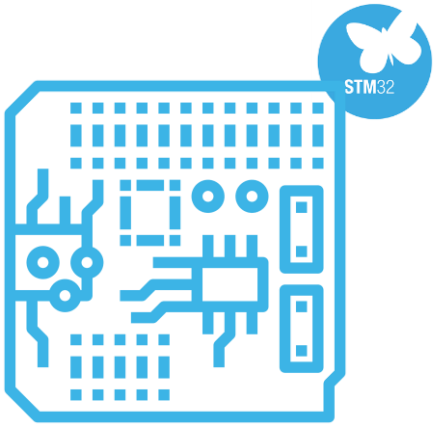
2 Use the library, MANY



Create and embed a self learning engine

For anomaly detection, the model is self-trained at the Edge

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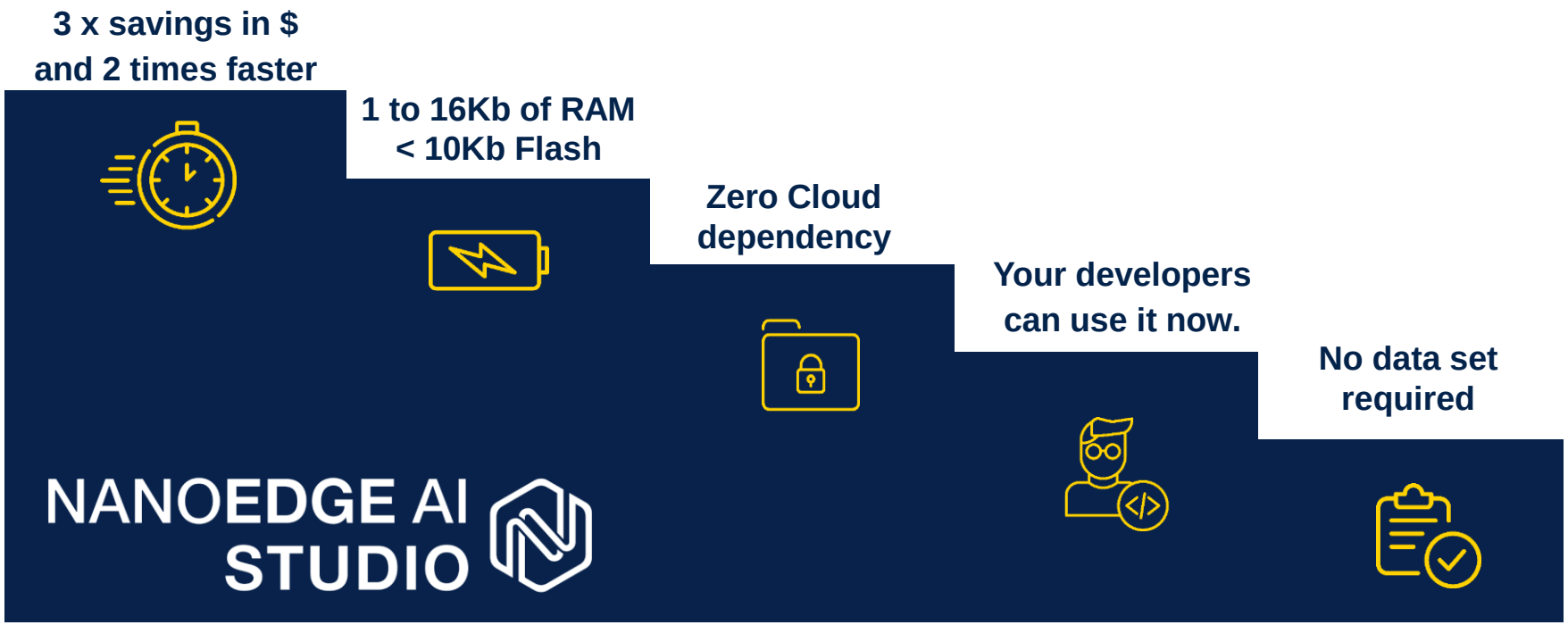
Create a state-of-the-art AI solution in a simple, fast, and affordable way

The power to create Edge AI solution, simply, quickly and affordably.



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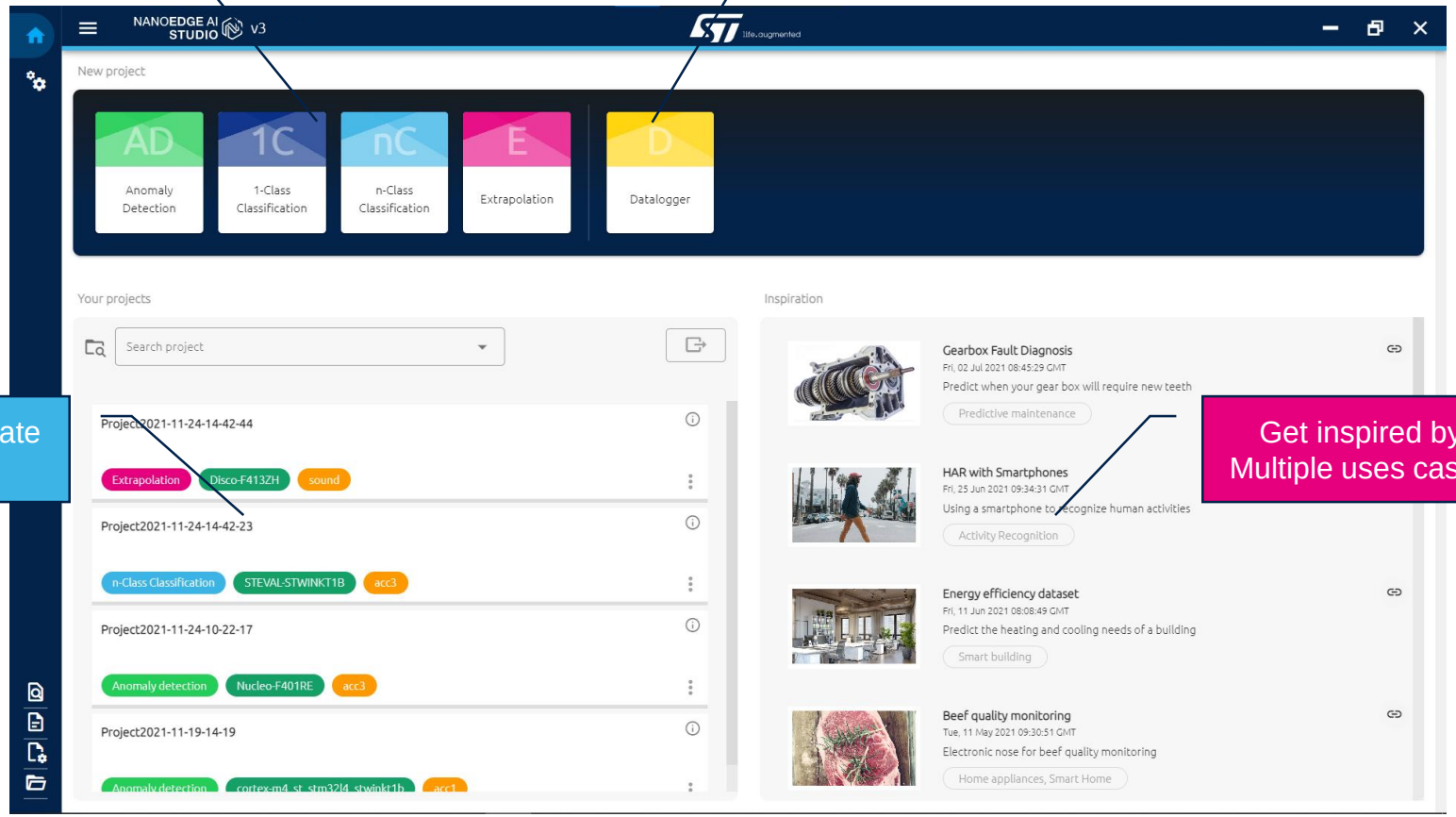
NanoEdge AI Studio V3: New User Interface More Functions, Better User Experience

New families of Machine Learning algorithms

New Datalogging experience



Easily retrieve or create projects

Get inspired by Multiple uses cases

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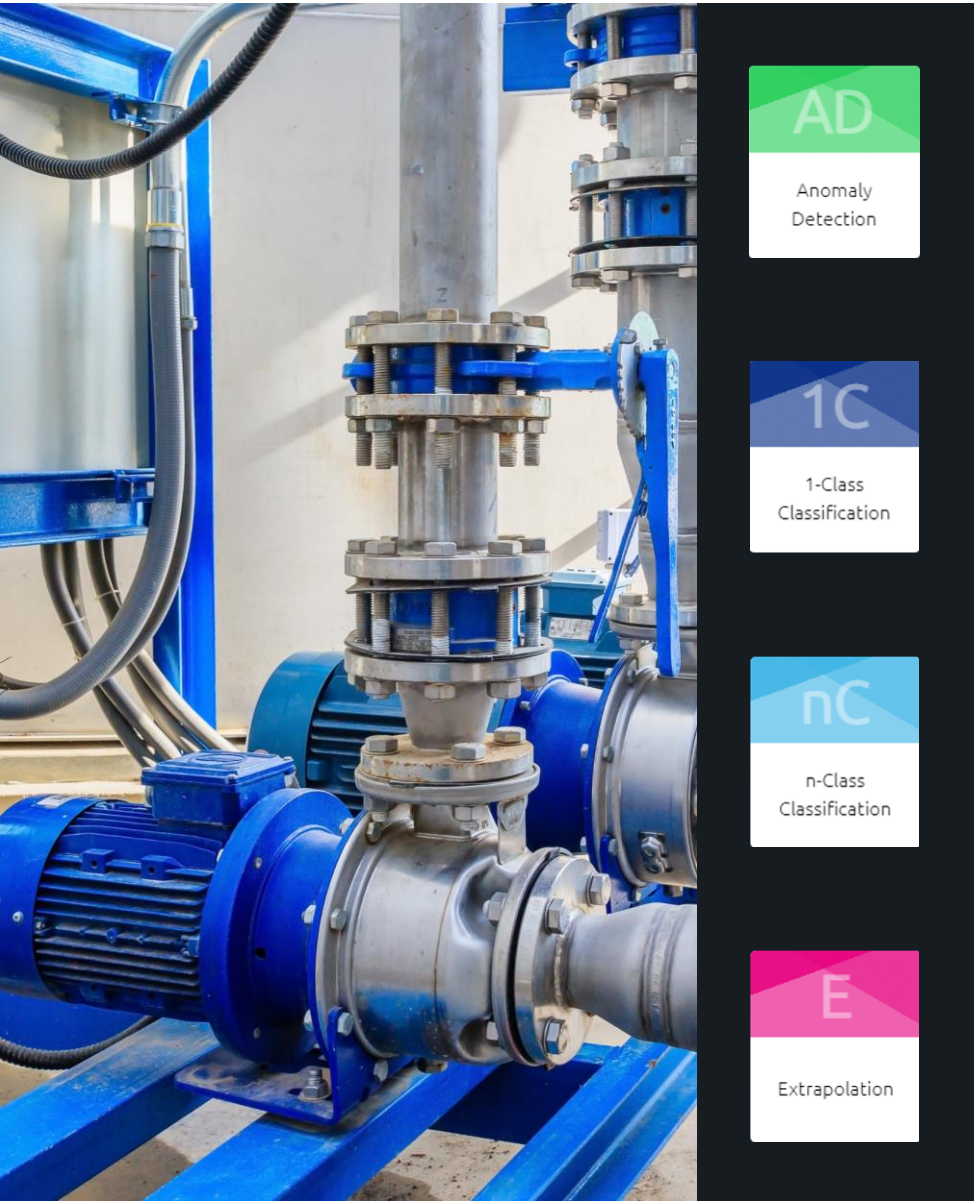
Our Customers Have Increasingly Ambitious Use Cases For Ever More Smart Products



AD
Anomaly Detection

1C
1-Class Classification

nC
n-Class Classification

E
Extrapolation

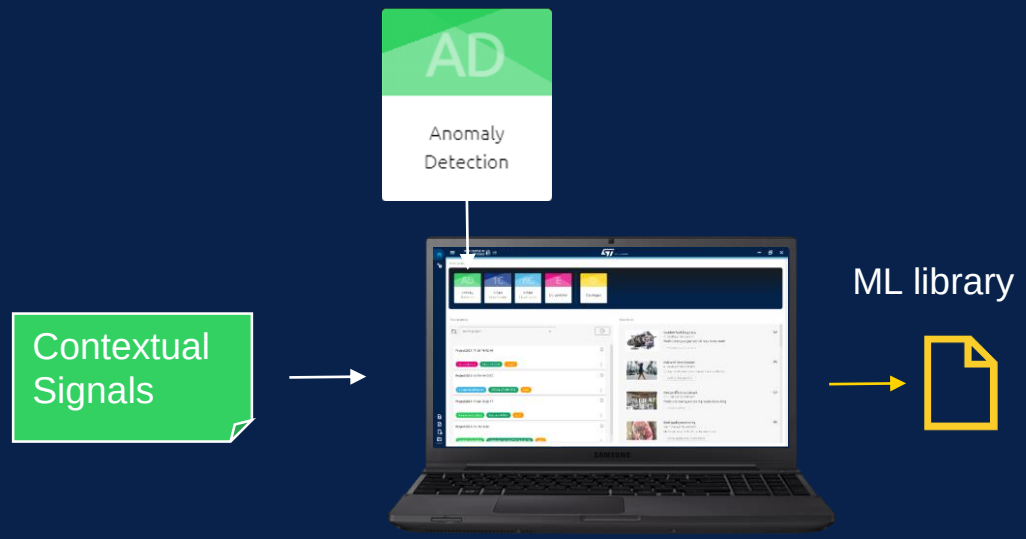
"My pumps are installed in a variety of environments that I can't anticipate.
I want them to autonomously adapt to their target environment and detect anomalies by themselves."

"I know exactly how my pumps behave.
I want to detect any outliers."

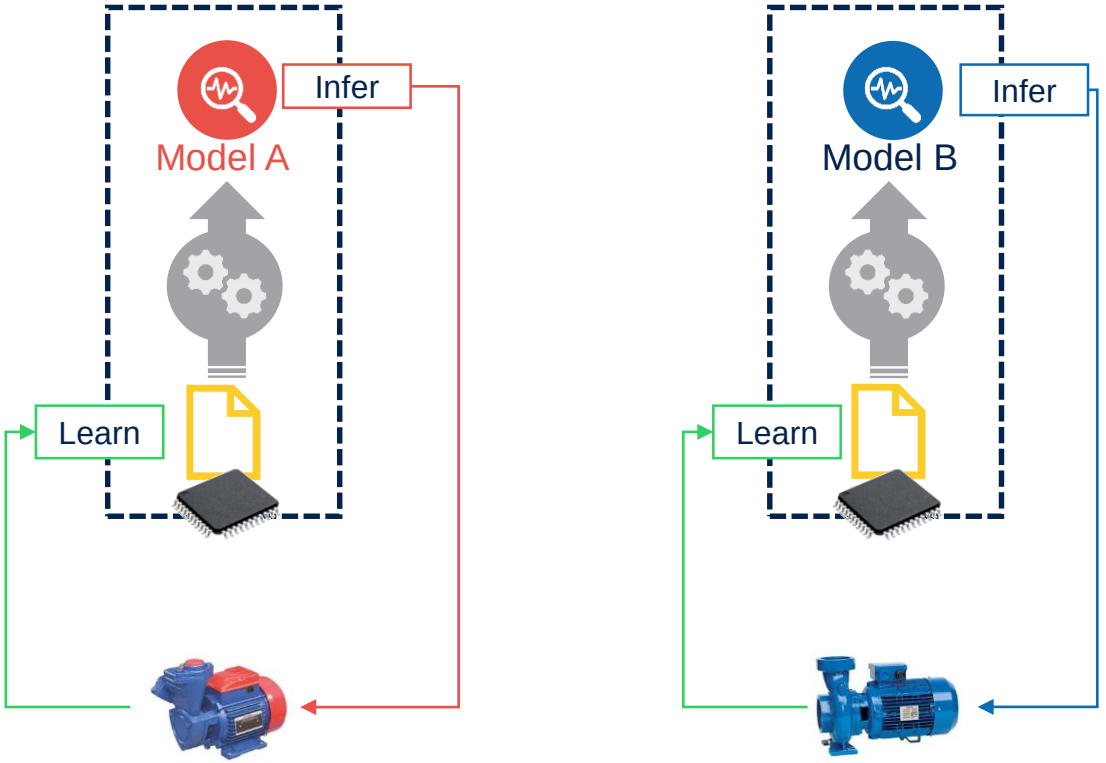
"I know the signals when a pump is experiencing, for example, ball bearing or cavitation problems.
I want to know by name what problems are occurring."

“I know several vibration values of my machine.
I want to anticipate when a specific vibration level will be reached so that I have time to take corrective actions before reaching that limit.”

Step 1 **(PC Side)**
Creation of an
ANOMALY DETECTION
Machine Learning library



Step 2 **(MCU Side)**
Use of an
ANOMALY DETECTION
Machine Learning library



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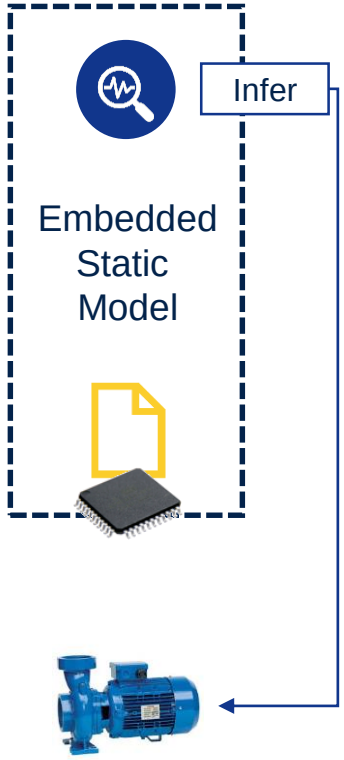
Step 1 **(PC Side)**
Creation of
ONE CLASS CLASSIFICATION (NEW)
Machine Learning library

Step 2 **(MCU Side)**
Use of a
ONE CLASS CLASSIFICATION
Machine Learning library



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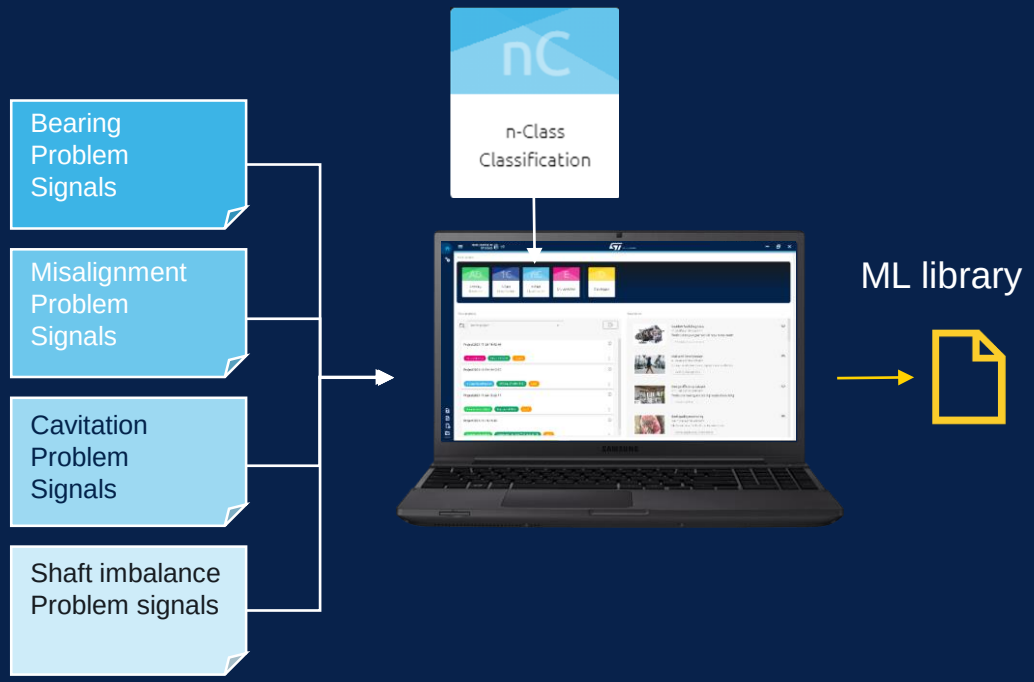
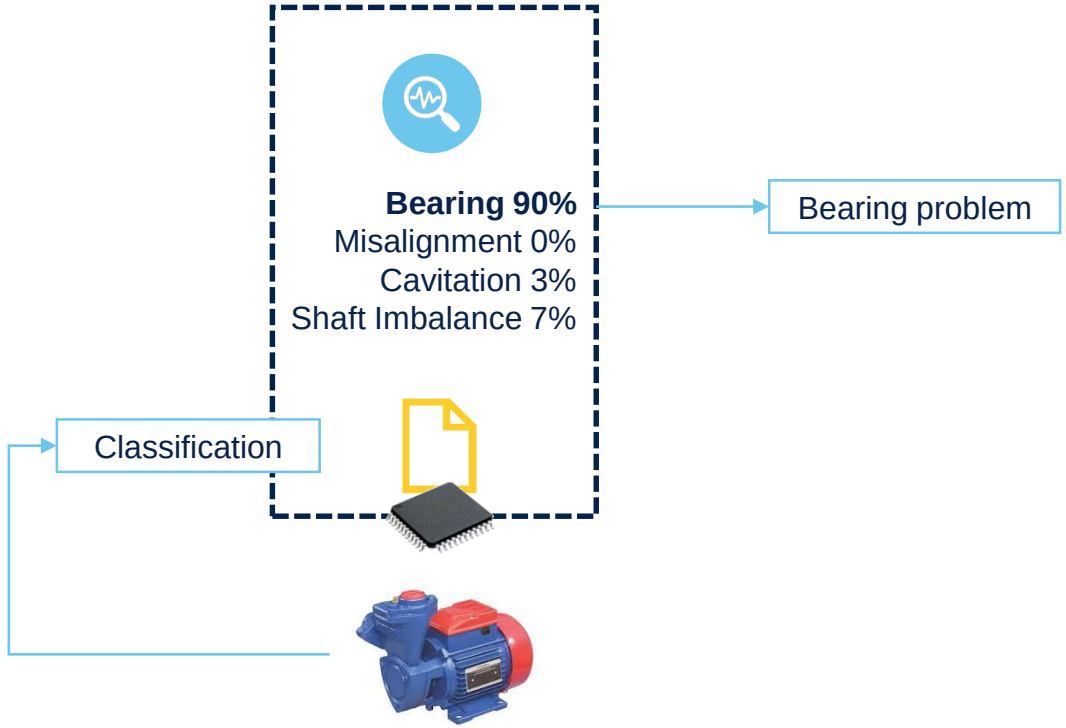
NANOEDGE AI STUDIO

Step 1 **(PC Side)**
Creation of an
n CLASS CLASSIFICATION
Machine Learning library



Step 2 **(MCU Side)**
Use of an
n CLASS CLASSIFICATION
Machine Learning library



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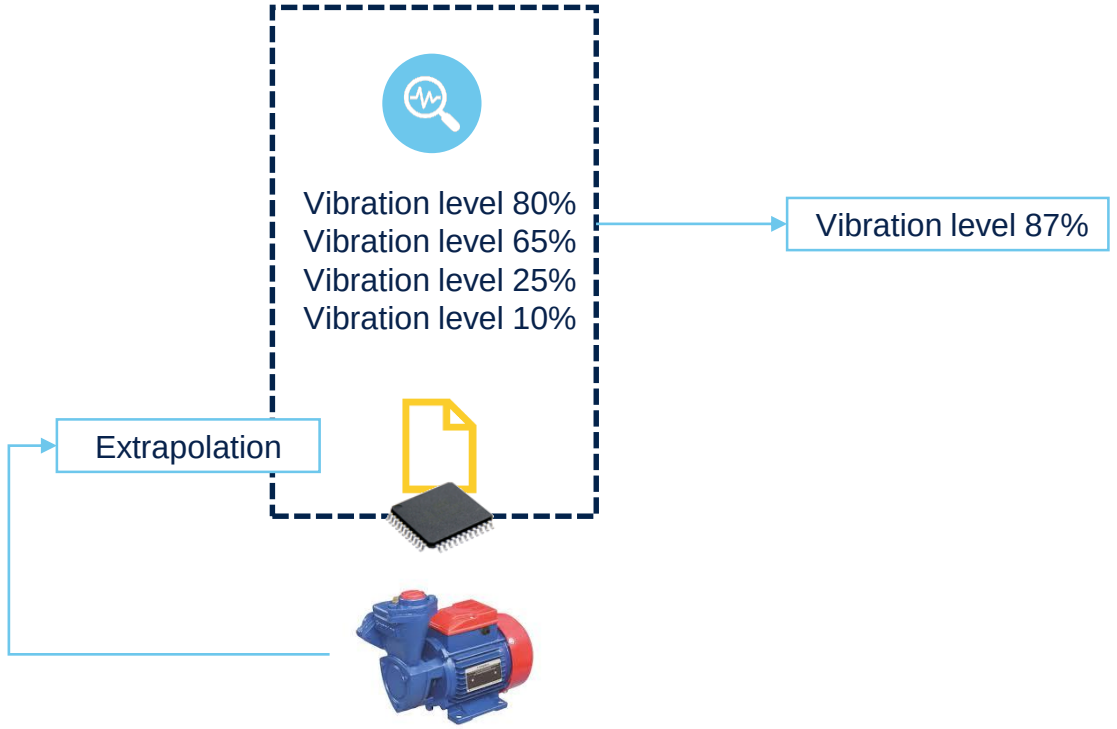
Step 1 **(PC Side)**
Creation of an
EXTRAPOLATION (NEW)
Machine Learning library

Step 2 **(MCU Side)**
Use of an
EXTRAPOLATION
Machine Learning library



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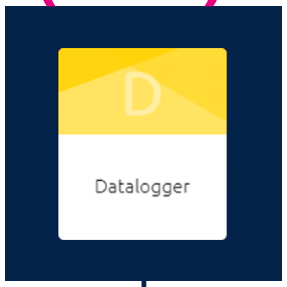
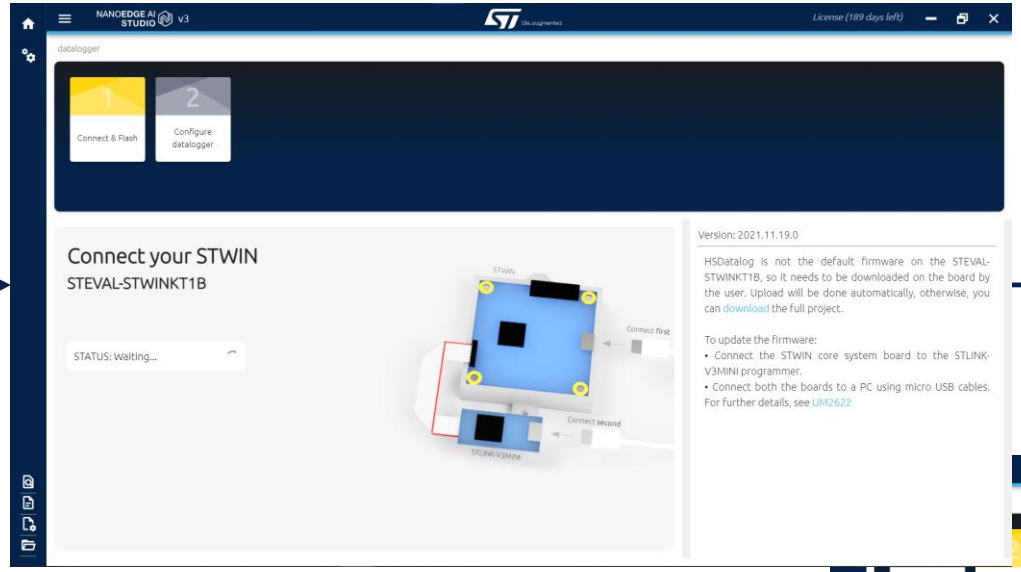
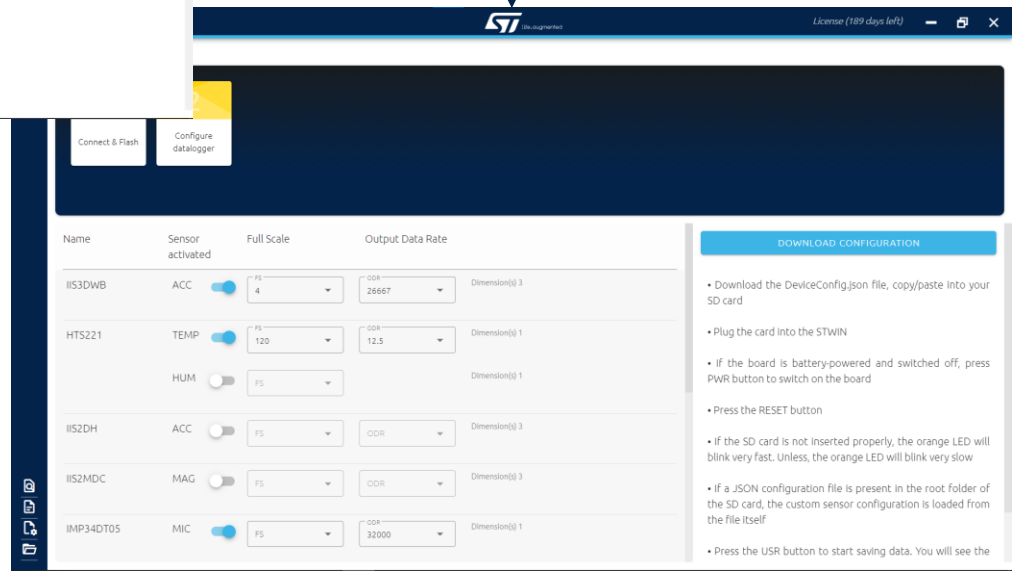
From Idea To Datalogging In A Matter Of Minutes

(NEW)



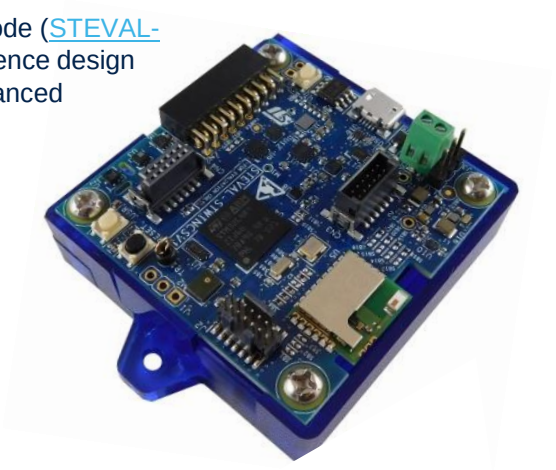


- Streamlined data logging process
- No code
- All settings done using a graphic interface



The STWIN SensorTile wireless industrial node (STEVAL-STWINKT1B) is a development kit and reference design that simplifies prototyping and testing of advanced industrial IoT applications such as condition monitoring and predictive maintenance

The kit features a core system board with a range of embedded industrial-grade sensors and an ultra-low-power microcontroller



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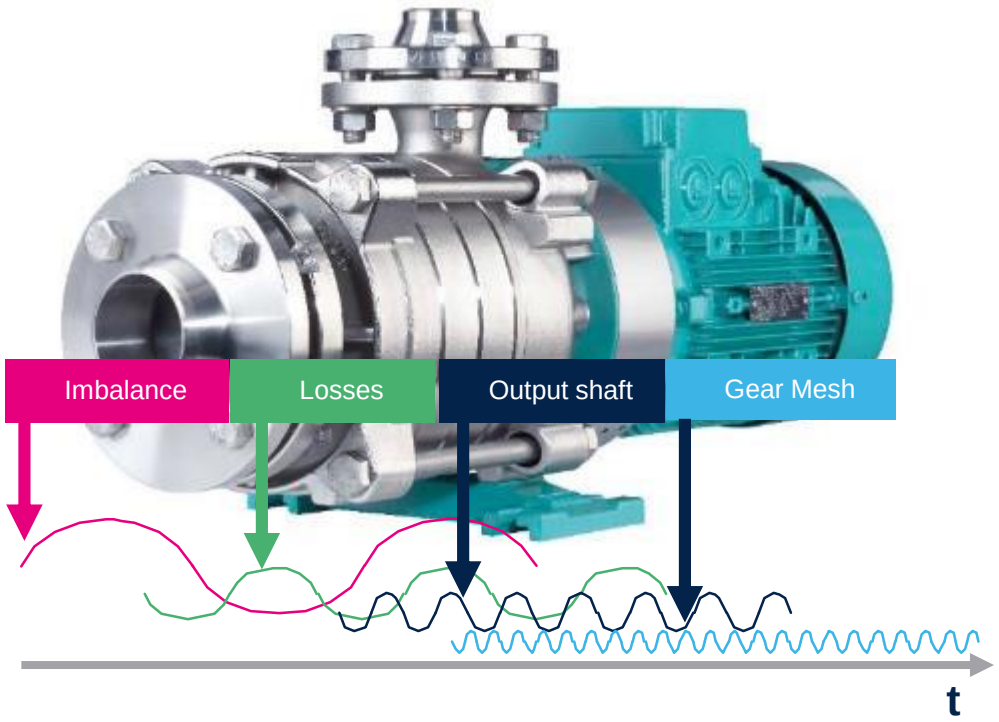
Typical use case industrial motor monitoring

Any parameter deviation is an indicator of potential failure

Mechanical vibration

- Displacement
- Speed
- Acceleration
- Acoustic noise
- Angular speed
- Torque



Functions to enable monitoring

Vibration Capture

Connectivity

Wireless Connectivity

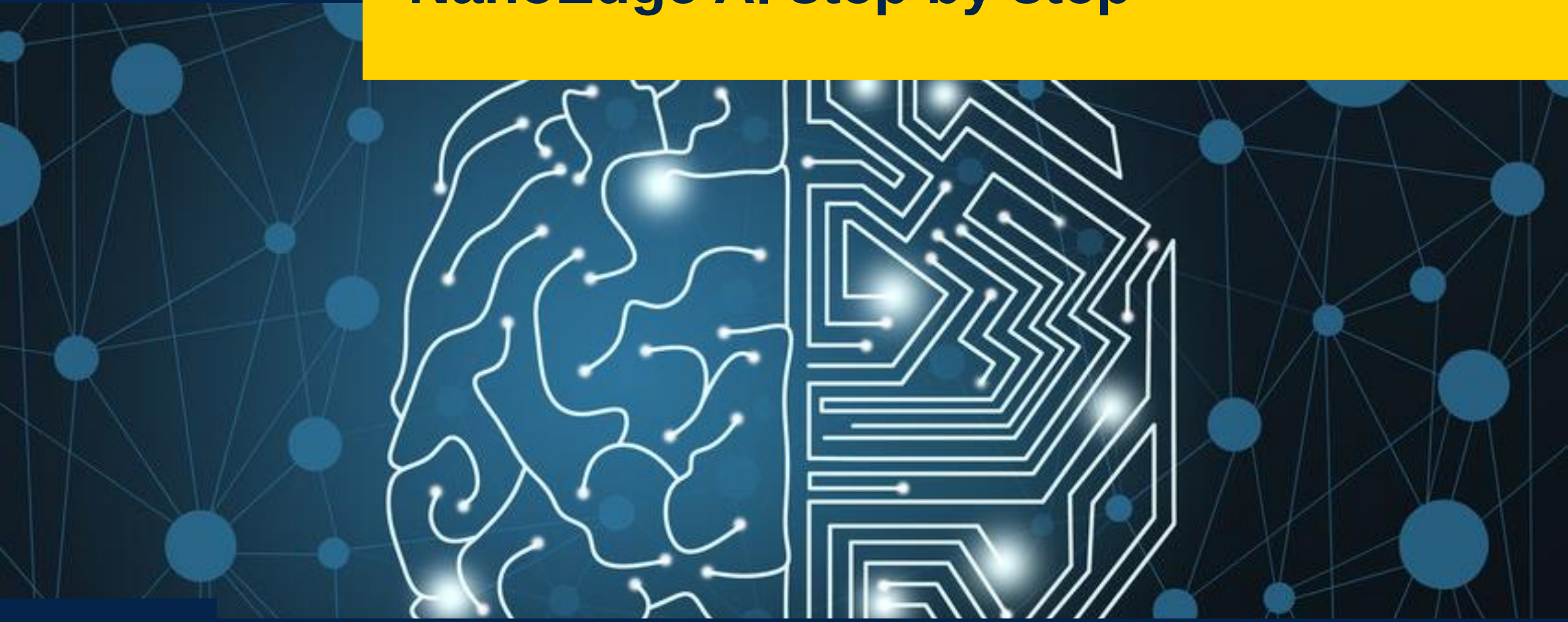
Processing

A
f

Secure Connections

Demo
Motor Control with NanoEdge AI

NanoEdge AI step by step



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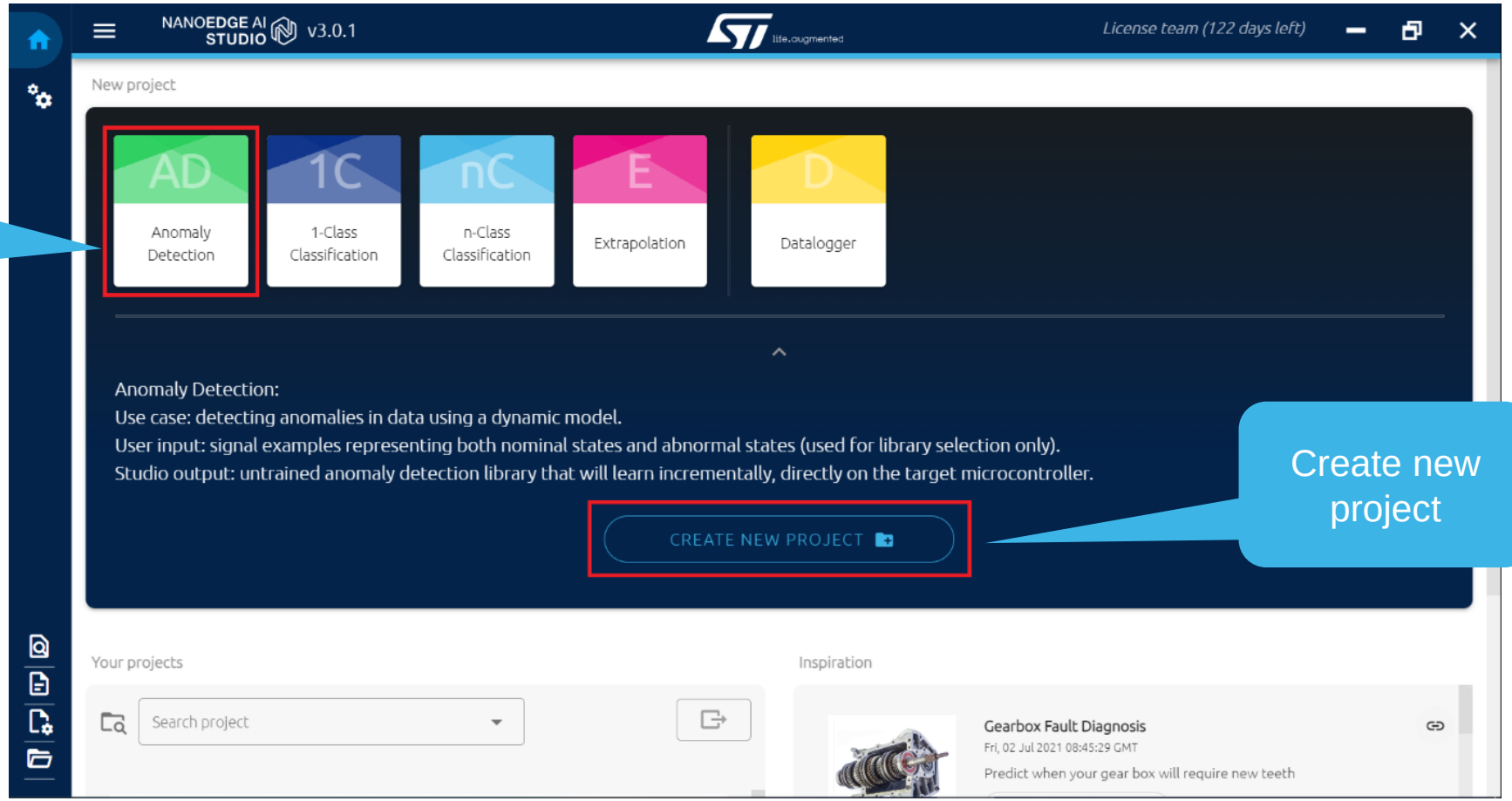
Creating new project

Suppose we want to detect anomaly of an electric motor based on current signal

1

Select Anomaly Detection

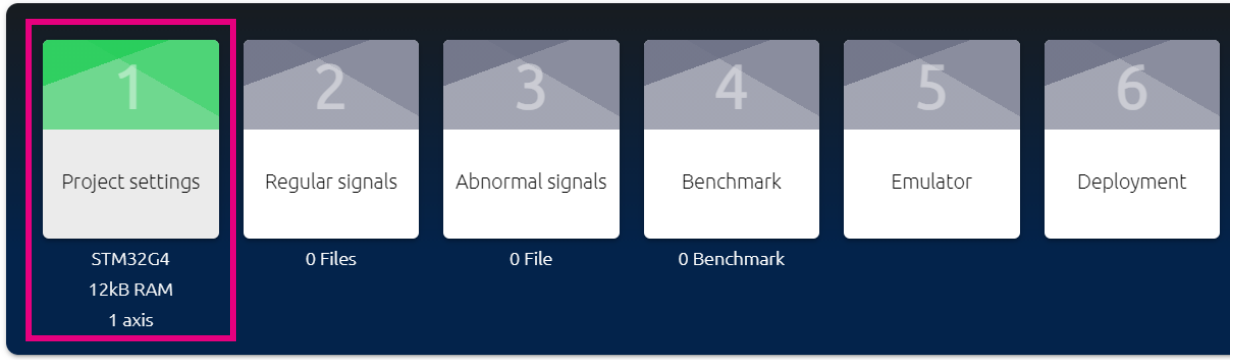


2

Create new project

Project settings

In “Project settings”, fill basic information of the project



Name of project

Max RAM allocated for AI library

Max Flash allocated for AI library

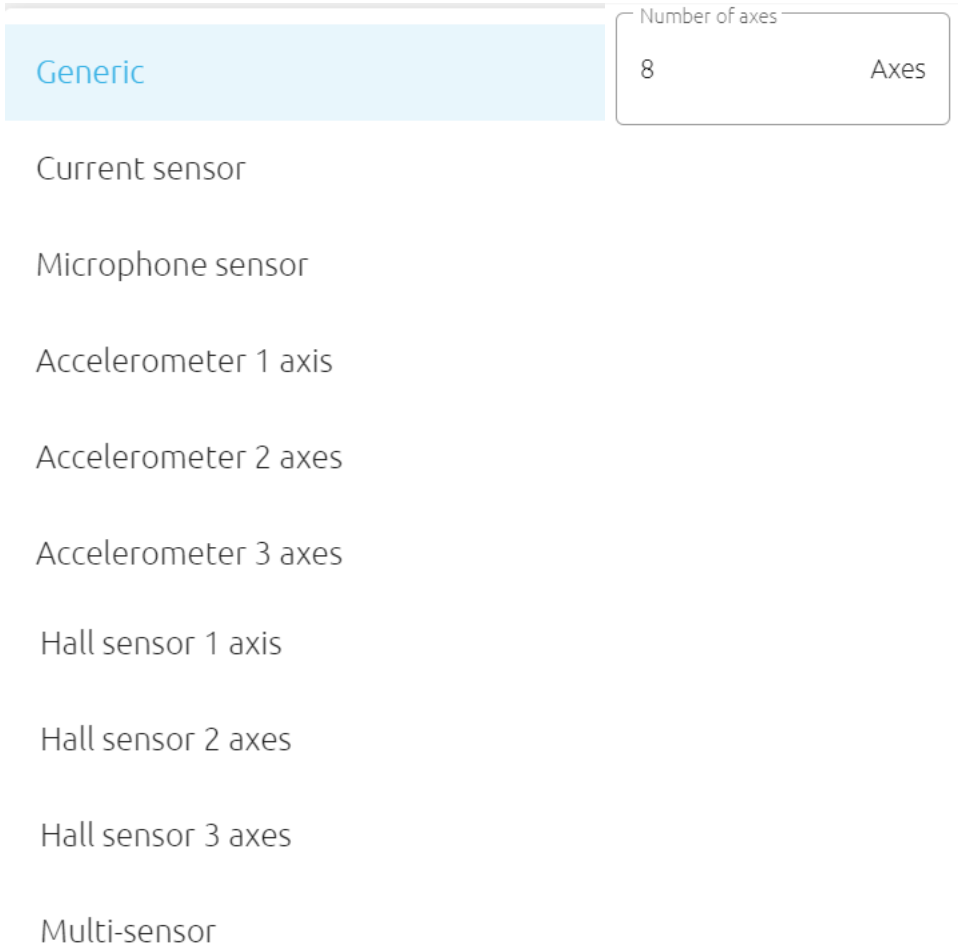
Target ISPU / MCU / board

Sensor type for input signal

Project settings

List of supported sensor types in NanoEdge AI

- Some typical sensor types are supported
- Also possible to combine different sensor types in the same input thanks to “**Generic**” type.



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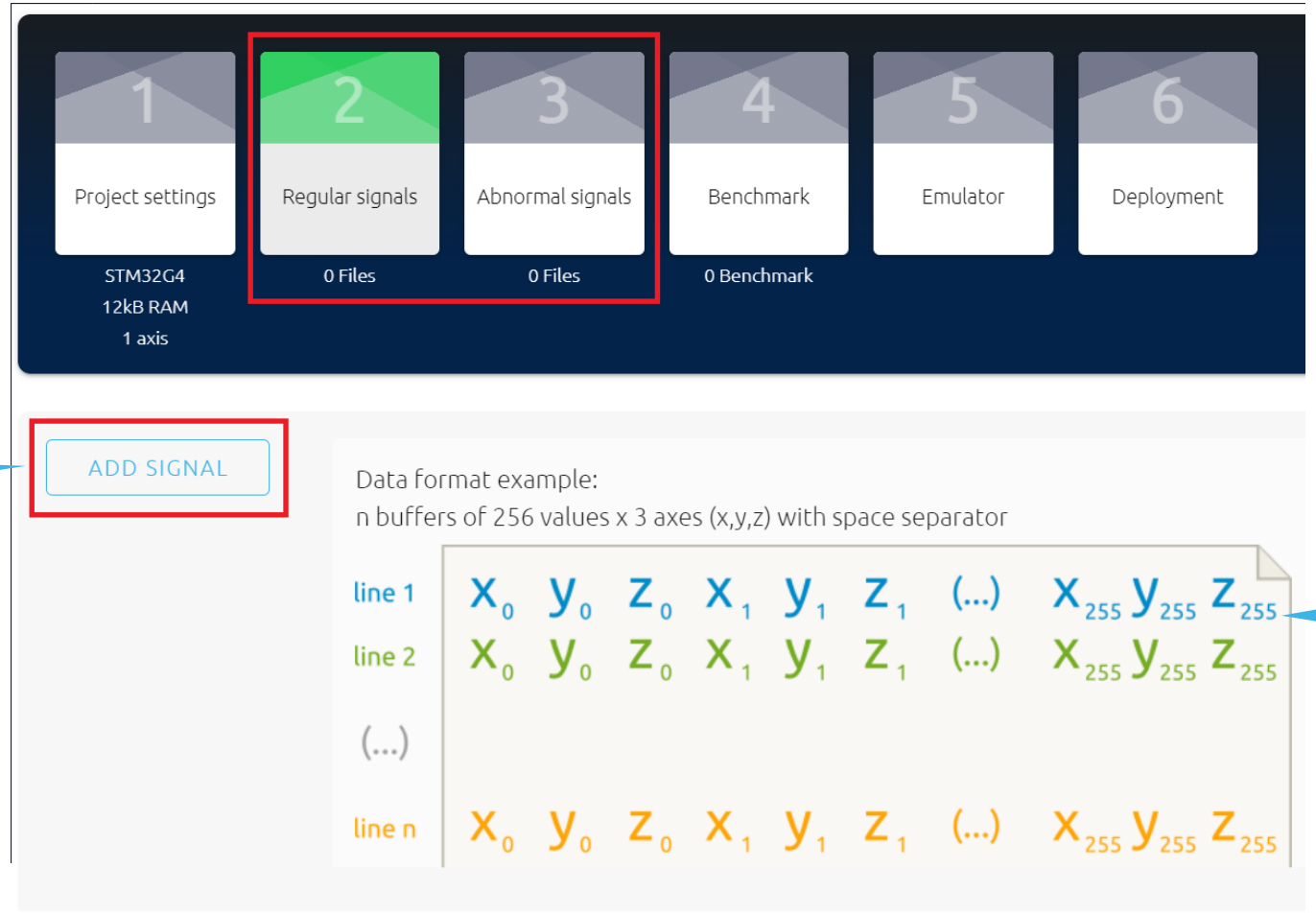
Adding signals

Adding signals for both “Regular” and “Abnormal” conditions

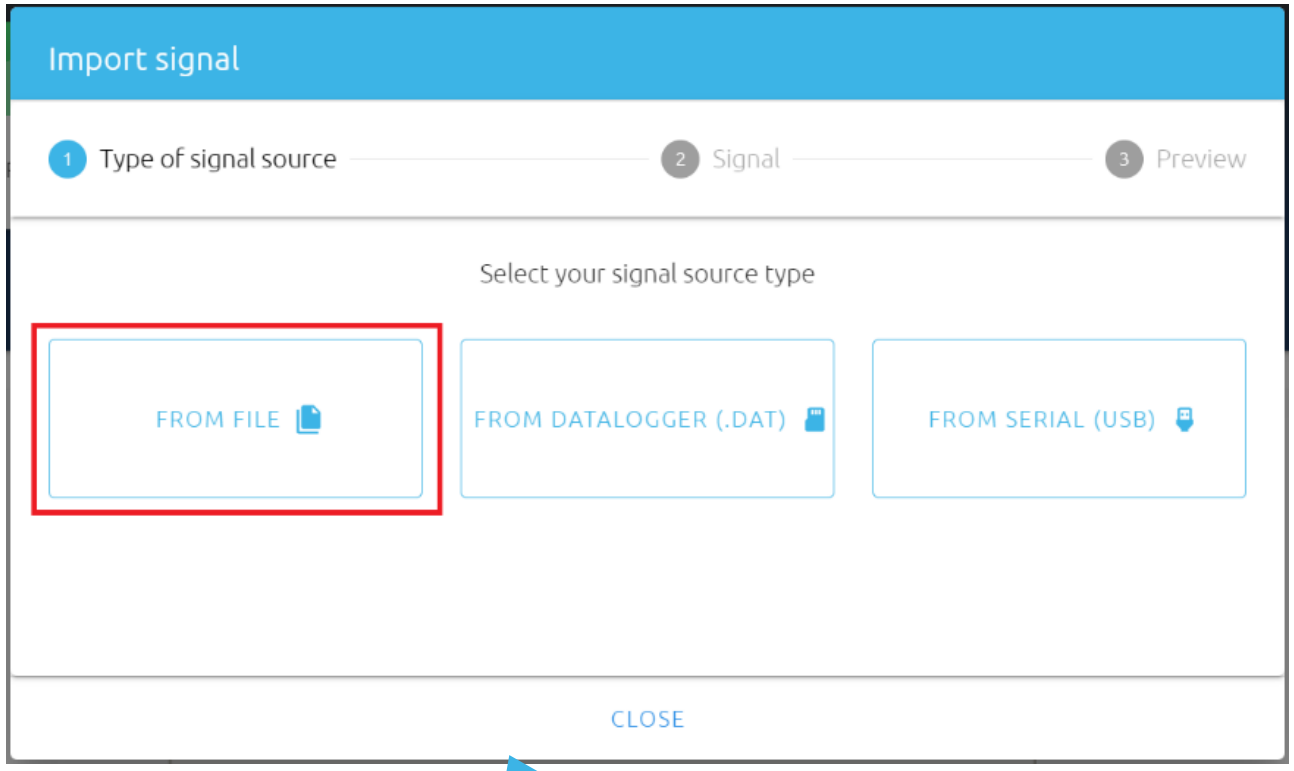


Click to add signal

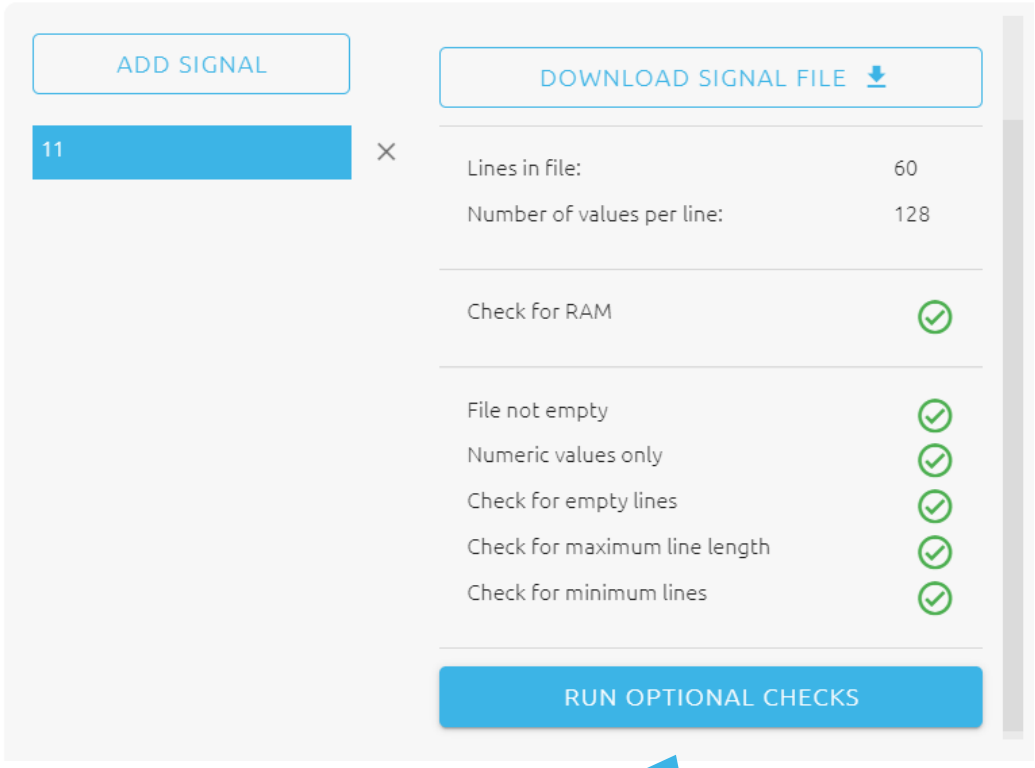
Signal format is explained here

Adding signals

3 possible types of signal sources: “From file”, “From Datalogger”, “From Serial (USB)”



Select source type



Check imported signals

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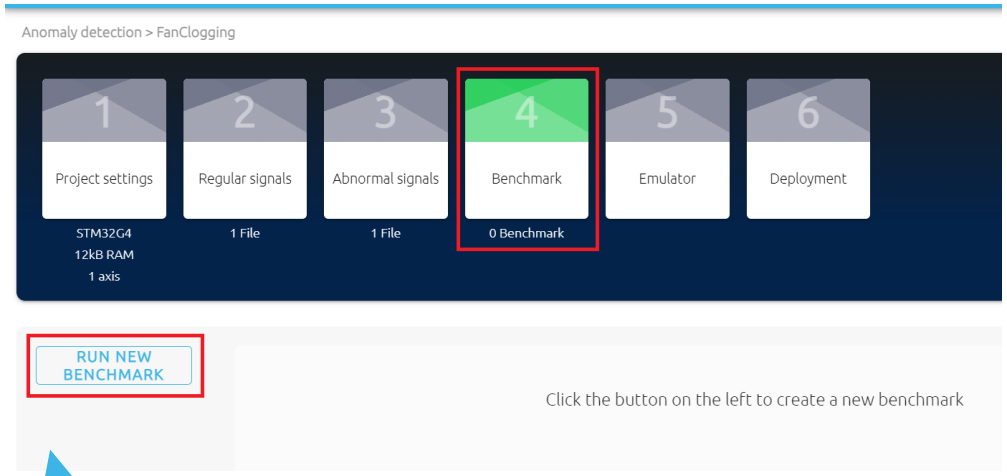
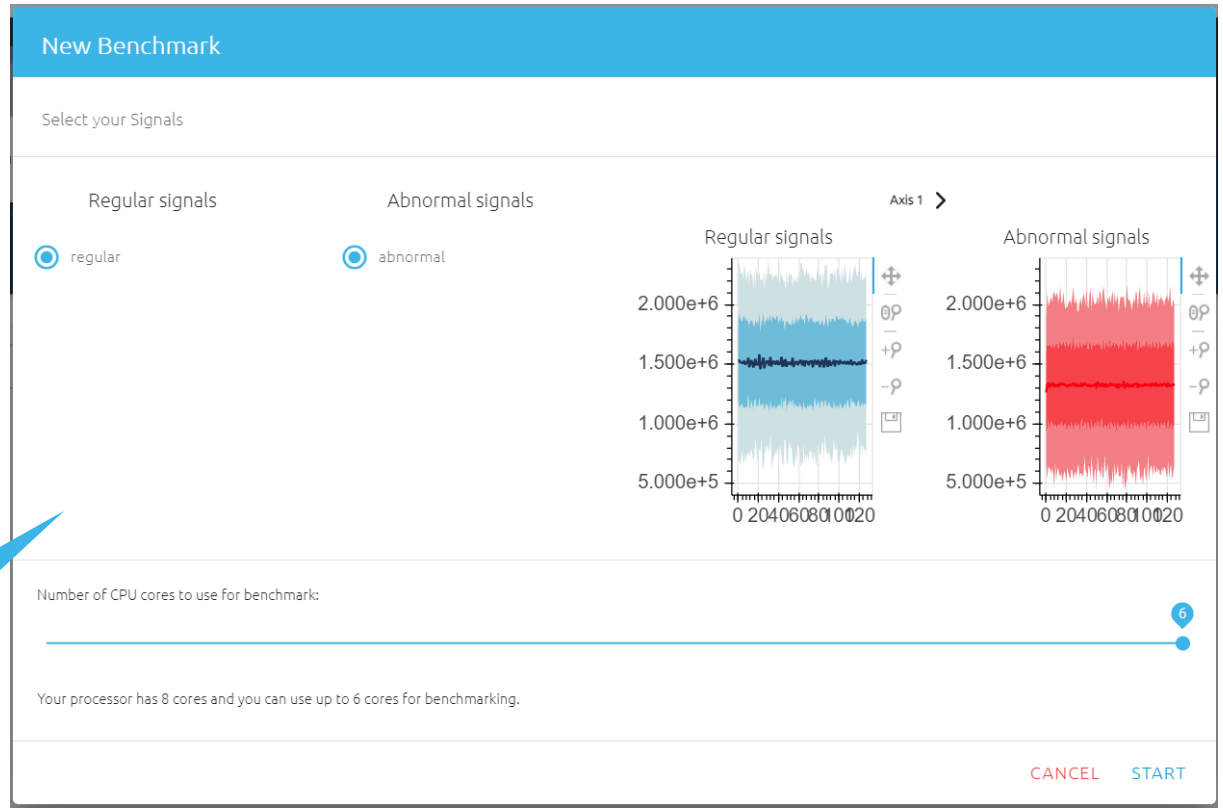
Benchmarking of NanoEdge AI Library

Run benchmark to generate an AI model which best fit the provided signals



Run new benchmark

Choose signals and number of CPU core for benchmark



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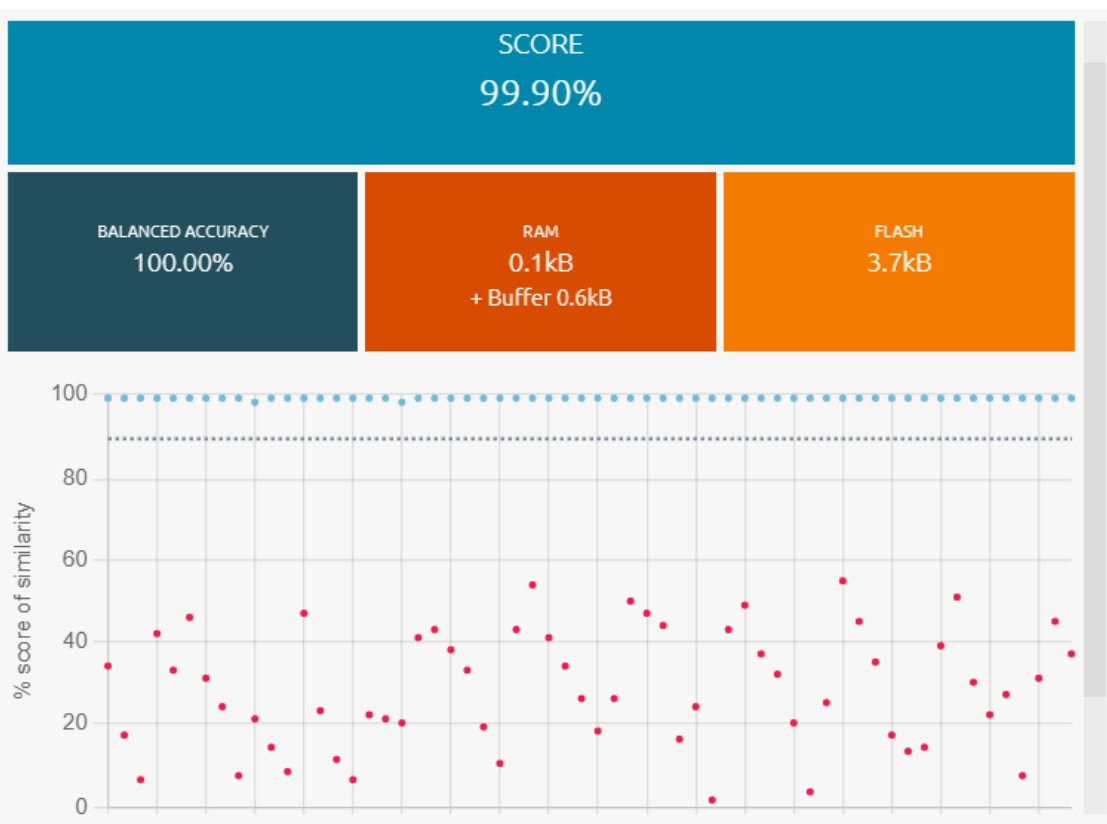
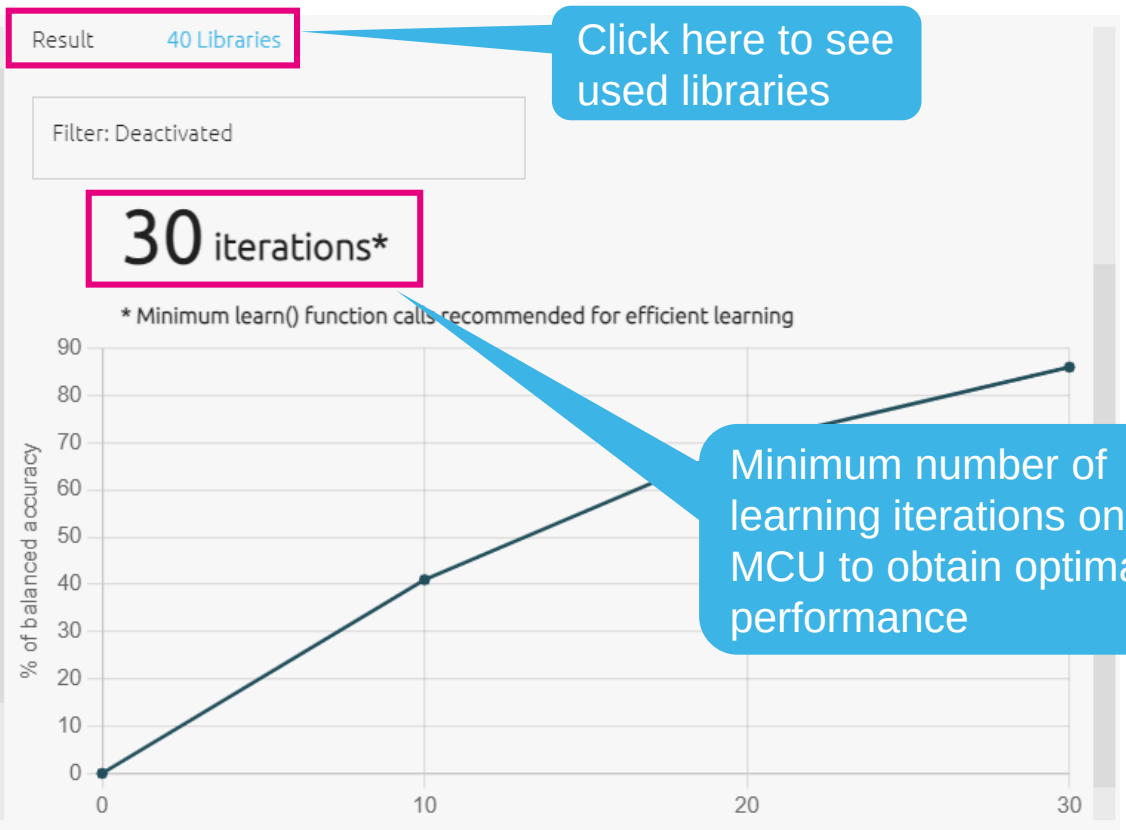
Benchmarking of NanoEdge AI Library

We can monitor different metrics of the current best model during the process of benchmark

Benchmarking of NanoEdge AI Library

After the benchmark, the recommended minimum learning iterations will appear





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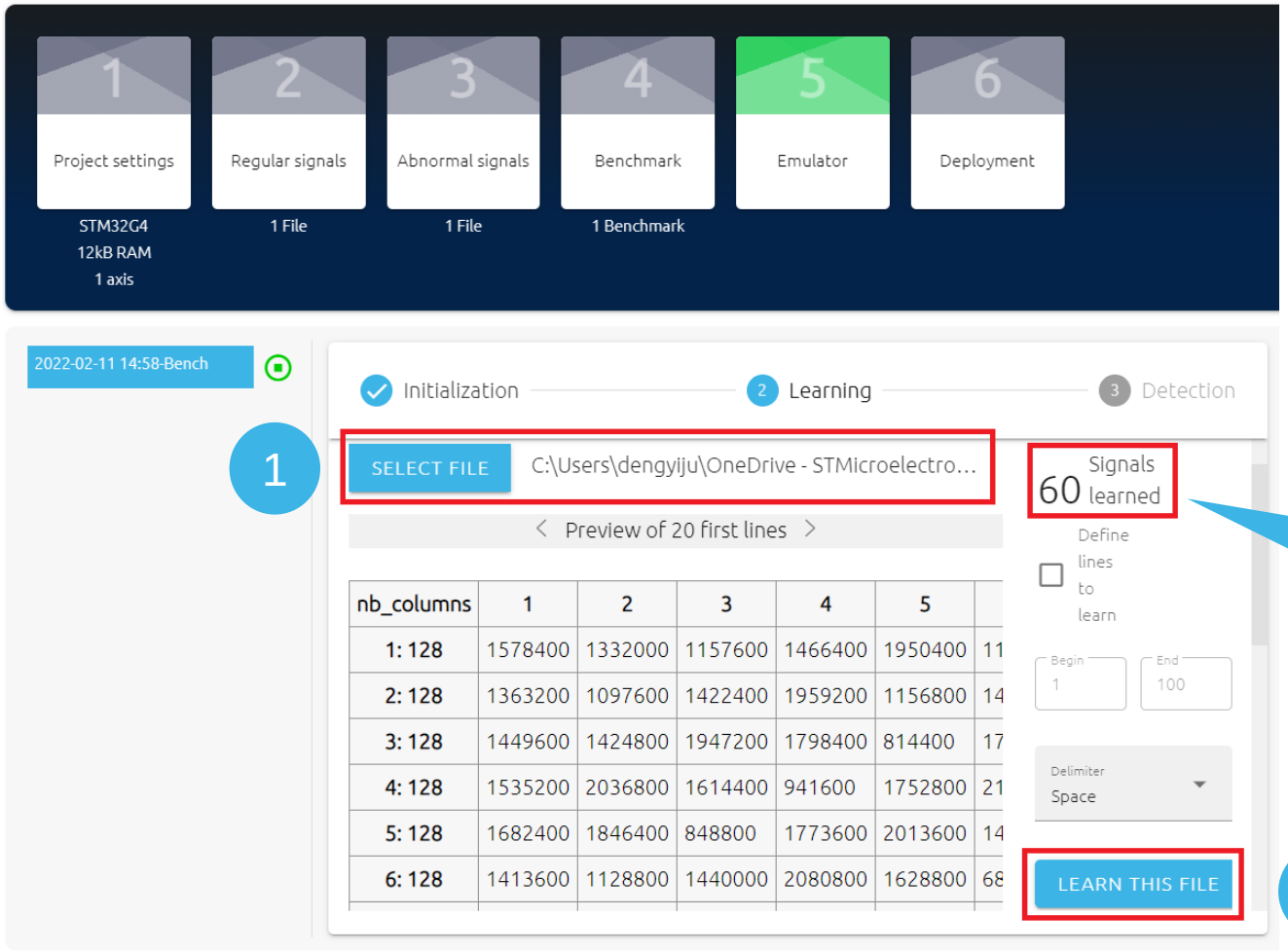
Validating the library by emulator

NanoEdge AI provides emulator to test the AI library without creating any embedded software.

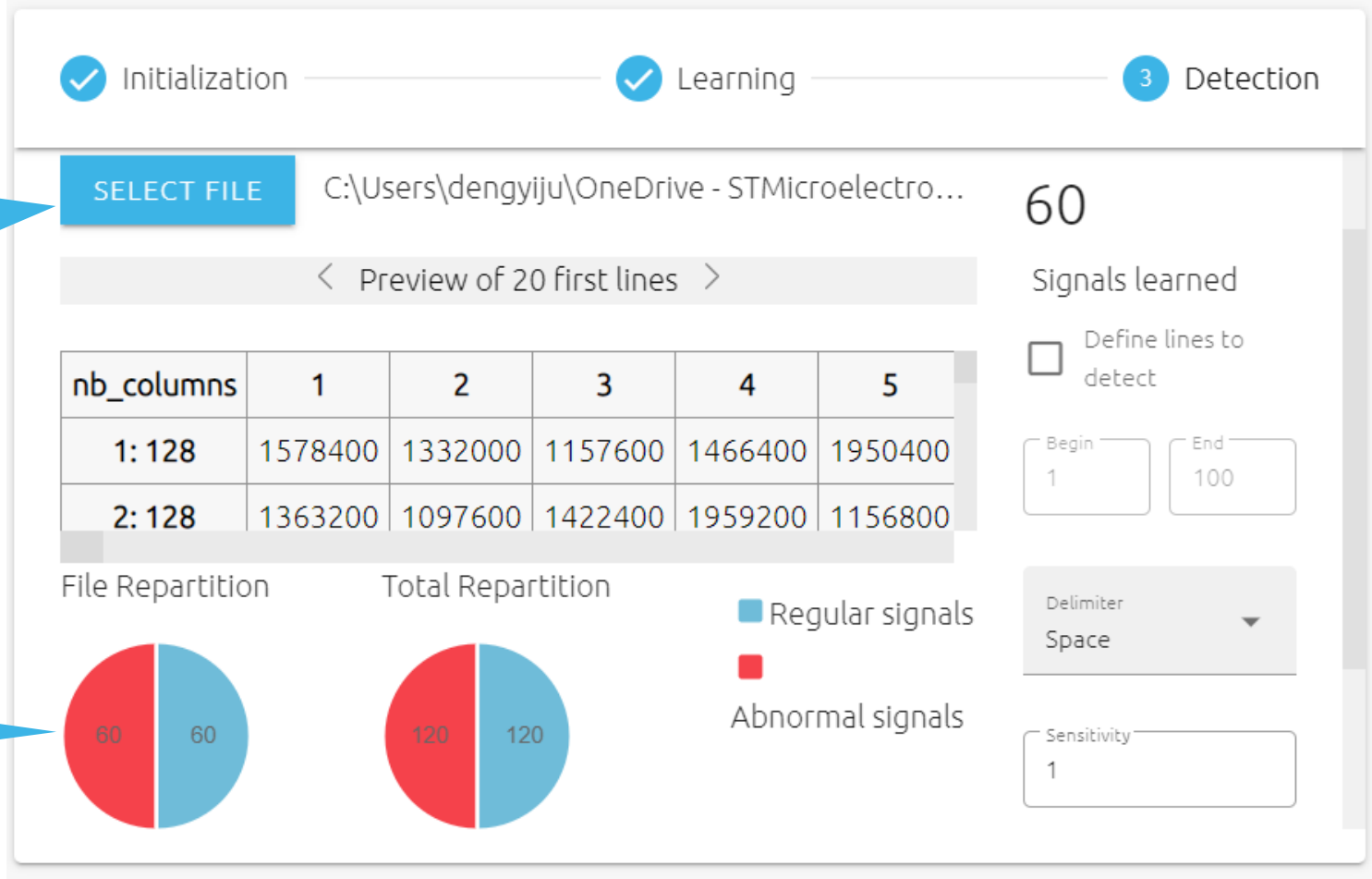


Validating the library by emulator

Go to detection after learning minimum number of normal signals

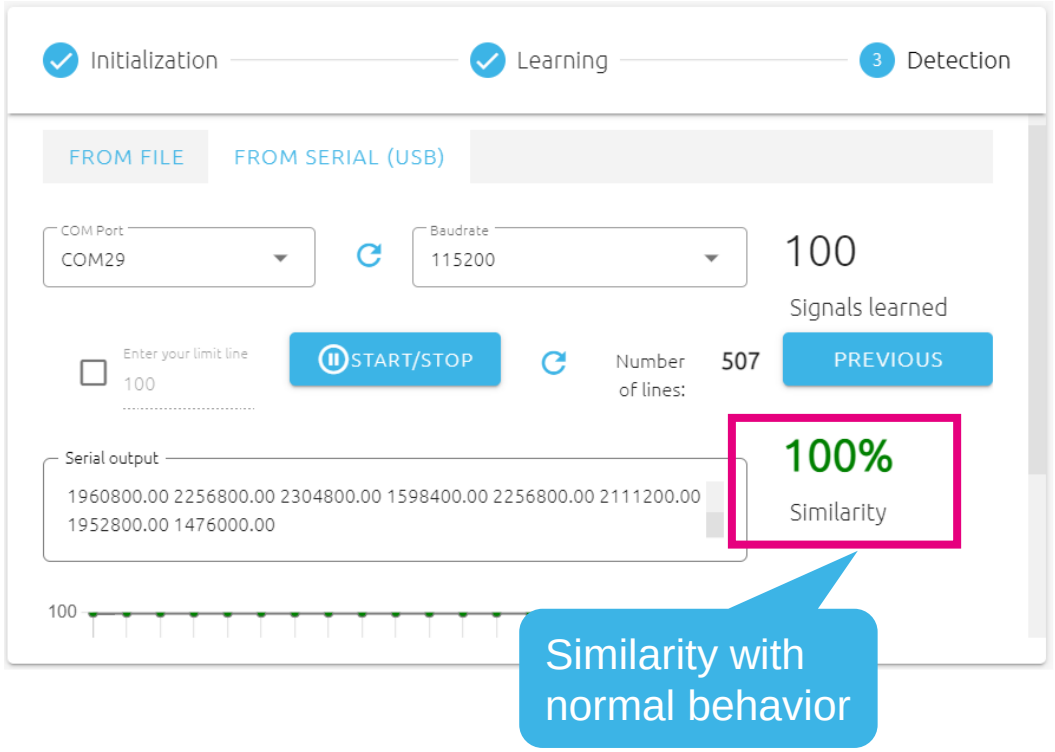
Select signal file for detection or detect in real-time from serial USB

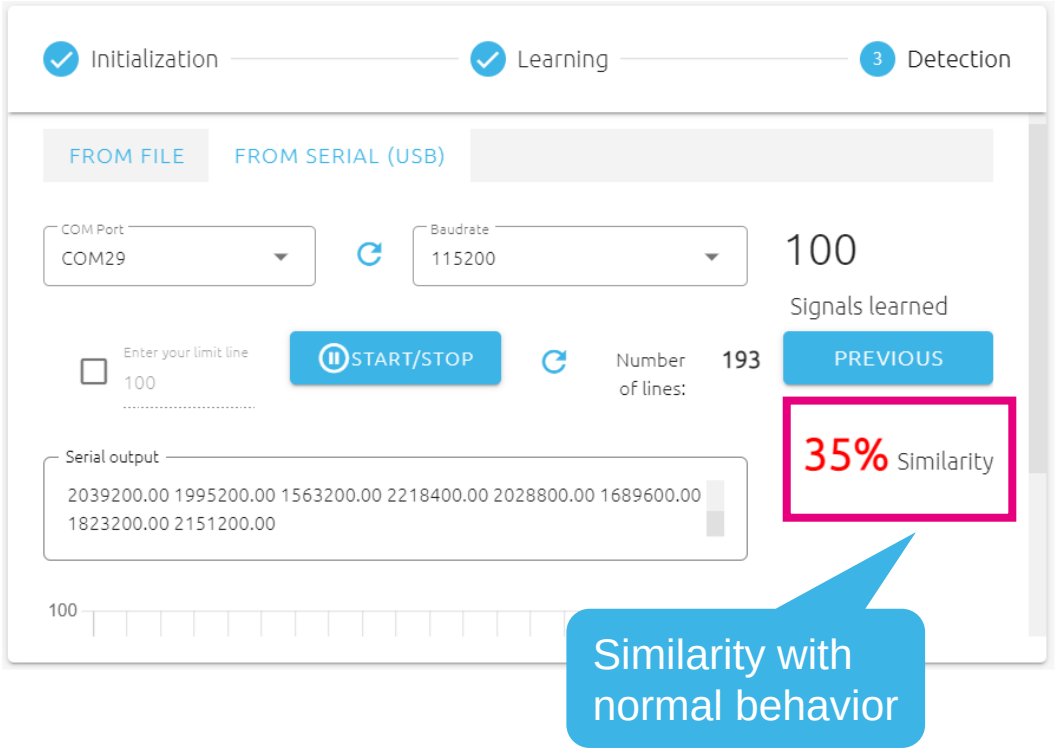
Results of detection



Validating the library by emulator

We can also test in real-time the signals received from serial USB





Similarity > threshold (e.g. 90%) => Normal
Similarity < threshold (e.g. 90%) => Abnormal

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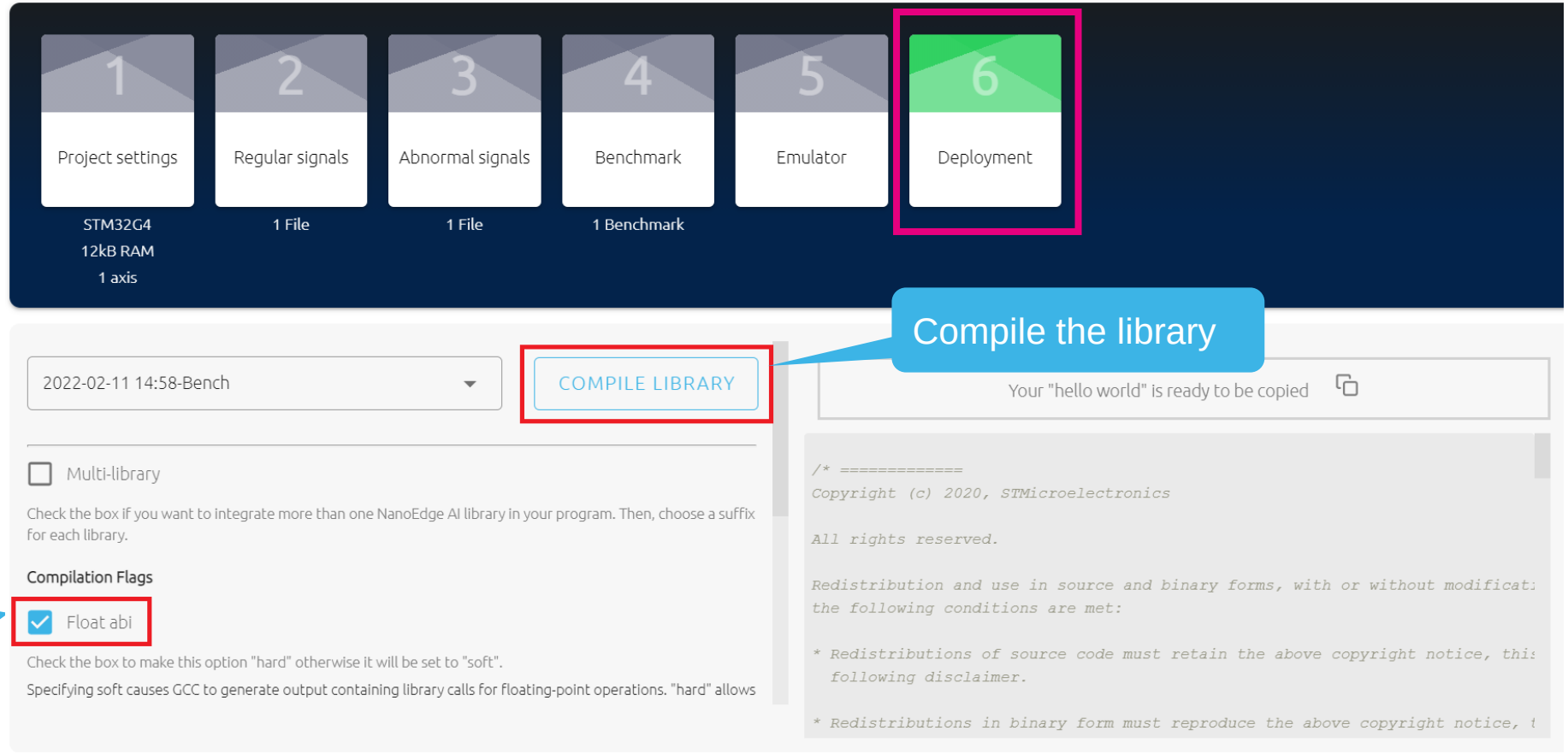
Deployment of NanoEdge AI library

After the library being validated, we can go to “Deployment” and compile the model into C library



Check the compilation option

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Integration of NanoEdge AI library

Finally, we can integrate the AI model into embedded software

Generated files after “Compile Library”

Name	Size	Packed Si...	Modified
docs	260 916	260 916	
emulators	496 616	496 616	
libneai.a	5 752	5 752	2022-0
metadata.json	2 203	2 203	2022-02-...
NanoEdgeAI.h	2 923	2 923	2022-02-...

Libneai.a: The static C library of AI model

NanoEdgeAI.h: The header file with all APIs

The APIs in NanoEdgeAI.h

```
/* Function prototypes */
#ifdef __cplusplus
extern "C" {
#endif
    enum neai_state neai_anomalydetection_init(void);
    enum neai_state neai_anomalydetection_learn(float data_input[]);
    enum neai_state neai_anomalydetection_detect(float data_input[], uint8_t *similarity);
    enum neai_state neai_anomalydetection_set_sensitivity(float sensitivity);
    float neai_anomalydetection_get_sensitivity(void);
#ifdef __cplusplus
}
#endif
```

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Integration of NanoEdge AI library

Example codes to implement an anomaly detection library generated by NanoEdge AI Studio

Initialization of the library

Learn minimum number of normal signals

Continuously detect anomaly

```
#include "NanoEdgeAI.h"

#define SIGNAL_LENGTH     128 // Signal length
#define LEARNING_NUMBER   30  // Minimum number of learning

float sample_buffer[DATA_INPUT_LENGTH];
uint8_t similarity;

/* Initialize NanoEdge AI library */
neai_anomalydetection_init();

/* Learn 30 nominal signals */
for (int i = 0; i < LEARNING_NUMBER; i ++) {
    // Get one sample and fill in the buffer
    fill_buffer(sample_buffer);
    // Learn the sample
    neai_anomalydetection_learn(sample_buffer);
}

/* Detection phase */
while (1) {
    // Get one sample and fill in the buffer
    fill_buffer(sample_buffer);
    // Detect the sample
    neai_anomalydetection_detect(sample_buffer, &similarity);
    // Output result
    if (similarity > 0.9) {
        printf("The motor is in normal state!\n");
    }
    else {
        printf("The motor is in abnormal state!\n");
    }
}
```

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Q&A

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Our technology starts with You

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