

arm

Introducing Physical Computing and Project Based Learning

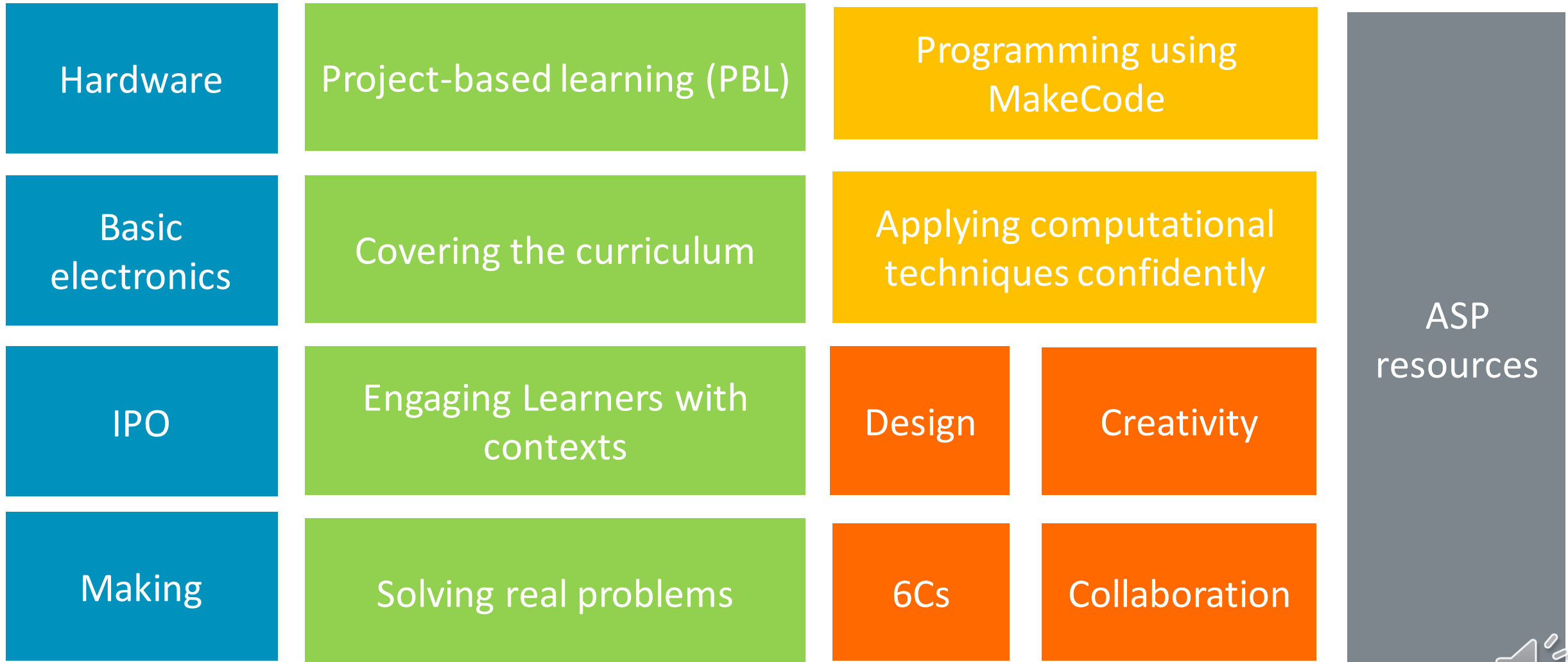
Theory and practice

Arm School Program

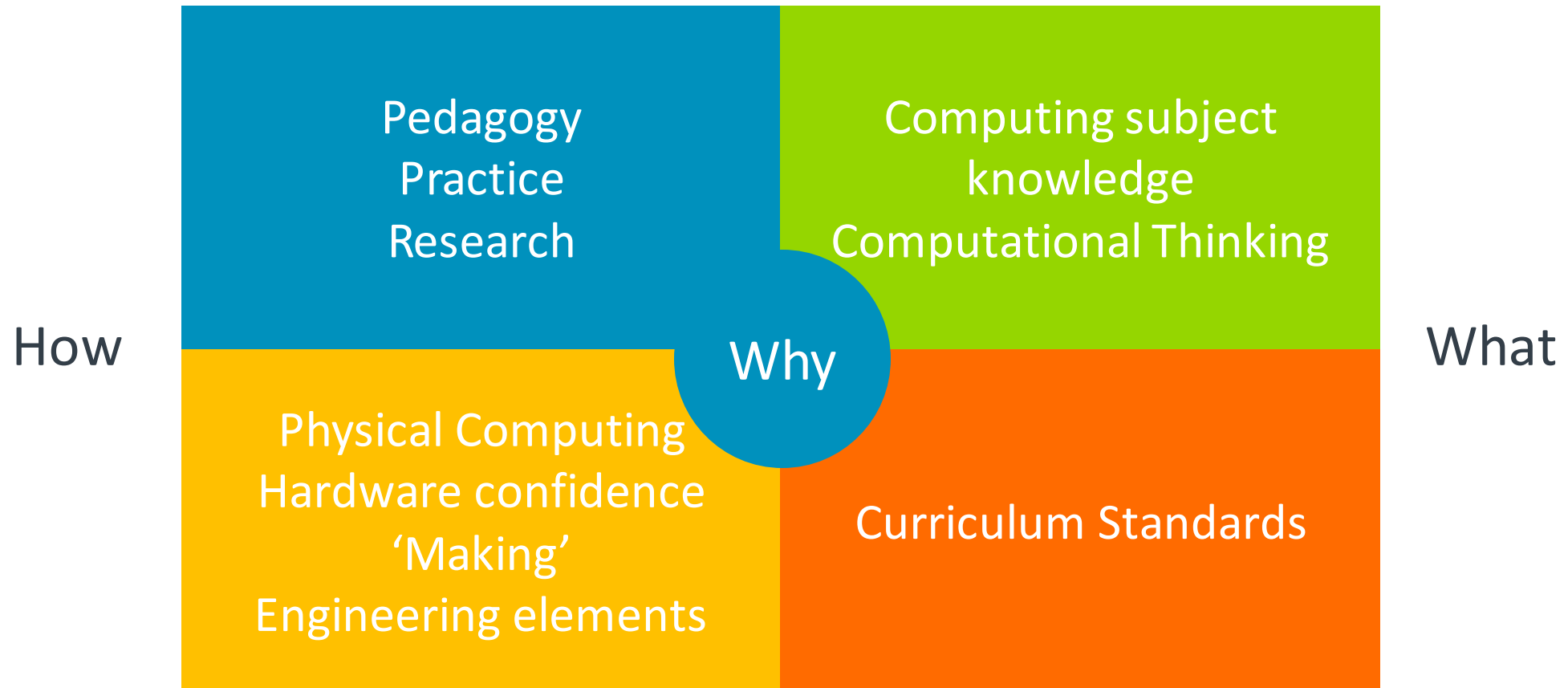
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The ASP approach to PBL/PC



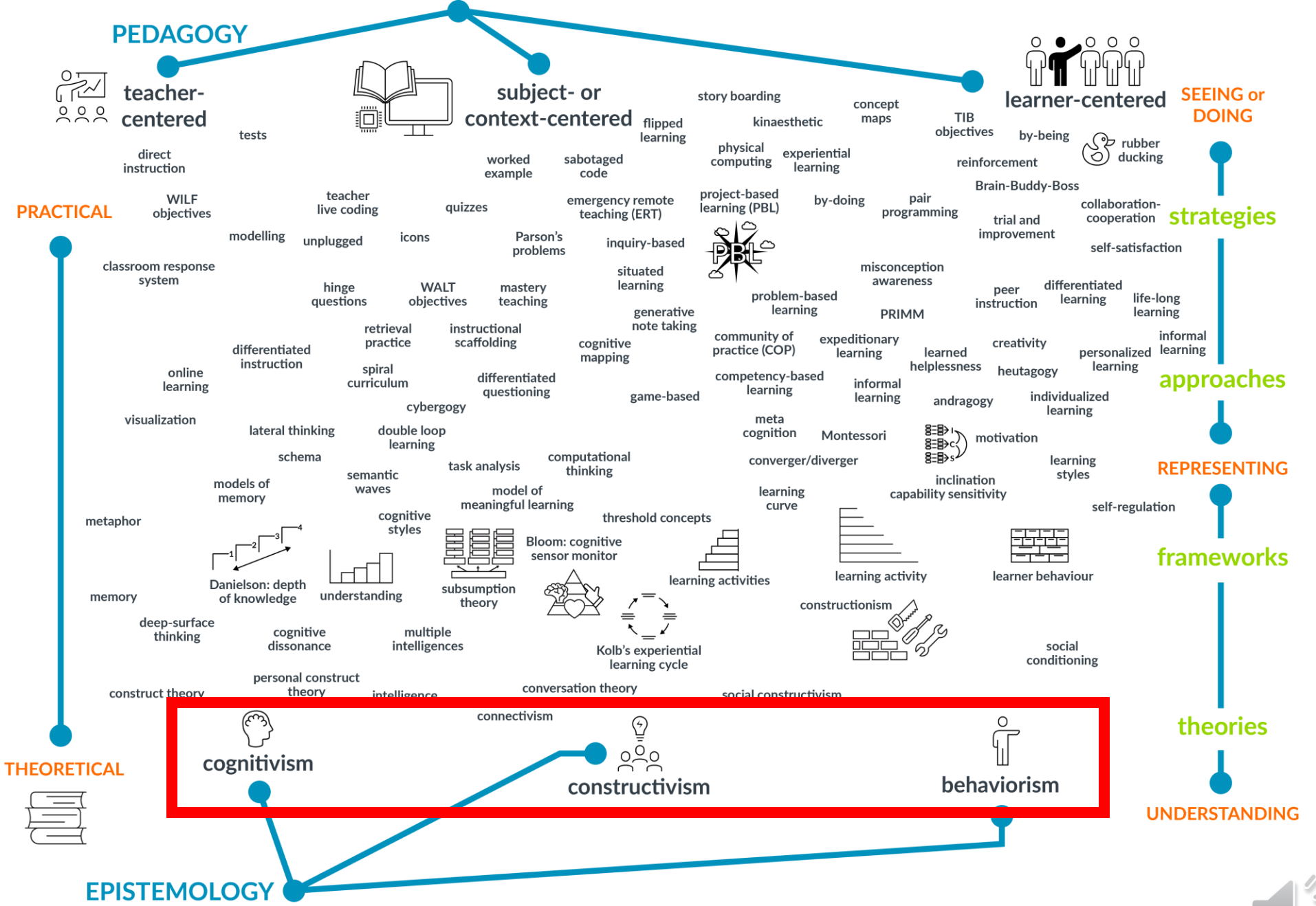
Pedagogical Content Knowledge (PCK)



arm

Theory and pedagogy



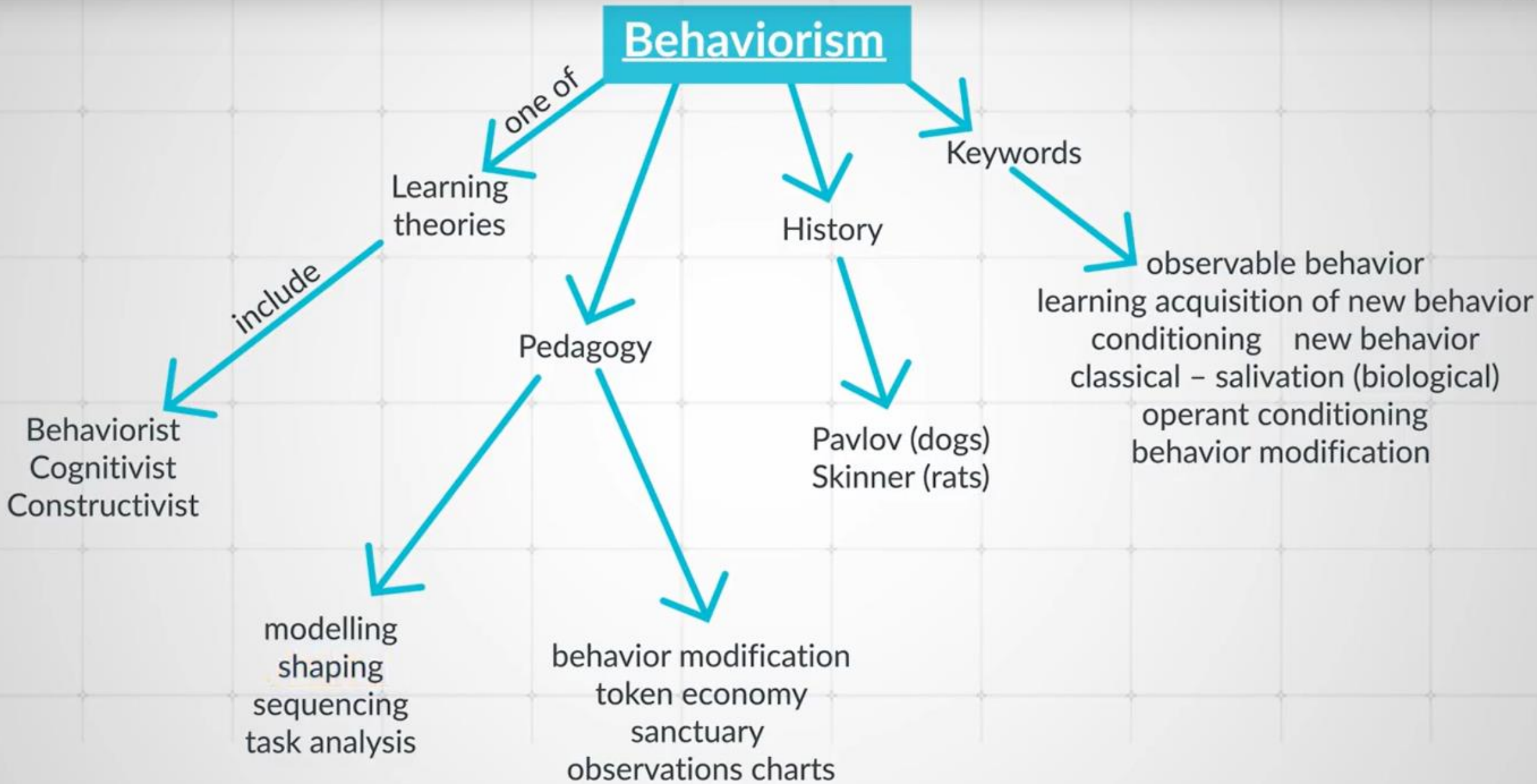


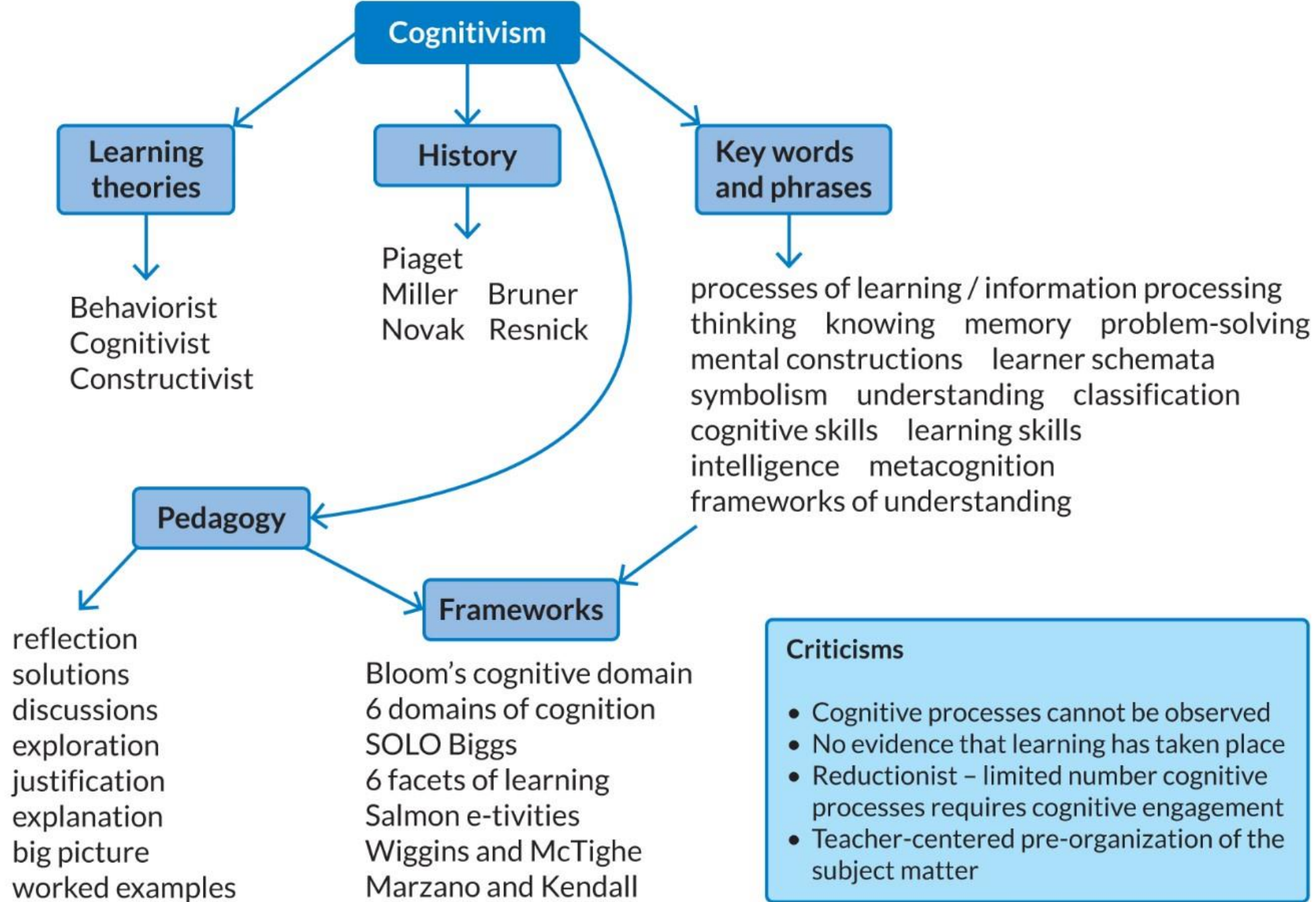


How

What

Changes





- Criticisms**
- Cognitive processes cannot be observed
 - No evidence that learning has taken place
 - Reductionist – limited number cognitive processes requires cognitive engagement
 - Teacher-centered pre-organization of the subject matter



Higher Order Thinking Skills



Evaluation

Make and defend judgments based on internal evidence or external criteria.

appraise
argue assess attach
choose compare conclude
contrast defend describe discriminate
estimate evaluate explain judge justify interpret
relate predict rate select summarize support value

Synthesis

Compile component ideas into a new whole or propose alternative solutions.

arrange assemble categorize collect combine comply
compose construct create design develop devise explain
formulate generate plan prepare rearrange reconstruct relate
reorganize revise rewrite set up summarize synthesize tell write

Analysis

Break down objects or ideas into simpler parts and find evidence to support generalizations.

analyze appraise breakdown calculate categorize compare
contrast criticize diagram differentiate discriminate distinguish
examine experiment identify illustrate infer model outline
point out question relate select separate subdivide test

Application

Apply knowledge to actual situations.

apply change choose compute demonstrate discover
dramatize employ illustrate interpret manipulate
modify operate practice predict prepare produce
relate schedule show sketch solve use write

Comprehension

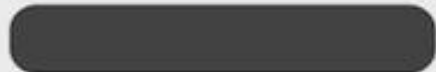
Demonstrate an understanding of the facts.

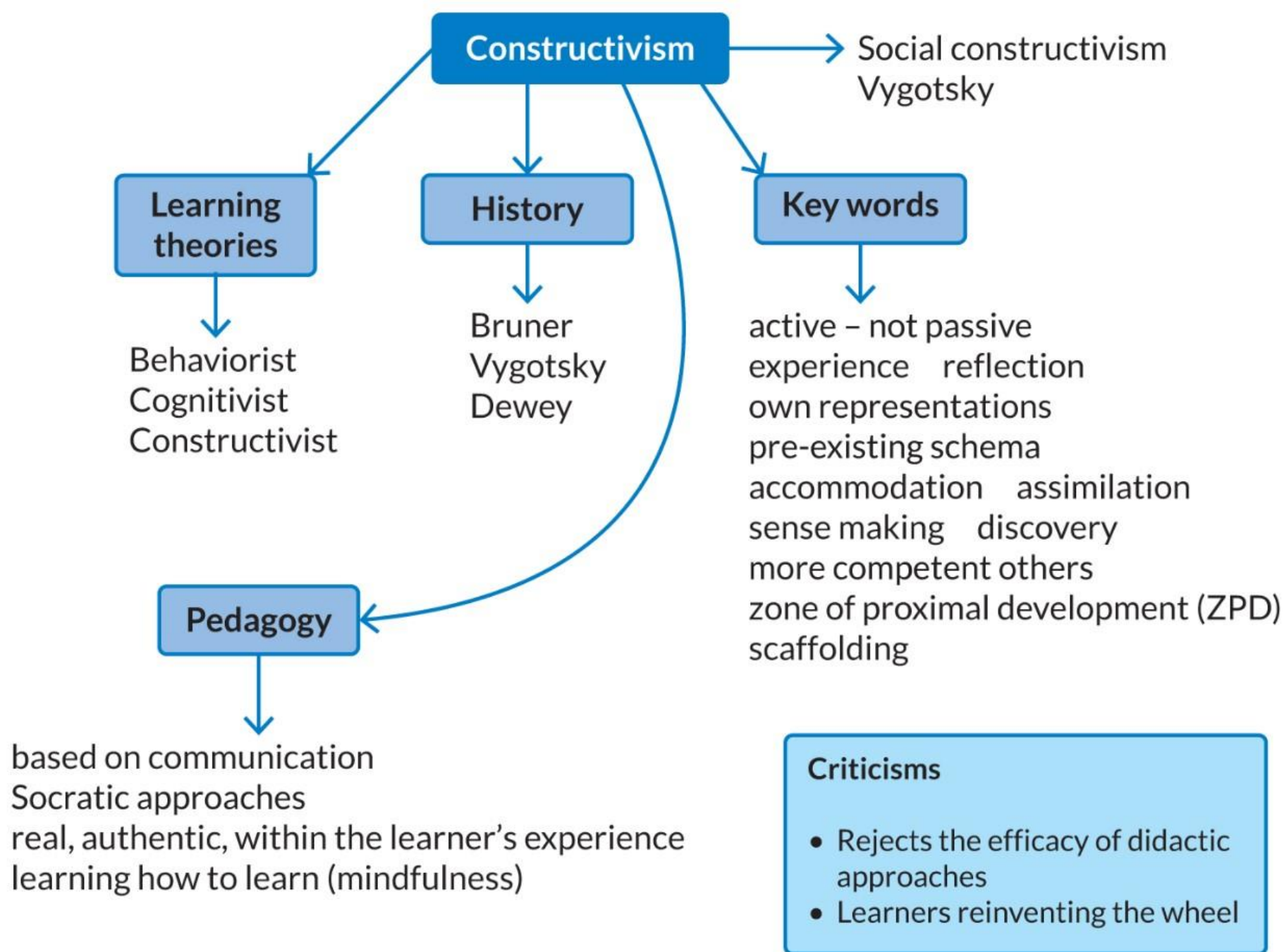
classify convert defend describe discuss
distinguish estimate explain express
extend generalized give example(s)
identify indicate infer locate paraphrase
predict recognize rewrite review select
summarize translate

Knowledge

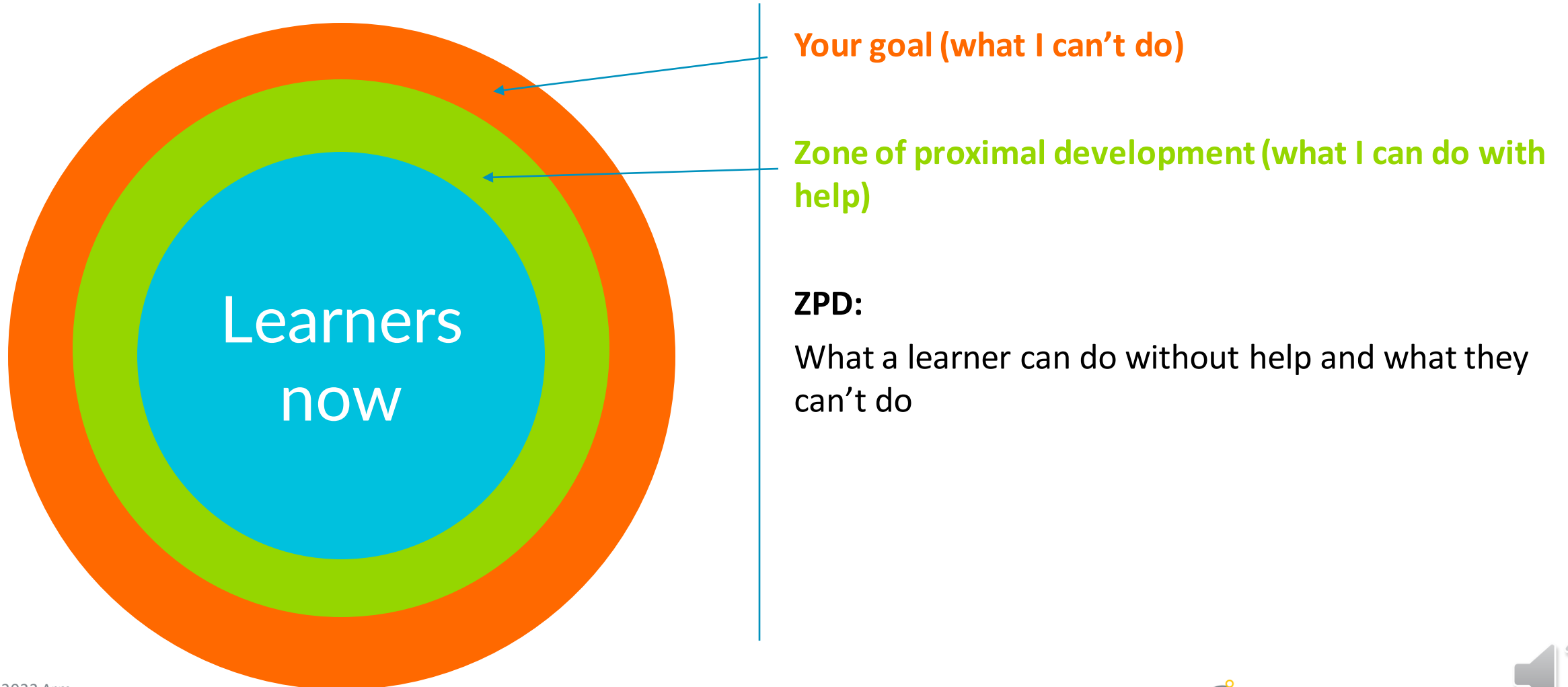
Remember previously learned information.

arrange define describe duplicate
identify label list match memorize
name order outline recognize
relate recall repeat reproduce
select state





Zones of proximal development (ZPD)

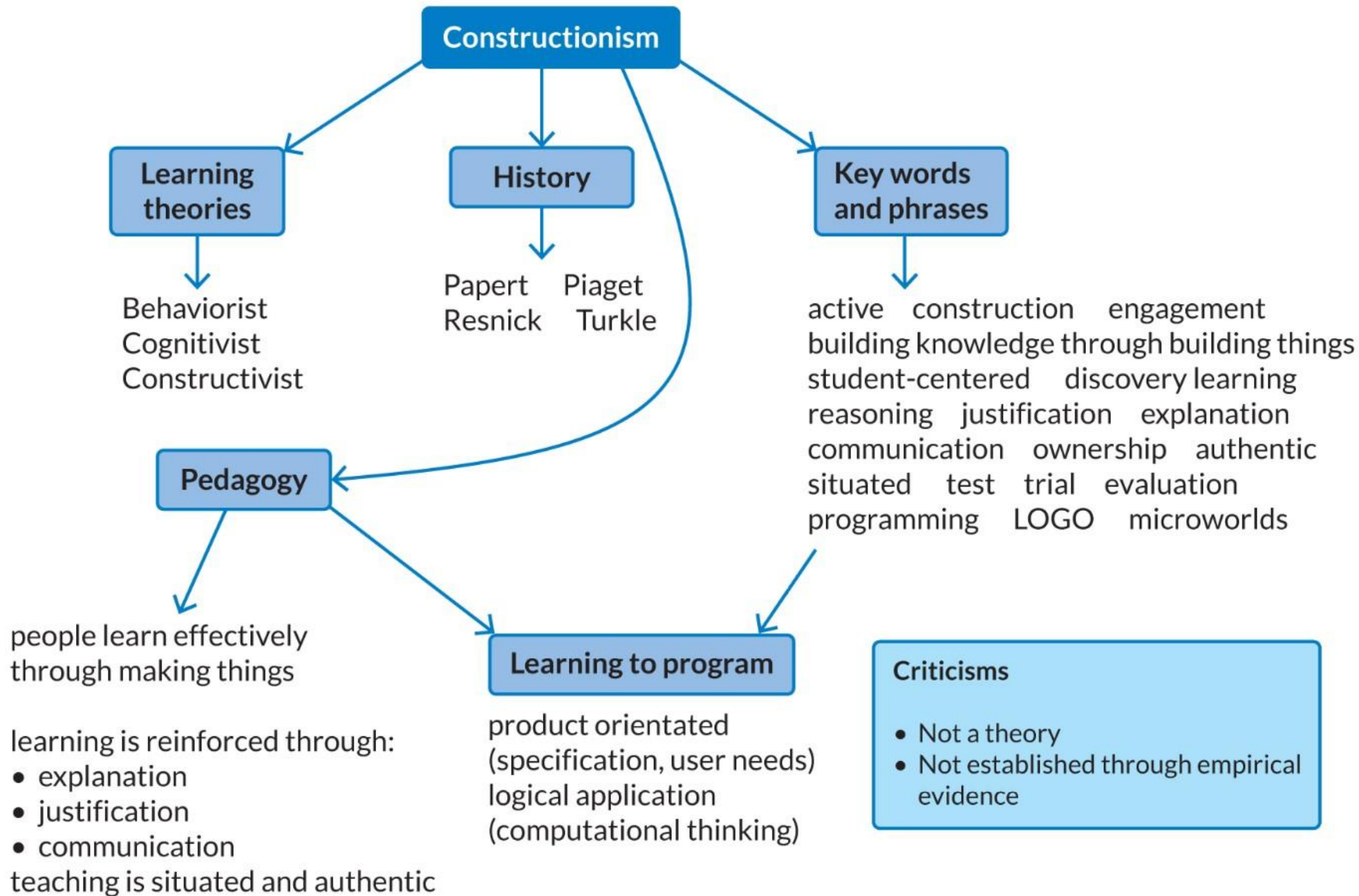


Your goal (what I can't do)

Zone of proximal development (what I can do with help)

ZPD:

What a learner can do without help and what they can't do



PBL is not just Constructionism!

Key concepts:

- A reaction to didactic teaching approaches
- Learning as contextualised action (practical in nature)
- “Learning by doing” (historically referred to as kinaesthetic)

Limitations:

- Assumption that only exploration yields learning
- Not all learners will discover the intended learning
- Assumes a deep desire for learning and unlimited engagement

Why making matters – thinking in systems

‘Engineers use a unique mode of thinking based on seeing everything as a system. They see structures that aren’t apparent to the layperson, they know how to design under constraints, and they understand trade-offs. Adopting an engineering mindset can help you in any field.’

Engineering mindset:

- The ability to see a structure where there’s nothing apparent
- Designing under constraints
- Understanding trade-offs

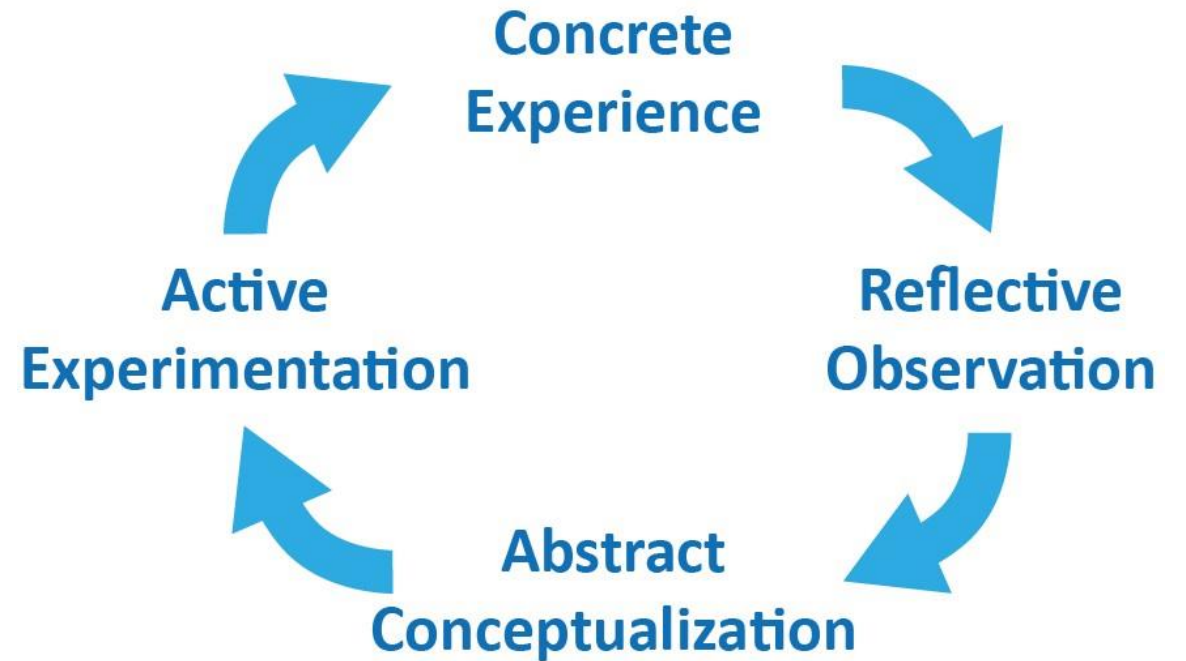


Engagement

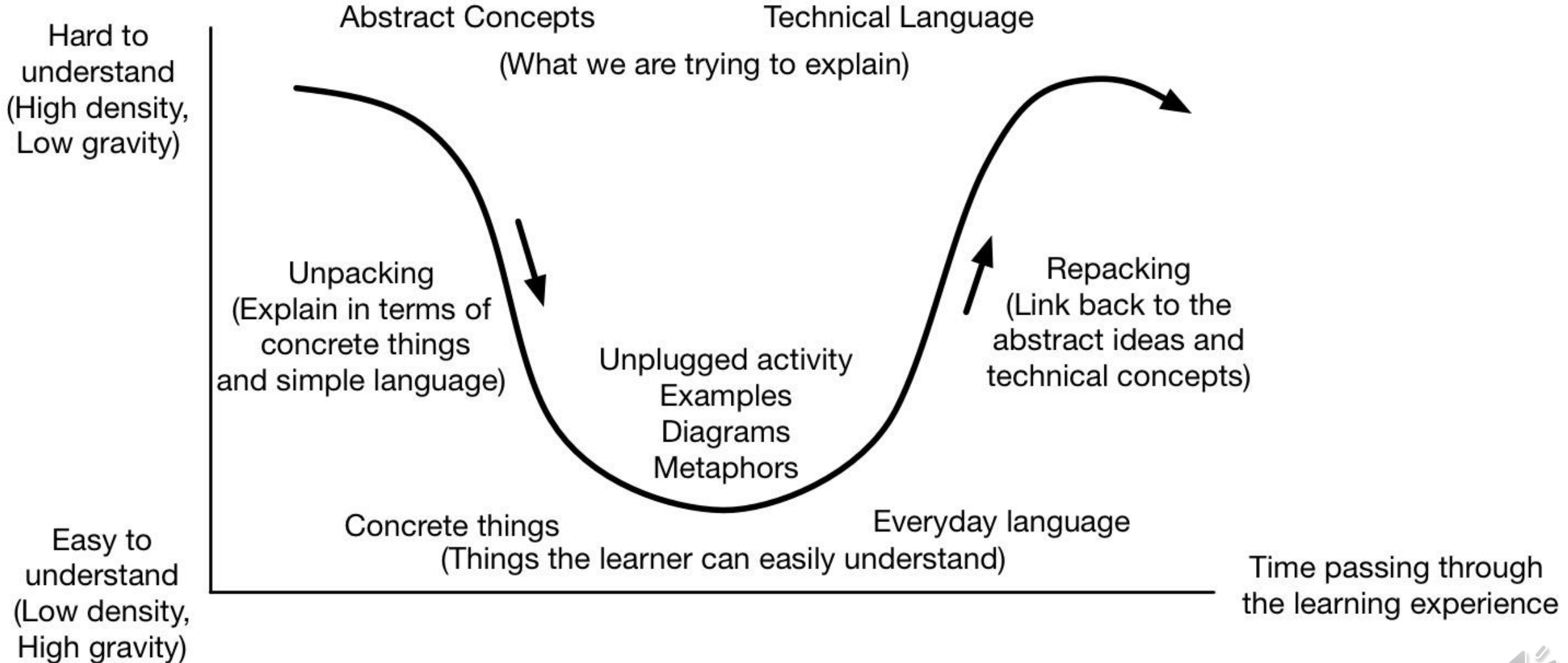


Kolb's learning theory (1984)

- + **Concrete Experience** - a new experience or situation is encountered, or a reinterpretation of existing experience.
- + **Reflective Observation of the New Experience** - of particular importance are any inconsistencies between experience and understanding.
- + **Abstract Conceptualization** - reflection gives rise to a new idea, or a modification of an existing abstract concept (the person has learned from their experience).
- + **Active Experimentation** - the learner applies their idea(s) to the world around them to see what happens.



Semantic waves

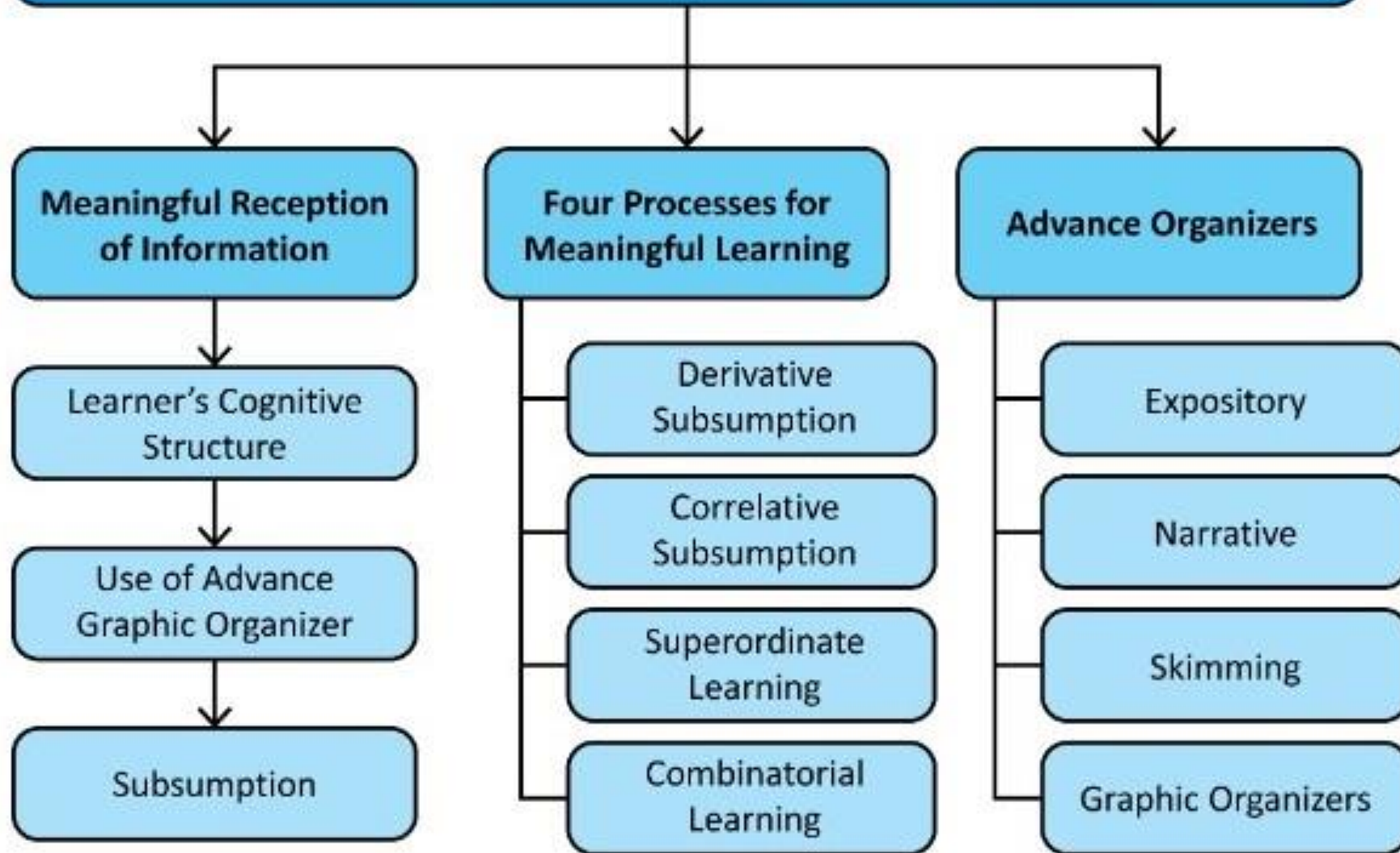


PRIMM for programming

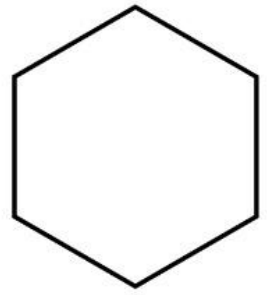
- **Predict**
- **Run**
- **Investigate**
- **Modify**
- **Make**

- + What will the code do? CT tasks
- + Low bar to entry – fundamentals
- + Scaffolded tasks on code/blocks
- + ‘Partly mine’ meeting a criteria
- + Applying it in anger

Ausubel's Subsumption Theory



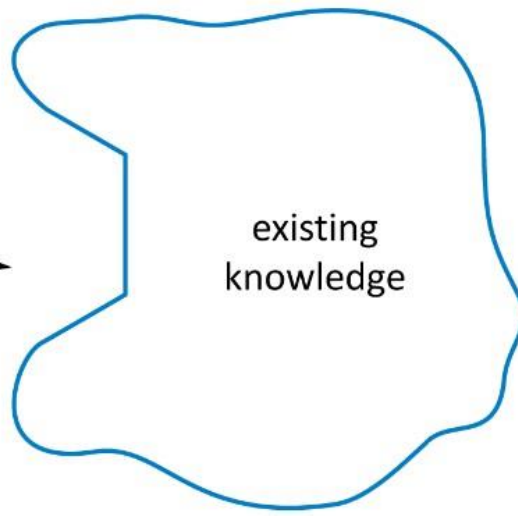
Constructivism



act of learning

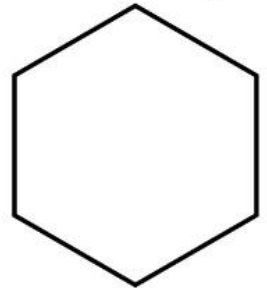


new knowledge to be learned

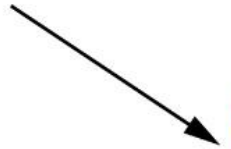


existing knowledge

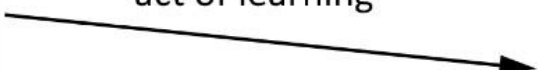
Scaffolding



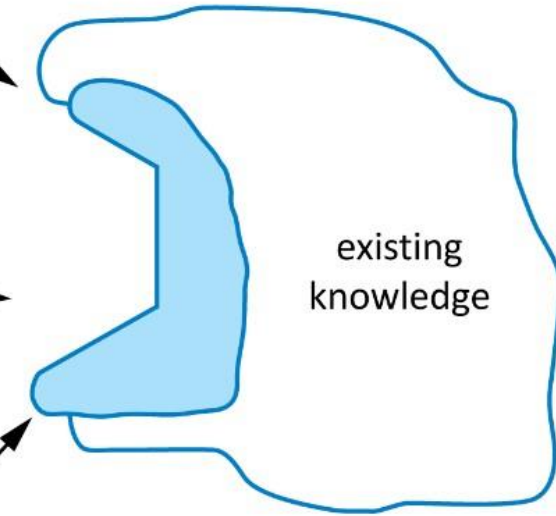
act of teaching



act of learning



new knowledge to be learned

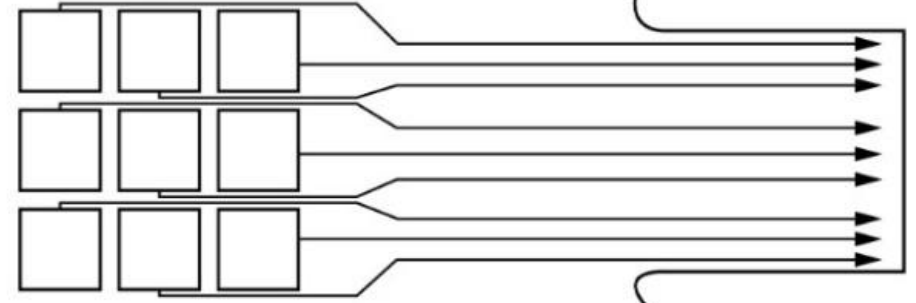


existing knowledge

scaffolding

knowledge that connects with the existing but can accommodate the new

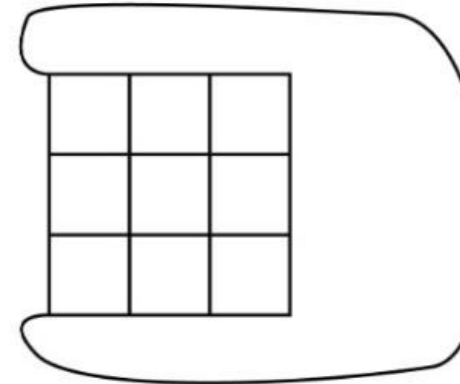
subsumption



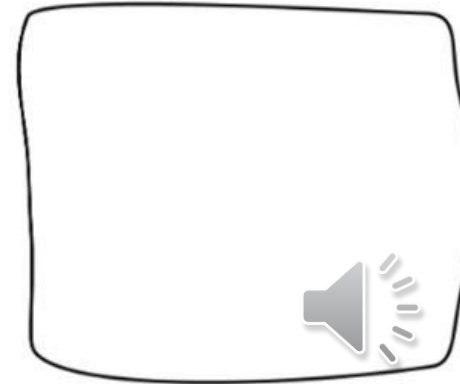
new knowledge to be learned

existing knowledge

constructivism



subsumption



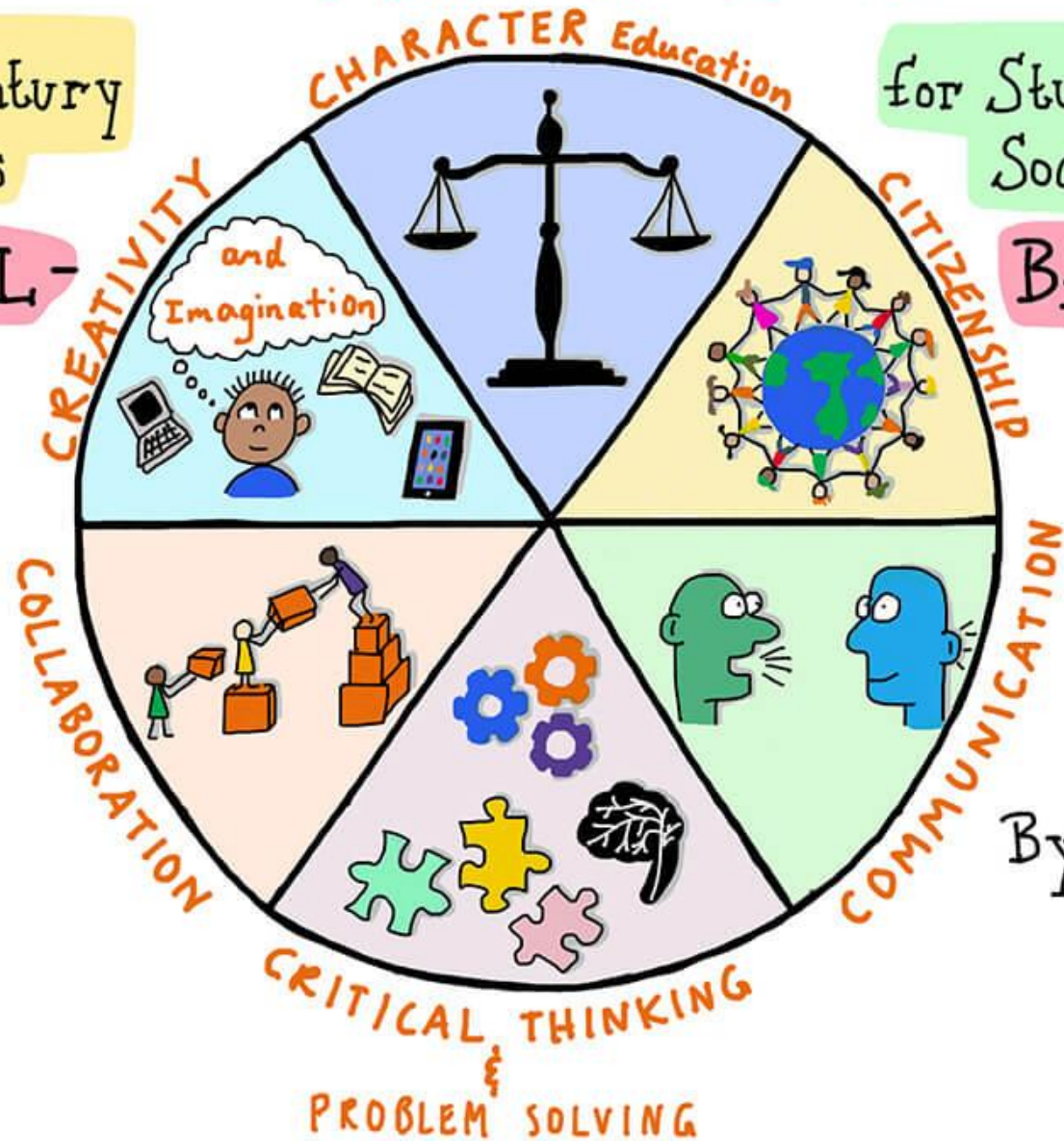
THE 6 C'S of Education

21st Century skills

for Student and Society

WELL-

BEING



By Michael Fullan

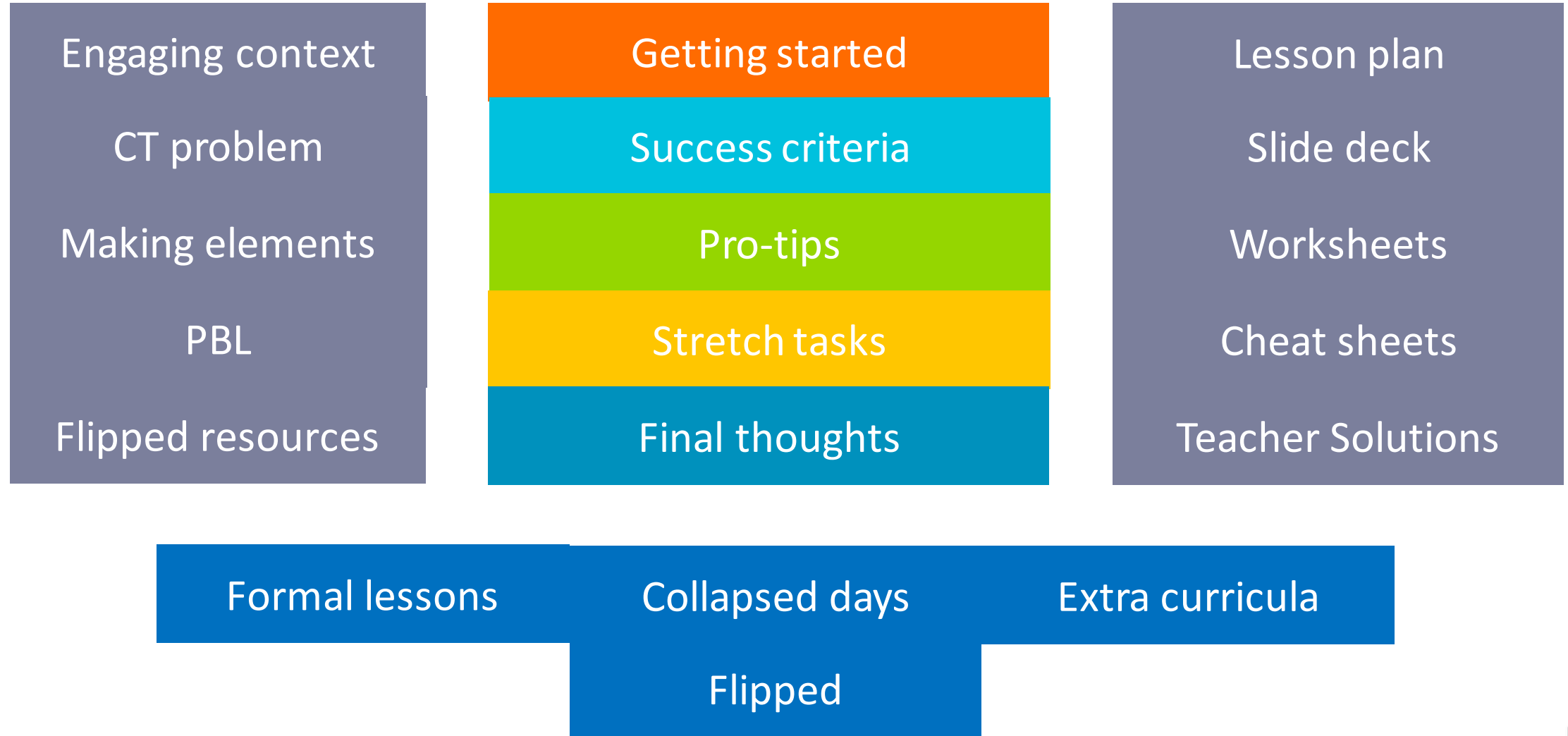
@sylvia duckworth

arm

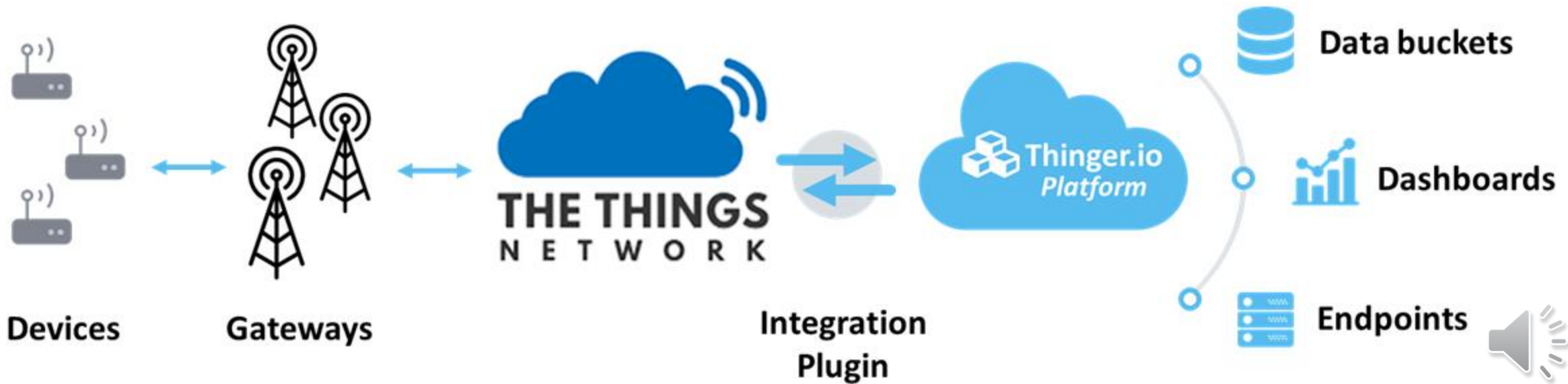
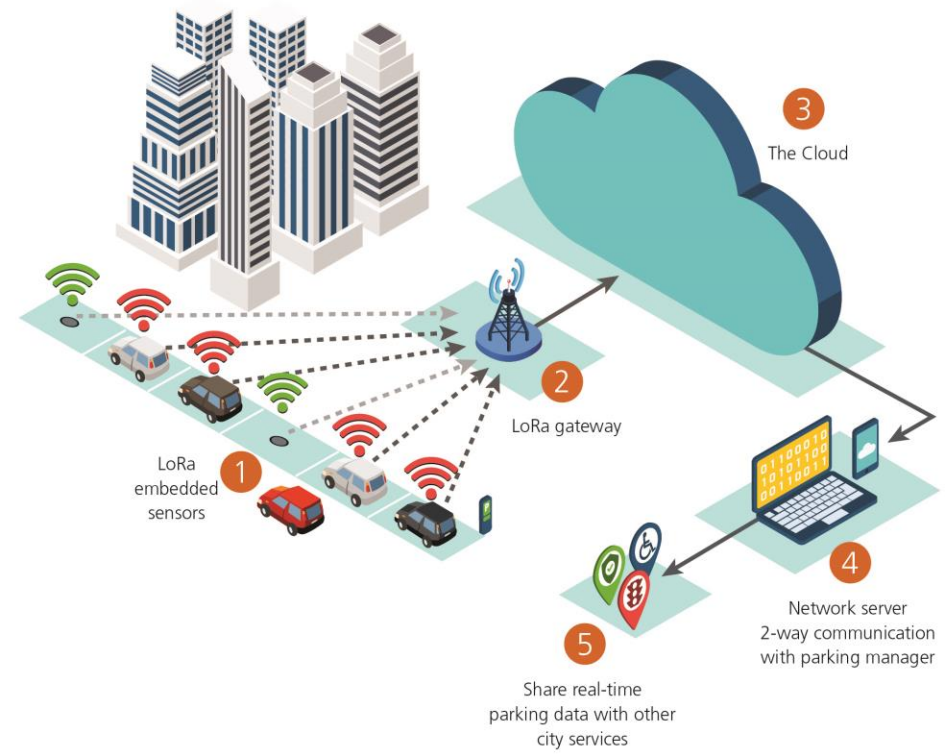
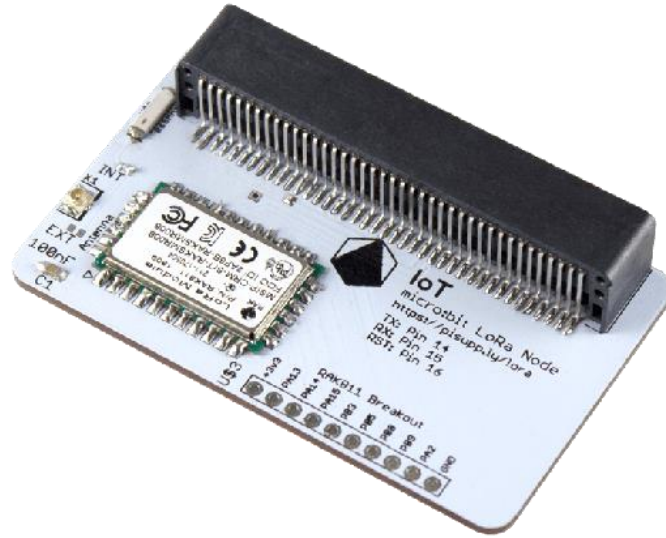
Practice and pedagogy

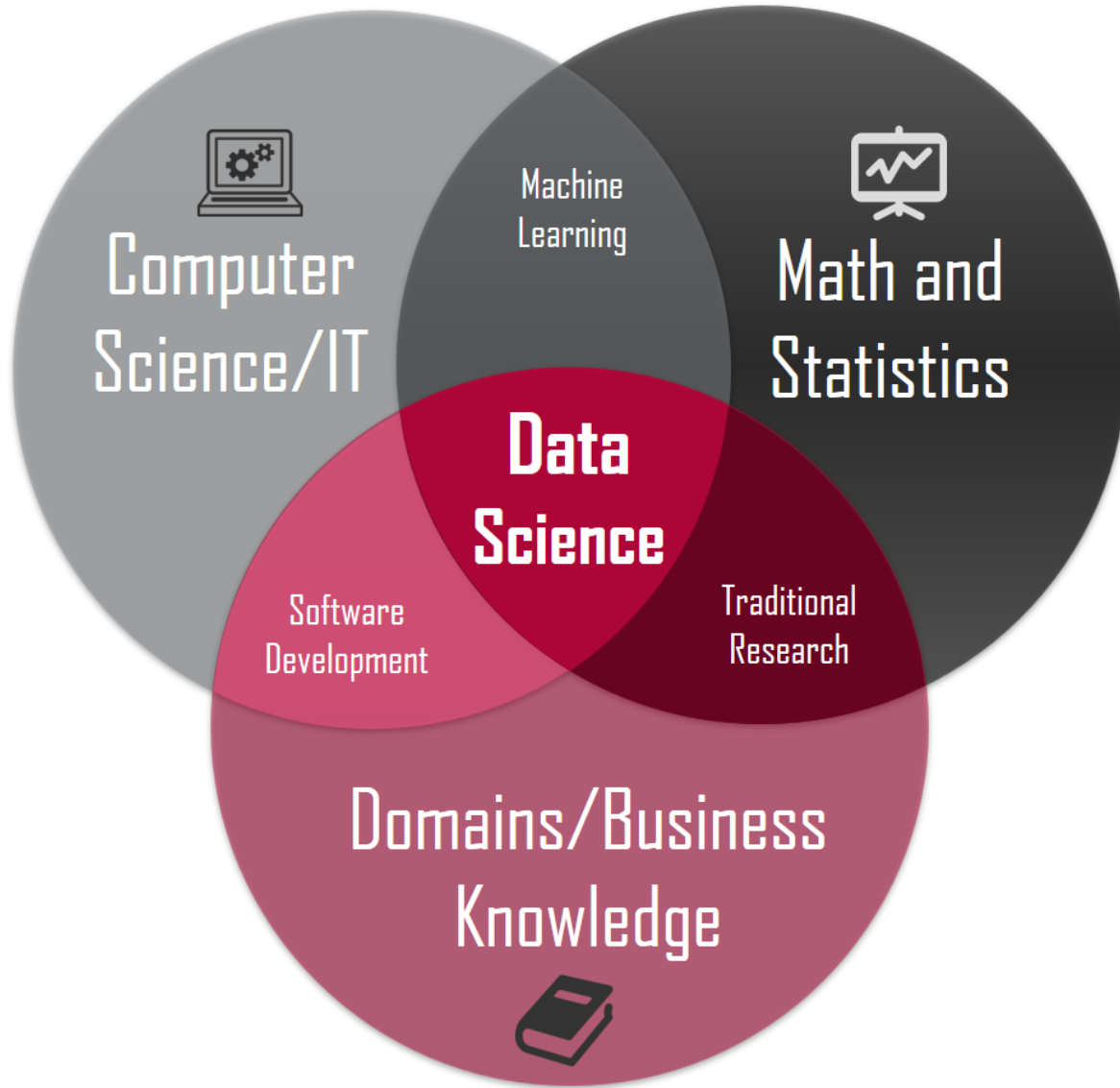


The ASP Schema



LoRaWAN®





Data Science

- The next tech wave
- A new subject?
- Where would it live in the curriculum?

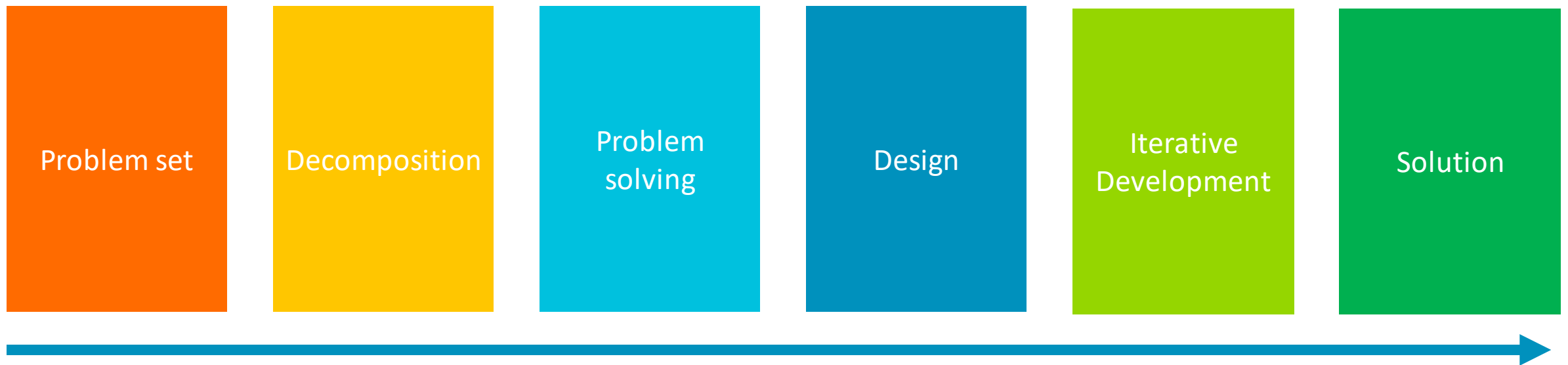
The Input Process Output (IPO) Model

- All computer systems take data into a system using 'Inputs', carry out processes on the inputs and then display the result of that processing using 'Outputs'
- Using the **Input, Process, Output** worksheet try to identify what the outputs will be

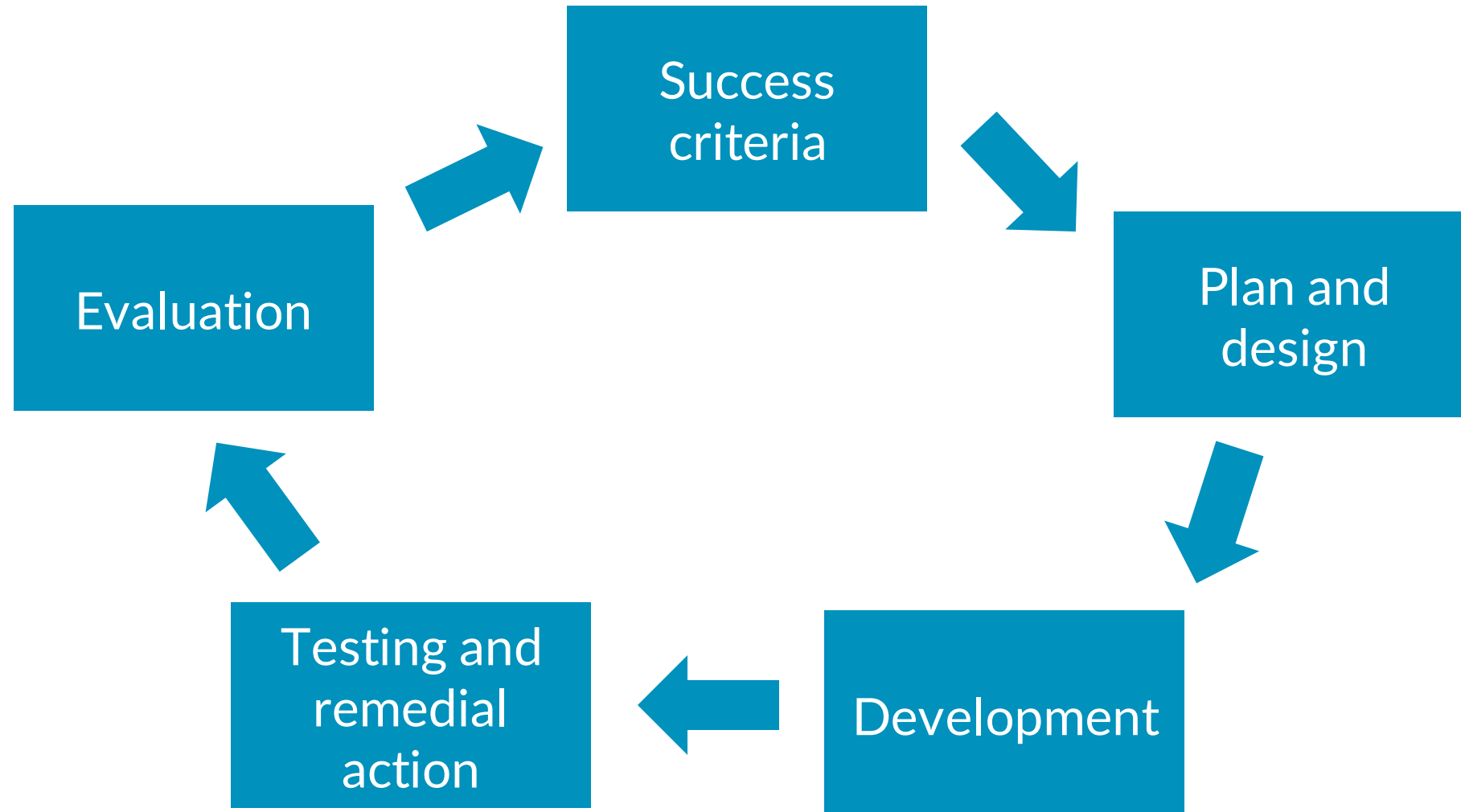


Decomposition

- Decomposition involves breaking down the overall task into a series of smaller problems



Iterative development cycle



Hardware as an intermediary relational step



Selection
as an
abstract
concept



```
a = [1,2,3]
b = [1,2,3]

if a == b:
    print("These lists have the same value.")

if a is b:
    print("These lists are the same list.")
```



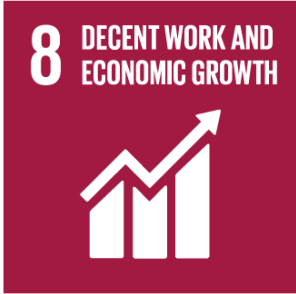
PBL

```
forever
  if temperature (°C) < 18 then
    show string "Too cold!"
```

- Real world context
- Instantly familiar
- Recognisable application of abstract concept
- Less cognitive demand

THE GLOBAL GOALS

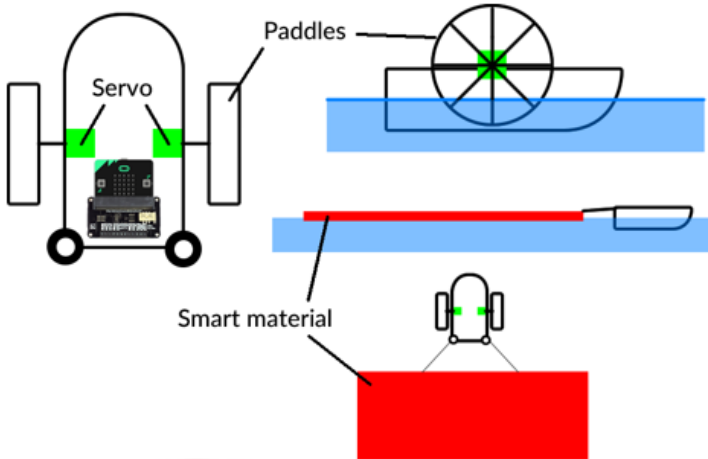
For Sustainable Development



Oil spill cleaner-upper

Building the product

For this project we need to build a simple boat. You can use anything that is waterproof.



Kit required:

- A micro:bit
- Header wires
- Battery pack
- Boat building materials
- A foam [sponge](#)
- A mini screwdriver
- A servo driver board

There are many types of servo controller boards for micro:bit, in this example an 'automation bit' was used.

Here you can see how the servo motors are wired to the servo controller and micro:bit.

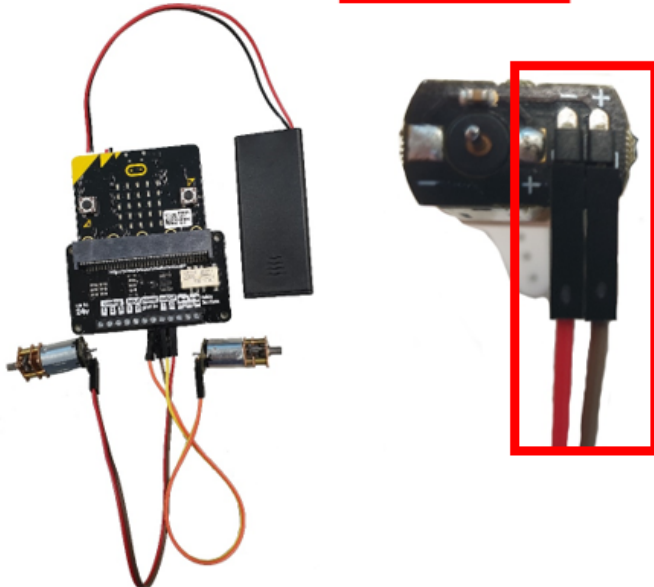
The + cable from **both** the servos need to go into the 3v opening on the servo control board.

The - cable needs to go into output 1 and 2 respectively.

Pay attention to which side you put them on. In this image:

Output 1 = Right
Output 2 = Left

You may have a third cable for the servo which is the ground (GND), attach this to the GND terminal on the board if you have this.



14 LIFE BELOW WATER



Conserve and sustainably use the oceans, seas and marine resources for sustainable development.

Goal 14 in Action Explore the Targets

Success criteria:

- Build a floating oil spill cleaner upper boat drone that starts with a button press
- The product should be able to autonomously navigate over an area
- The product should be made to clean up an oil spill by dragging a 'smart material'

Setting the scene

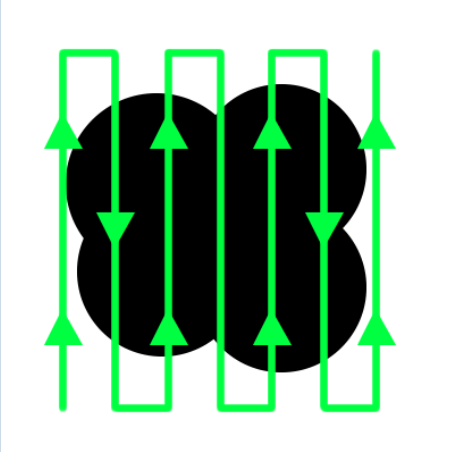
A group of marine scientists have asked you to develop an algorithm that could be used on a boat drone to drag around a sheet of this smart material to clean up an oil spill.



Success criteria:

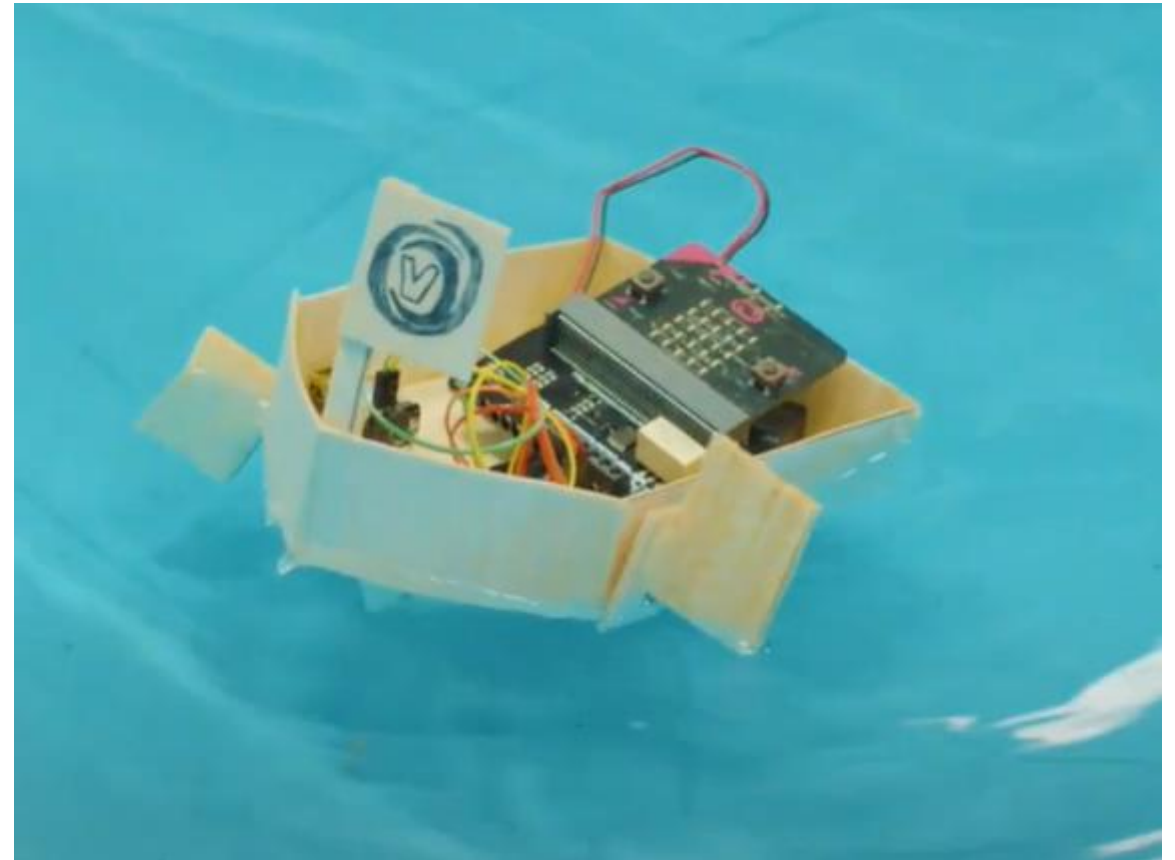
- Build a floating oil spill cleaner-upper boat drone that starts with a button press
- The product should be able to autonomously navigate over an area
- The product should be made to clean up an oil spill by dragging a 'smart material'

Input process output

Input	Process	Output
Button press	<p>Algorithm to control the movement of the boat drone in a path to clean up oil:</p>  <p>The diagram shows a black silhouette of a boat drone with two circular engines. It is positioned in the center of a white square. Overlaid on the drone and extending to the edges of the square are four vertical green lines. Each line has a green arrow pointing upwards at the top and a green arrow pointing downwards at the bottom. The lines are connected at the top and bottom by horizontal green bars, forming a continuous path that moves the drone up and down in a series of parallel lines, illustrating a cleaning pattern.</p>	Servo motor control

Making – rapid prototyping

- + Key part of Physical Computing
- + Ensures the projects are tangible, visceral and most importantly, engaging
- + Typical making tools:
 - Cardboard
 - Scissors
 - Glue guns
 - Tape
 - Velcro tape
 - Colouring pens/pencils



Group task:

- Get into pairs/groups
- Use the Oil Spill Cleaner Upper worksheet to help you design and create your product
- The product must meet the success criteria
- Use the IPO worksheet to design further features
- Make a model tree to test your product

Goal 14 - Life under water – oil spill cleaner upper

Getting started

Oil spills do untold damage to eco-systems.

A new material can absorb up to 90 times its own weight in spilled oil and then be squeezed out like a sponge and reused, raising hopes for easier clean-up of oil spill sites.

<https://www.newscientist.com/article/2123391-sponge-can-soak-up-and-release-spilled-oil-hundreds-of-times/>

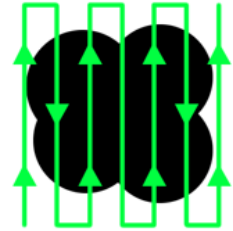
Success criteria

- Build a floating oil spill cleaner upper boat drone that starts with a button press
- The product should be able to autonomously navigate over an area
- The product should be made to clean up an oil spill by dragging a 'smart material'

Breaking down the problem

The input and output for this problem are simple as the drone boat should start with a button press and should follow a pre-programmed path. Creating the algorithm for the movement is the tricky part and will require some thought.

Input process output (IPO)

Input	Process	Output
Button press	Algorithm to control the movement of the boat drone in a path to clean up oil: 	Servo motor control

Pro-tip

Don't worry about distances at this point. Oil spills can be small or large, and the product just needs to be able to autonomously clean an area. Think about how the size of the area can be changed.

We won't have access to any smart [material](#) but we can simulate it using a normal sponge.

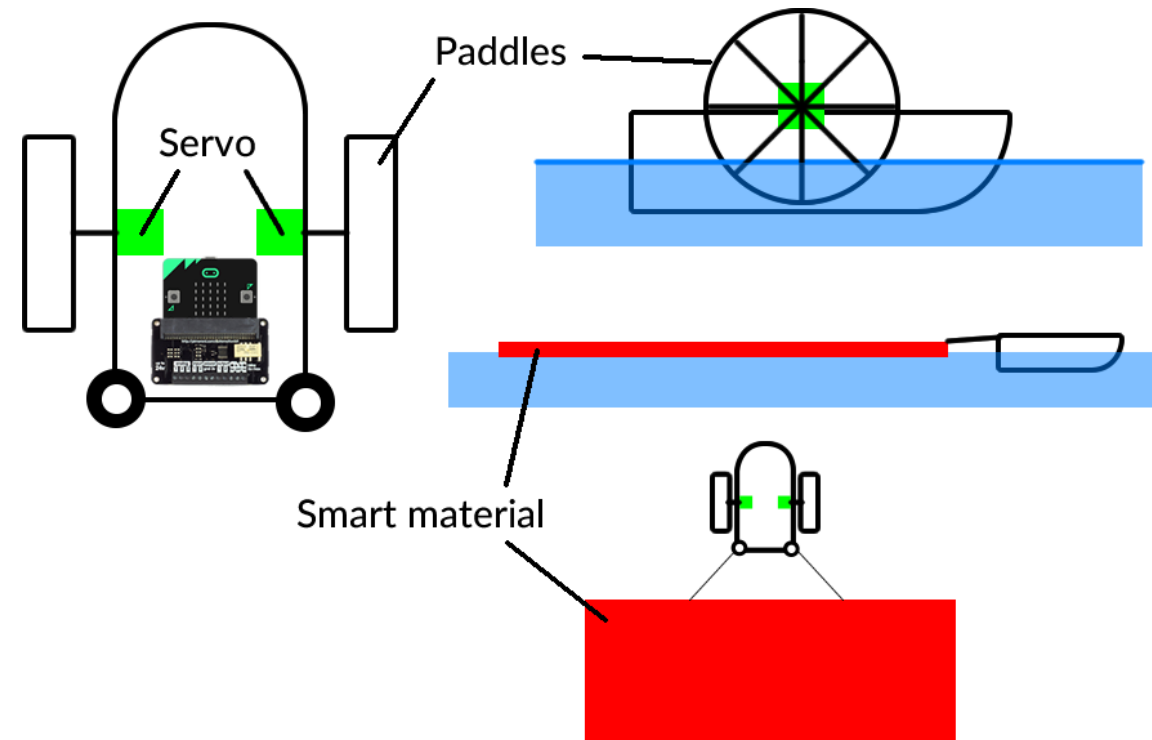
Creating a model

The image shows a Scratch script for a boat simulation. It starts with an 'on start' block containing two blocks: 'set boat to create sprite at x: 0 y: 5' and 'boat turn left by (°) 90'. Below this is an 'on button A pressed' block containing a 'repeat 2 times' loop. Inside the loop, there are two 'call function' blocks: 'go up' and 'go down'. Below the loop is another 'call function go up' block. The 'go up' function block contains a 'repeat 4 times' loop with a 'do' block containing 'boat move by 1' and 'pause (ms) 1000'. After the loop, there are two 'boat turn right by (°) 90' blocks and another 'boat move by 1' block followed by a 'pause (ms) 1000' block. The 'go down' function block contains a 'repeat 4 times' loop with a 'do' block containing 'boat move by 1' and 'pause (ms) 1000'. After the loop, there are two 'boat turn left by (°) 90' blocks and another 'boat move by 1' block followed by a 'pause (ms) 1000' block.

These blocks create an on-screen mock-up using a sprite.

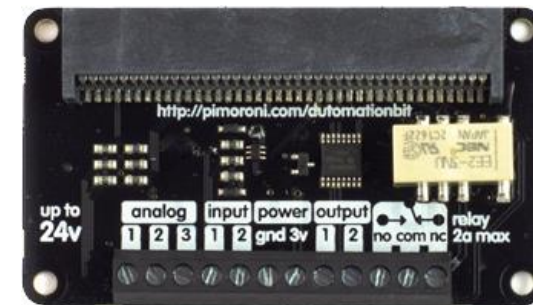
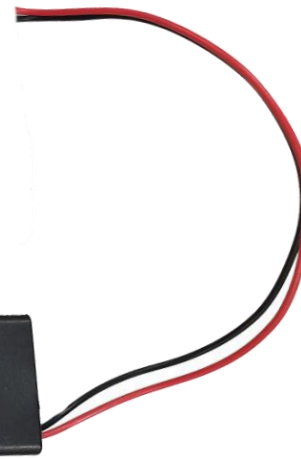
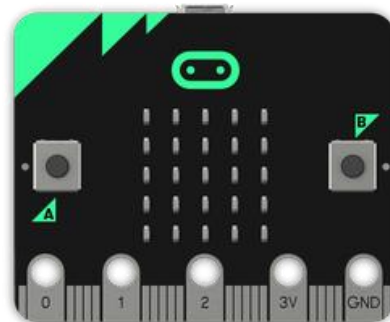
We can use this to test our algorithm on the micro:bit or in MakeCode.

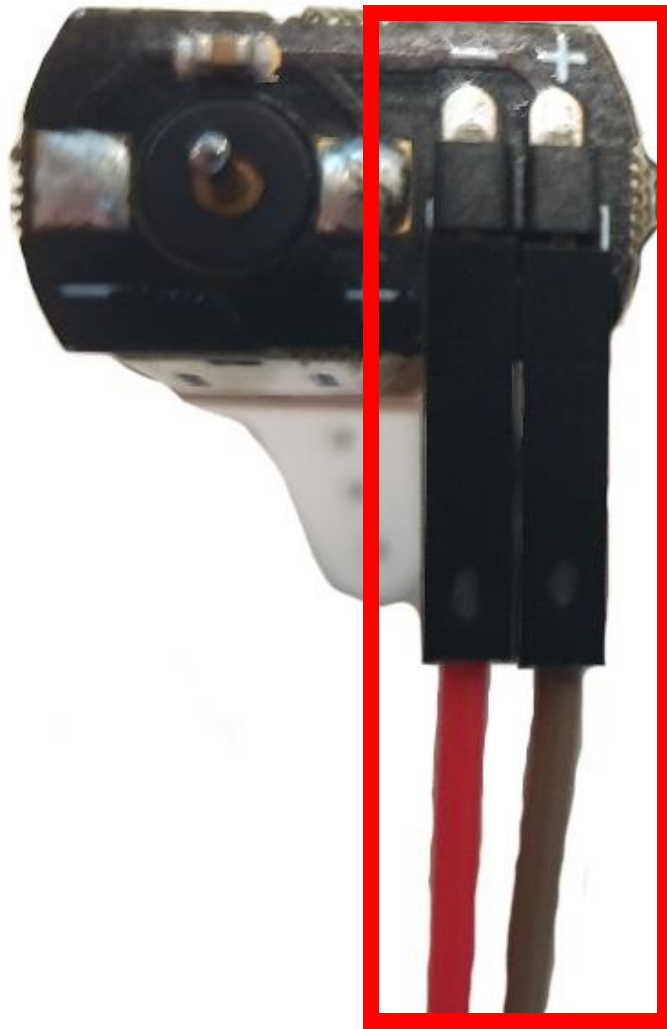
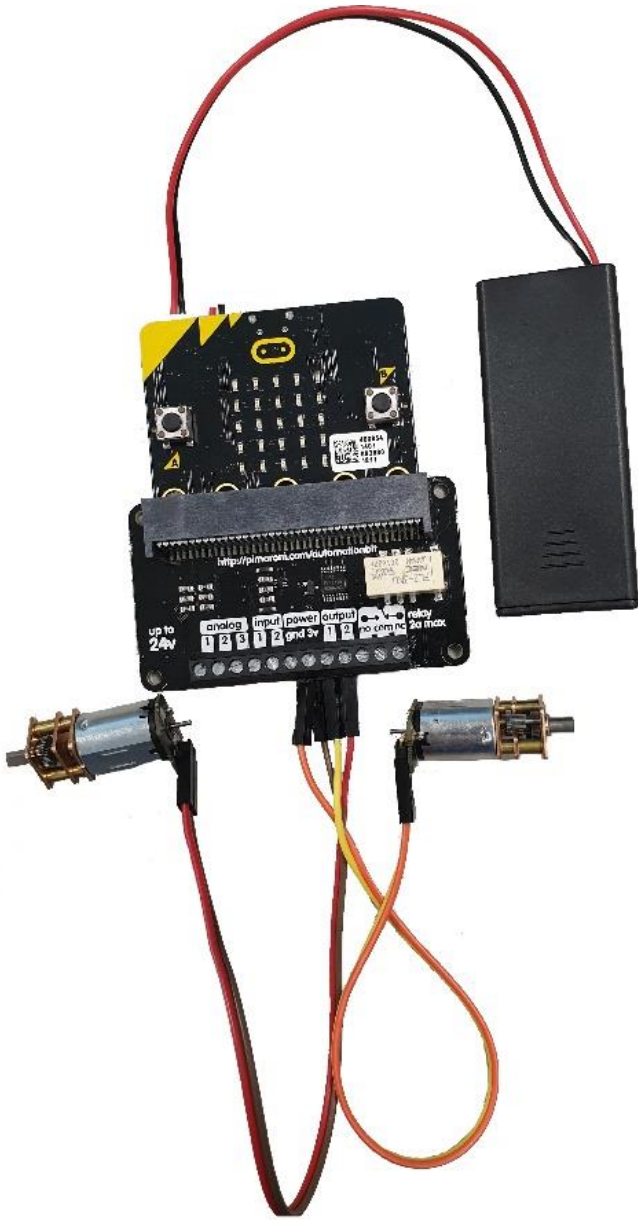
The paddle wheel:



Hardware needed:

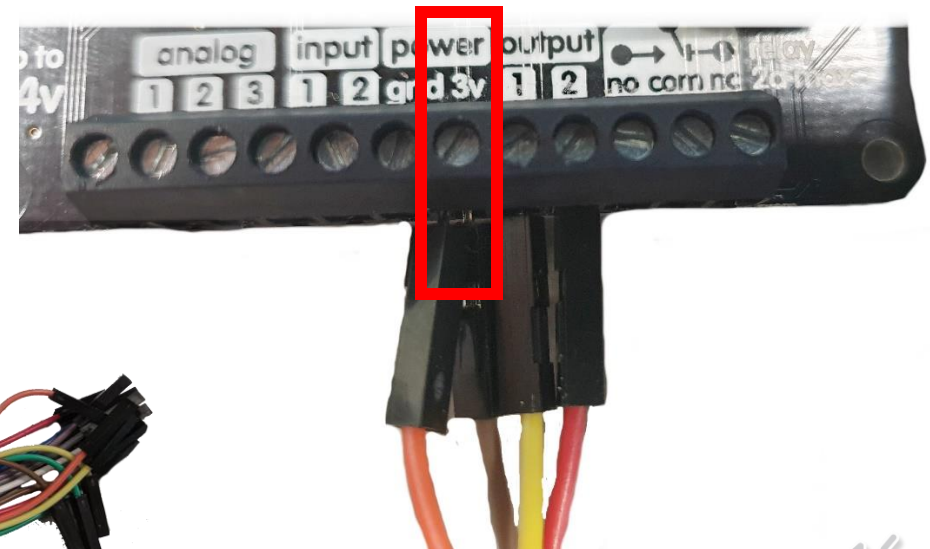
- micro:bit(s)
- battery peripheral and batteries
- materials to make the floating body and paddles
- servo control board
- servo motors
- a sponge to simulate the smart material





Note:

- The motors need power from the batteries
- The + wires from both servos go into the 3v terminal
- Output one is right
- Output two is left
- Ground (GND) wires got to the GND terminal



Research driven

- EEF meta analysis of EdTech shows “consistent benefits”
 - The technology in isolation is irrelevant, technology enthuses learners, what matter is that the pedagogy, activity and technology are aligned
 - Enhances teaching rather than replacing it
- Collaborative use of technology (in pairs or small groups) is usually more effective than individual use, though some pupils, especially younger children, may need guidance in how to collaborate effectively and responsibly.
 - Technology can be as powerful as a short but focused intervention to improve learning, particularly when there is regular and frequent use (about three times a week) over the course of about a term (5 - 10 weeks). Sustained use over a longer period is usually less effective at improving this kind of boost to attainment.
 - Remedial and tutorial use of technology can be particularly practical for lower attaining pupils, those with special educational needs or those from disadvantaged backgrounds in providing intensive support to enable them to catch up with their peers.
 - In researched interventions, technology is best used as a supplement to normal teaching rather than as a replacement for it. This suggests some caution in the way in which technology is adopted or embedded in schools.
 - Tested gains in attainment tend to be greater in mathematics and science (compared with literacy for example) though this is also a more general finding in meta-analysis and may be at least partly an artefact of the measurement process. In literacy the impact tends to be greater in writing interventions compared with reading or spelling.
 - At least a full day's training or on-going professional inquiry-based approaches to support the introduction of new technology appear the most successful. The implication is that such support should go beyond the teaching of skills in technology and focus on the successful pedagogical use of technology to support teaching and learning aims.

The Impact of Digital Technology on Learning: A Summary for the Education Endowment Foundation

Implications

Pedagogical:

- + Authentic contexts required
- + Achievable success criteria
- + Appropriate scaffolding of resources and differentiation
- + Resource heavy approach
- + Group work commonly employed but no necessary
- + Assessment (formative/summative)

Practical:

- + Hardware accessibility
- + Hardware availability
- + Cost
- + Time constraints on projects (multi lesson)

Teaching with Physical Computing MOOC on edX

A new series of Professional Development (PD) courses from the Arm School Program

Training for teachers on Physical Computing and how to apply it through Project-Based Learning in the classroom.

Teaching with Physical Computing

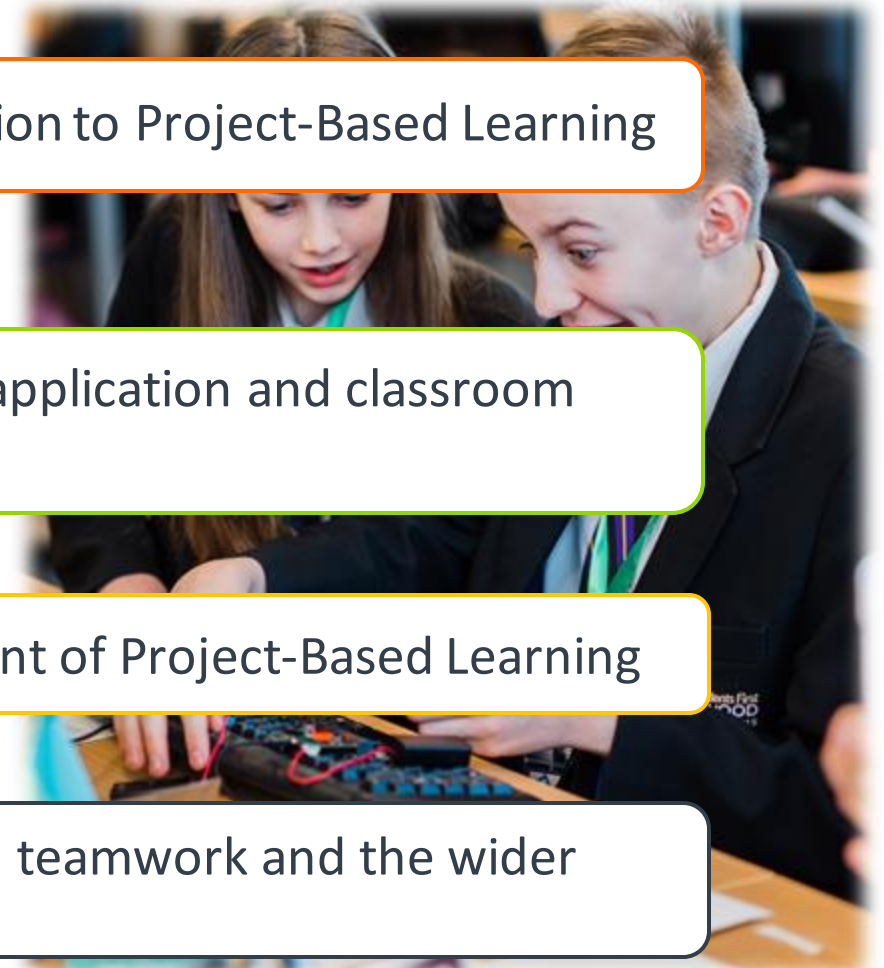
Search for “Project-Based Learning” on edX.org

Course 1 Introduction to Project-Based Learning

Course 2 Practical application and classroom strategies for PBL

Course 3 Assessment of Project-Based Learning

Course 4 Soft skills, teamwork and the wider curriculum



arm

Thank You

Danke

Gracias

Grazie

谢谢

ありがとう

Asante

Merci

감사합니다

धन्यवाद

Kiitos

شكرًا

ধন্যবাদ

תודה



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